

# An Efficient Constitutive Model for Shape Memory Alloy Materials

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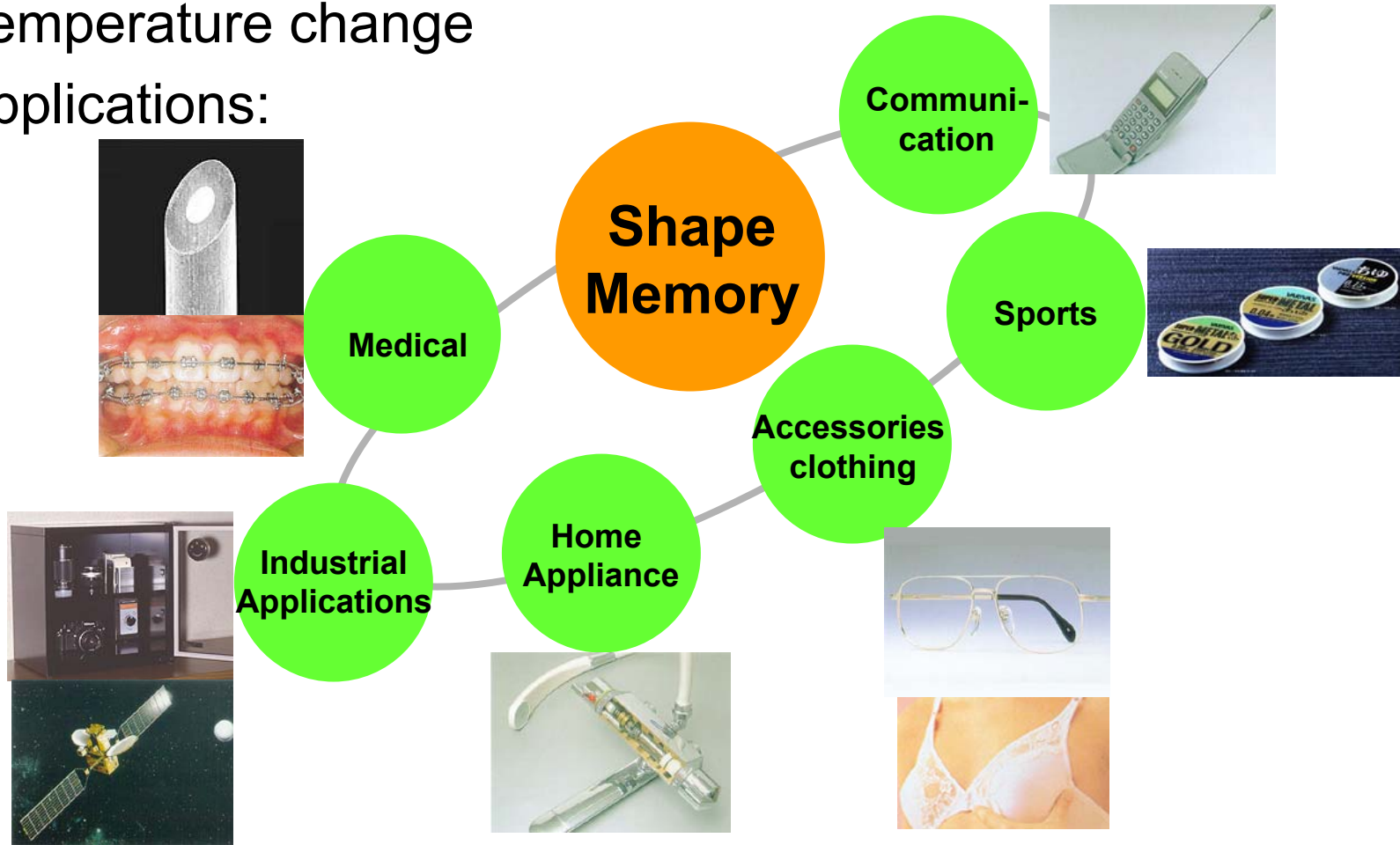
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MSC.Software Corporation,  
Redwood City, CA USA

# Shape Memory Alloys



Materials that return to some shape upon appropriate temperature change

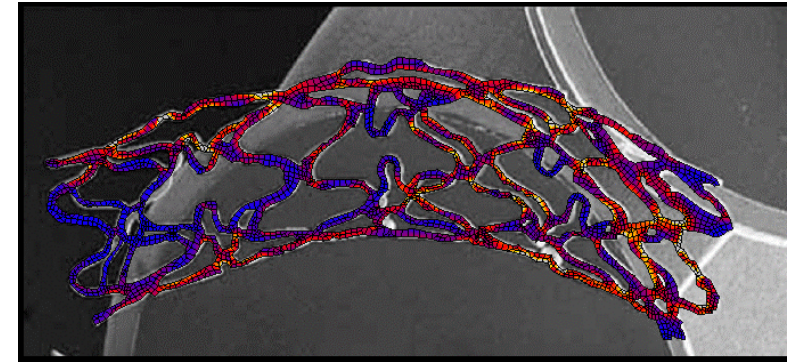
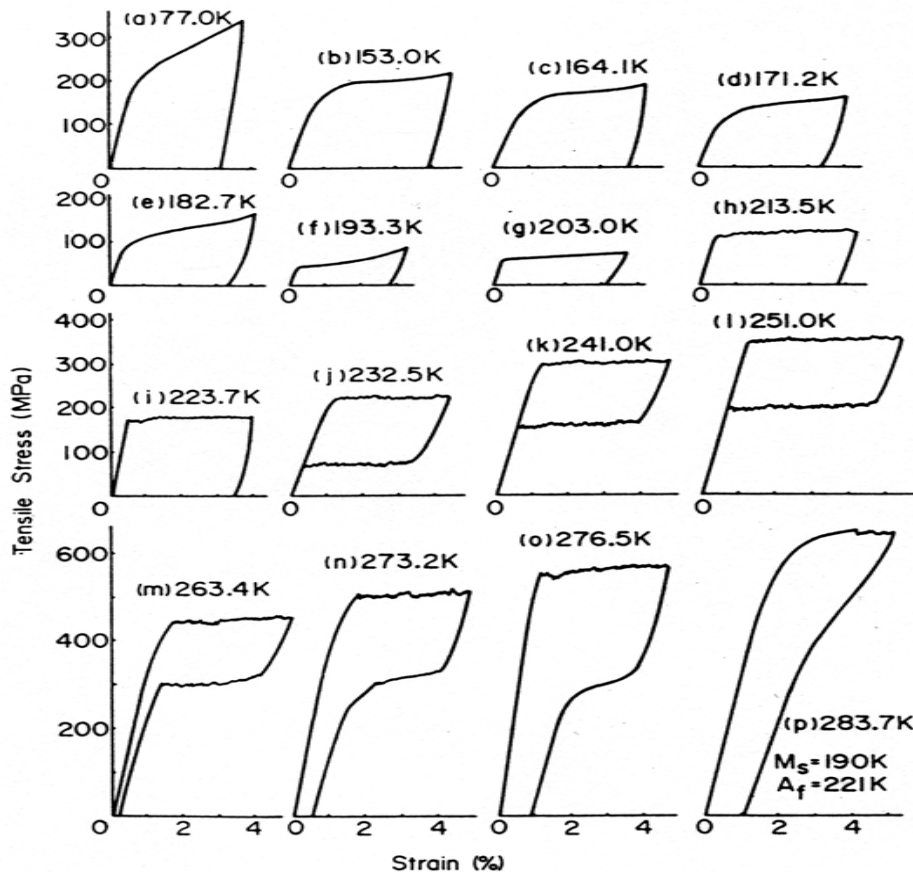
Applications:



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Nickel-Titanium alloys to show shape memory effect that severely deformed specimens, with residual strains up to 15%, regained their original shape after a loading cycle at a certain temperature.

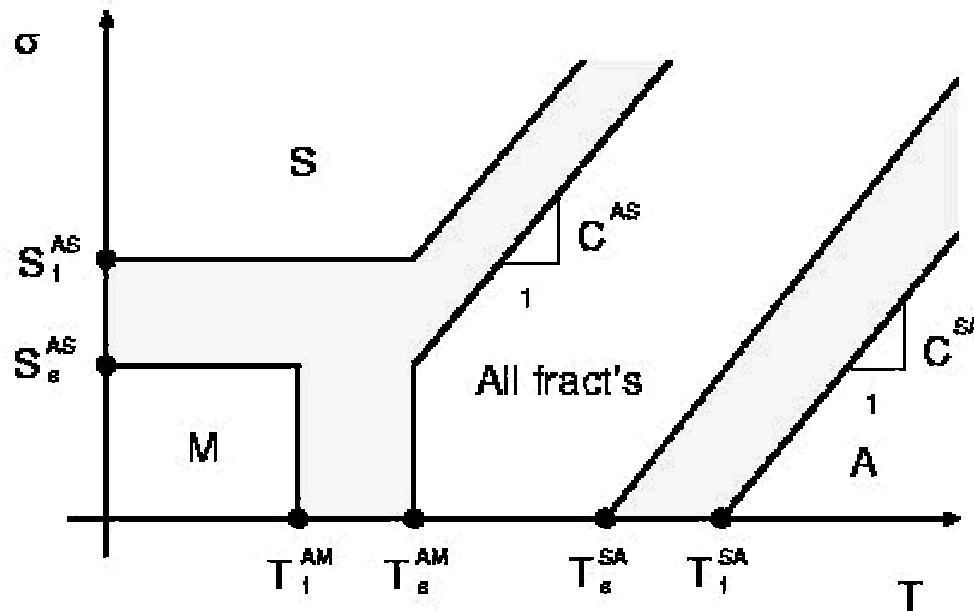


NiTi Stent



Shape memory effect is a consequence of a crystallographically reversible solid-solid phase transformation occurring in particular metal alloys (Ni – Ti, Cu based alloys).

This transition occurs between a crystallographically more-ordered phase (called *austenite*) and a crystallographically less-ordered phase (*martensite*).

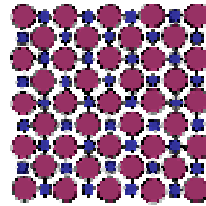


# Stability for Martensite and Austenite Phases



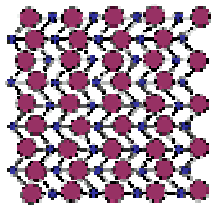
## Austenite

- High temperature phase
- Cubic Crystal Structure

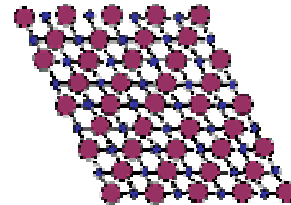


## Martensite

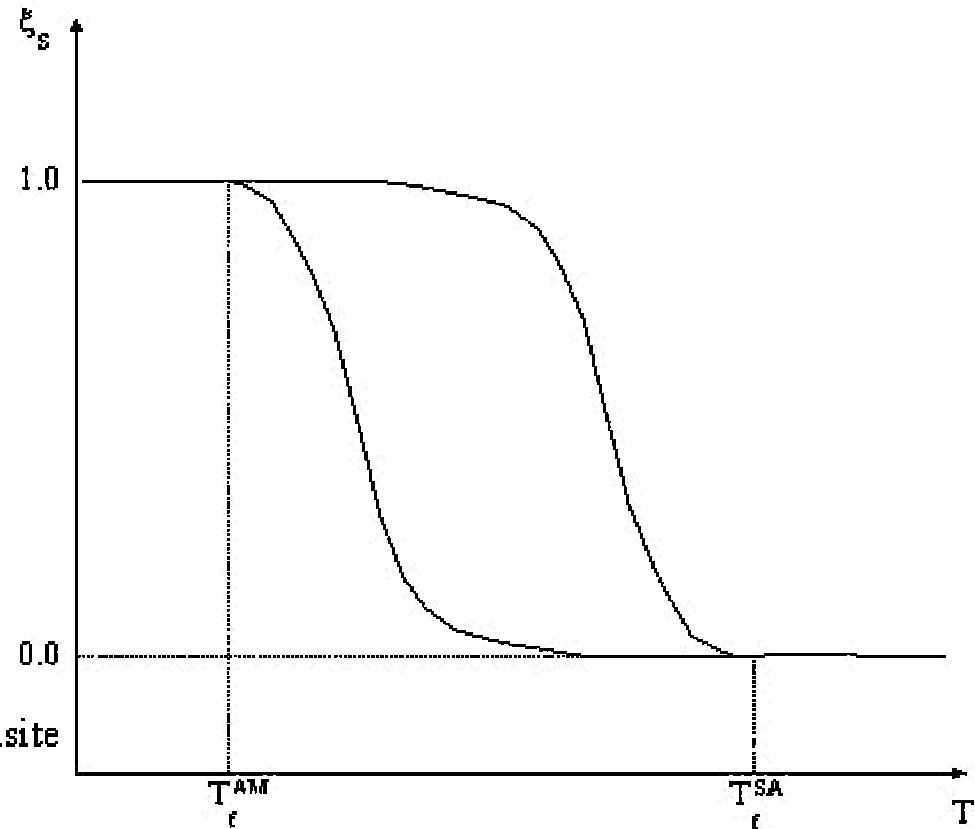
- Low temperature phase
- Monoclinic Crystal Structure



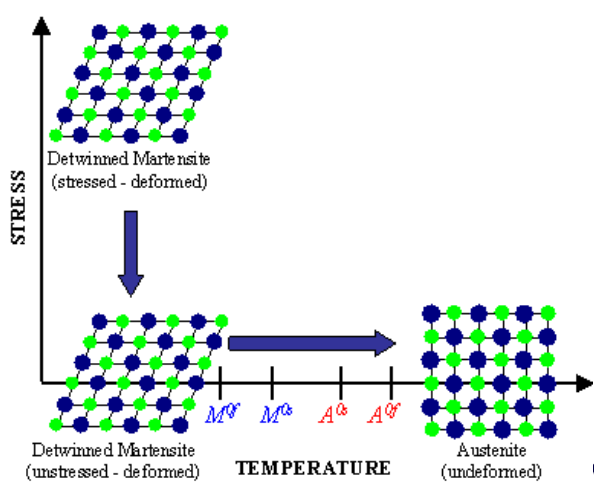
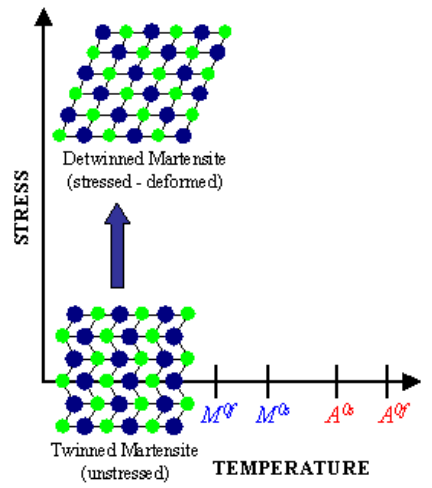
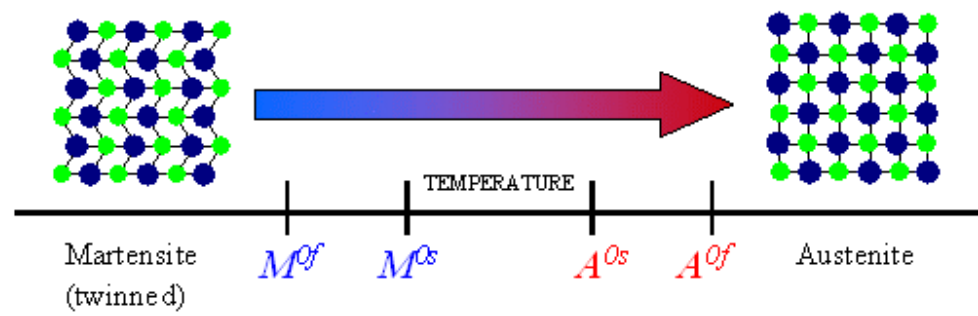
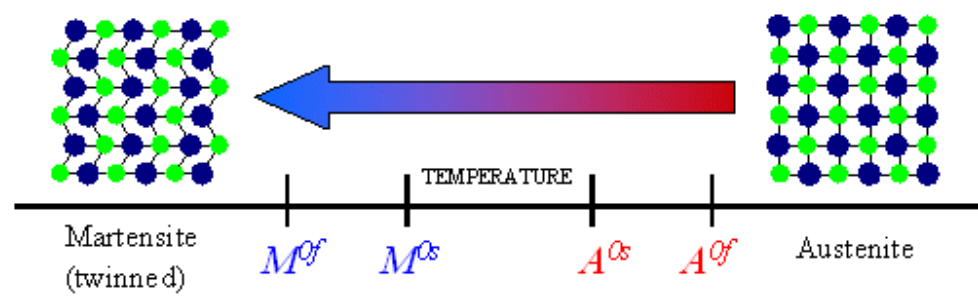
Twinned Martensite



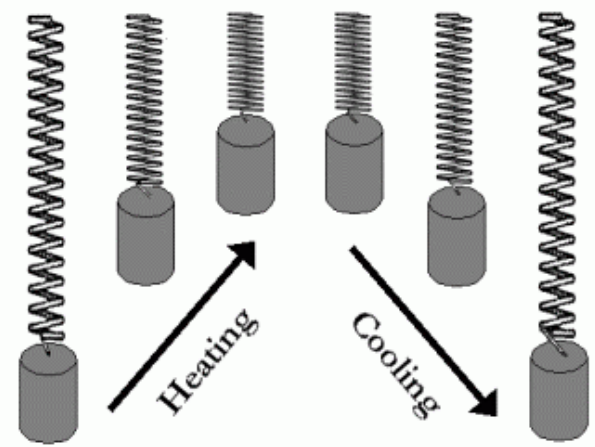
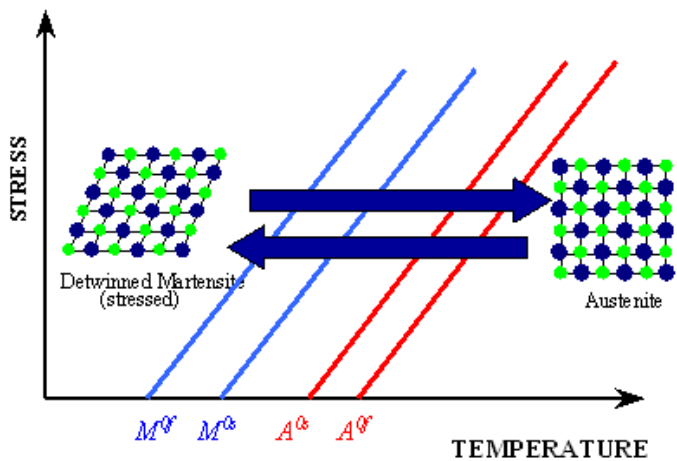
Detwinned Martensite



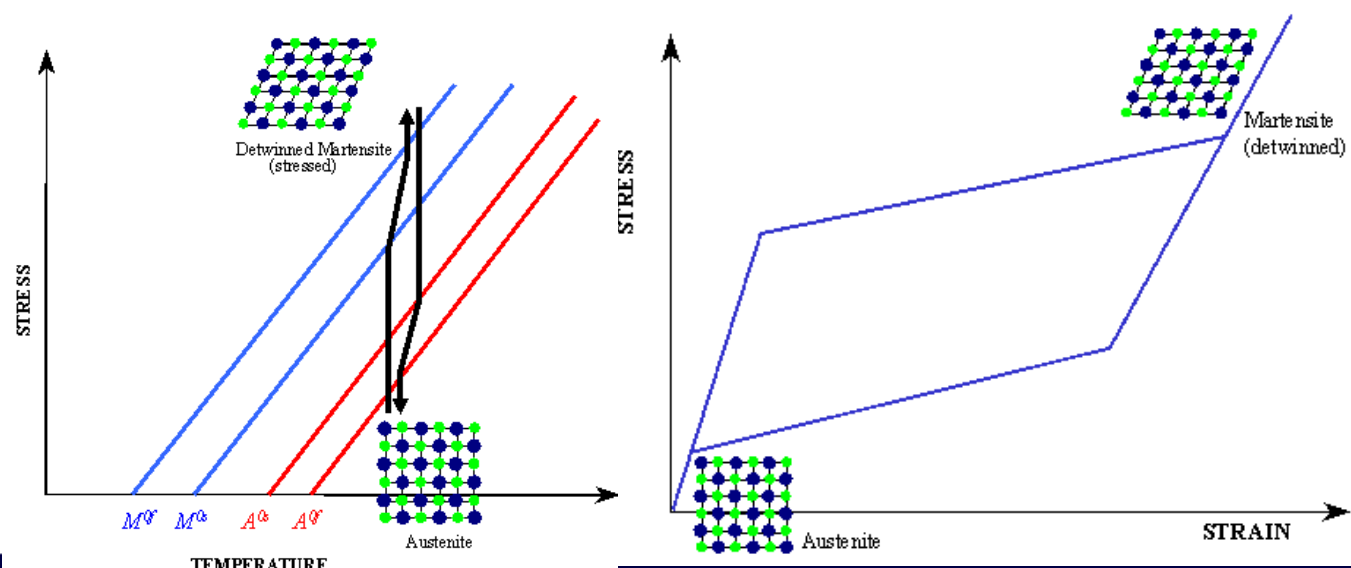
# Shape Memory Effect



# Temperature induced phase transformation



## Peudoelastic Stress-Strain Behavior



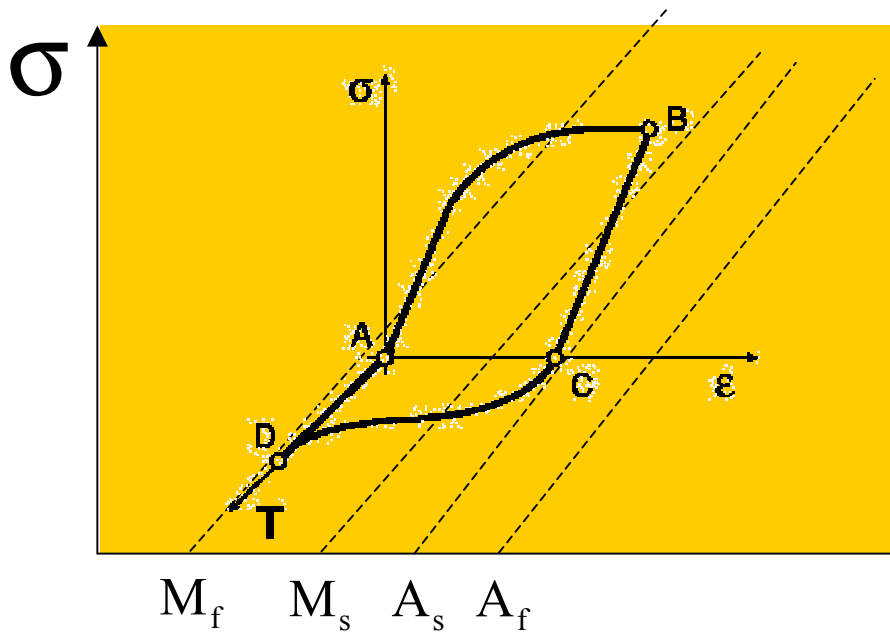
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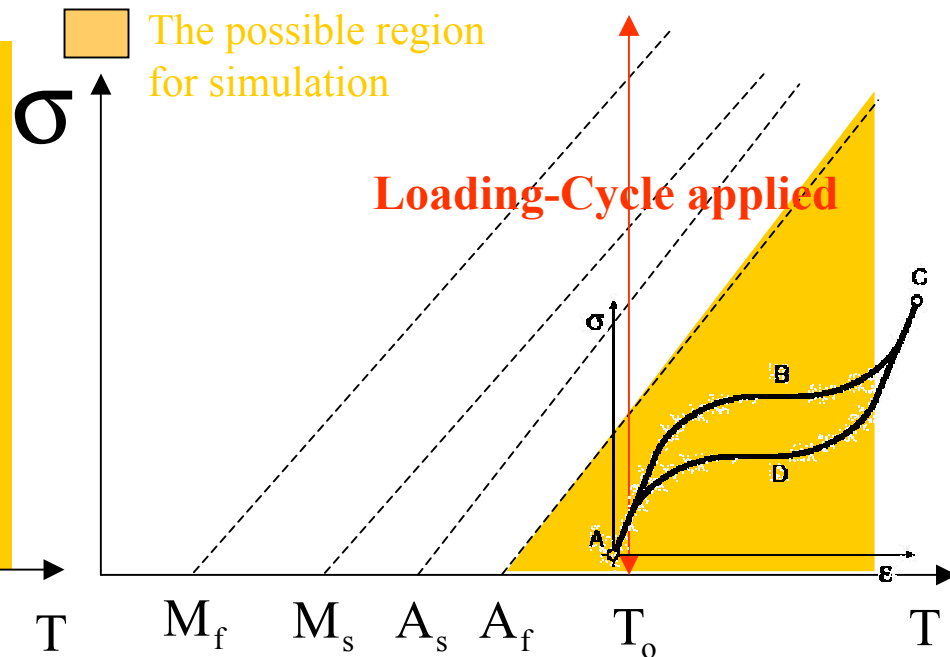
- Thermo-mechanical model  
(Saeedvafa & Assaro's model)

- Mechanical model :  
(Auricchio's model) based on super-elasticity

**Thermo-mechanical model**



**Mechanical model**

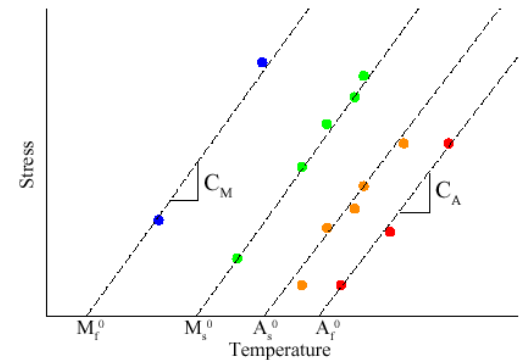




$$\dot{\boldsymbol{\varepsilon}} = \dot{\boldsymbol{\varepsilon}}^{\text{EL}} + \dot{\boldsymbol{\varepsilon}}^{\text{Th}} + \dot{\boldsymbol{\varepsilon}}^{\text{PL}} + \dot{\boldsymbol{\varepsilon}}^{\text{Ph}} \quad (= \dot{\boldsymbol{\varepsilon}}^{\text{TRIP}} + \dot{\boldsymbol{\varepsilon}}^{\text{TWIN}})$$

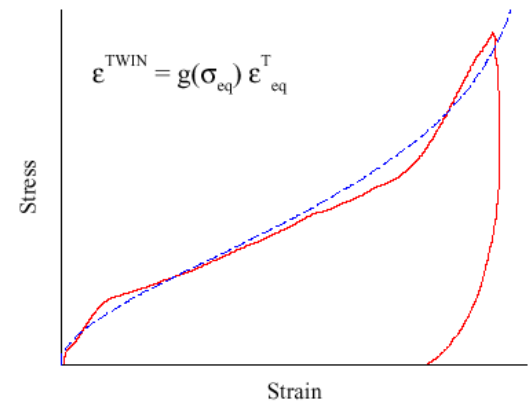
where

$$\dot{\boldsymbol{\varepsilon}}^{\text{EL}} = \mathbf{L}^{-1} : \dot{\boldsymbol{\sigma}}, \quad \dot{\boldsymbol{\varepsilon}}^{\text{Th}} = \alpha \dot{T} \mathbf{I}, \quad \dot{\boldsymbol{\varepsilon}}^{\text{PL}} = \dot{\lambda} \frac{3\dot{\boldsymbol{\sigma}}'}{2\sigma_{\text{eq}}}$$



$$\dot{\boldsymbol{\varepsilon}}^{\text{TRIP}} = \dot{f}^{(+)} \underline{g(\sigma_{\text{eq}})} \underline{\boldsymbol{\varepsilon}_{\text{eq}}^{\text{T}}} \frac{3}{2} \frac{\boldsymbol{\sigma}'}{\sigma_{\text{eq}}} + \dot{f}^{(+)} \underline{\boldsymbol{\varepsilon}_{\text{v}}^{\text{T}}} \mathbf{I} + \dot{f}^{(-)} \boldsymbol{\varepsilon}^{\text{Ph}}$$

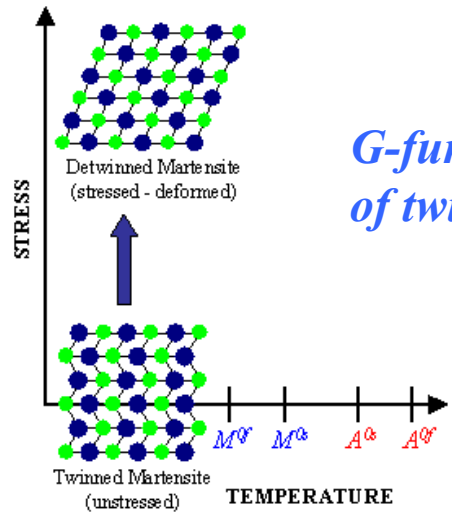
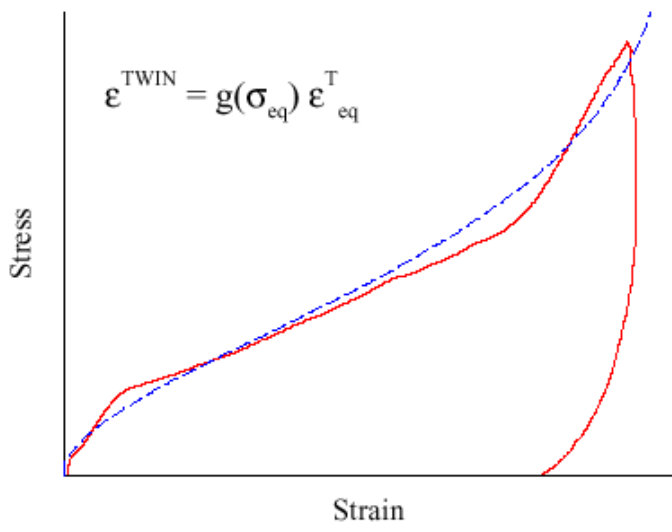
$$\dot{\boldsymbol{\varepsilon}}^{\text{TWIN}} = \underline{f} \underline{\dot{g}(\sigma_{\text{eq}})} \underline{\boldsymbol{\varepsilon}_{\text{eq}}^{\text{T}}} \frac{3}{2} \frac{\boldsymbol{\sigma}'}{\sigma_{\text{eq}}} \{ \sigma_{\text{eq}} \} \{ \sigma_{\text{eq}} - \underline{\sigma_{\text{eff}}^{\text{g}}} \}$$



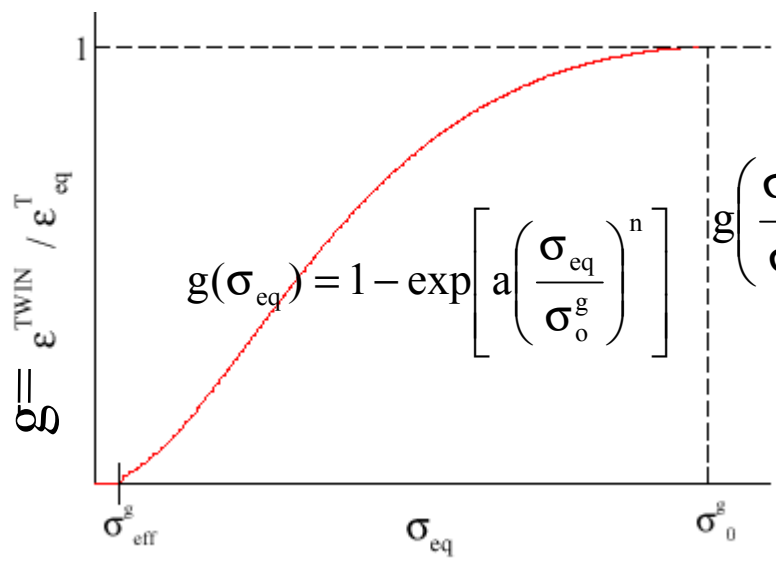
where

$$\dot{f} = \dot{f}^{(+)}(T, M_s, M_f, C_m, \sigma_{\text{eq}}) + \dot{f}^{(-)}(T, A_s, A_f, C_a, \sigma_{\text{eq}})$$

$$\{ \mathbf{x} \} = 0.5 * (\mathbf{x} + |\mathbf{x}|) / |\mathbf{x}| \quad \text{---: input value}$$



*G-function fits the formation of twin stress below  $M_f$*



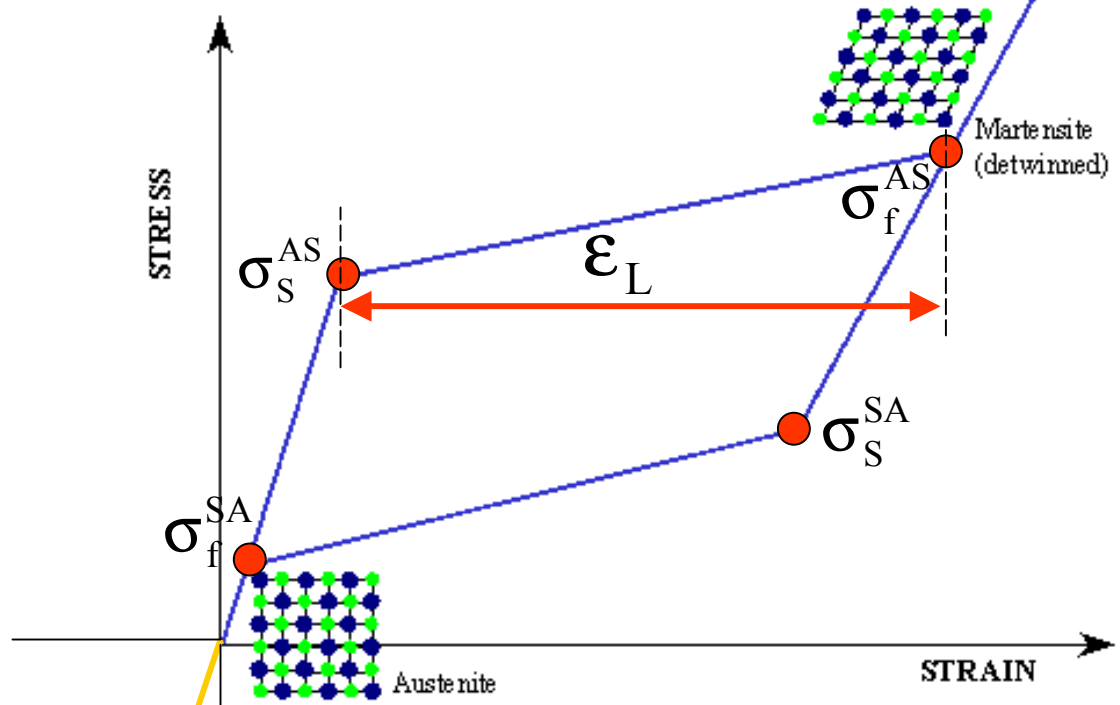
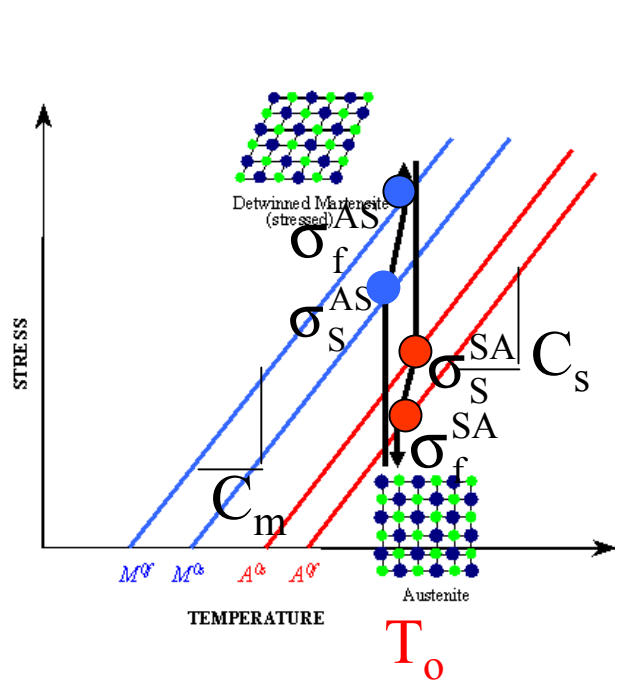
**More general form for g-function**

$$g\left(\frac{\sigma_{eq}}{\sigma_o^g}\right) = 1 - \exp\left[ g_a \left(\frac{\sigma_{eq}}{\sigma_o^g}\right)^{g_b} + g_c \left(\frac{\sigma_{eq}}{\sigma_o^g}\right)^{g_d} + g_e \left(\frac{\sigma_{eq}}{\sigma_o^g}\right)^{g_f} \right]$$

$$g_a < 0, \quad g_b = 3.0, \quad g_c \geq 0,$$

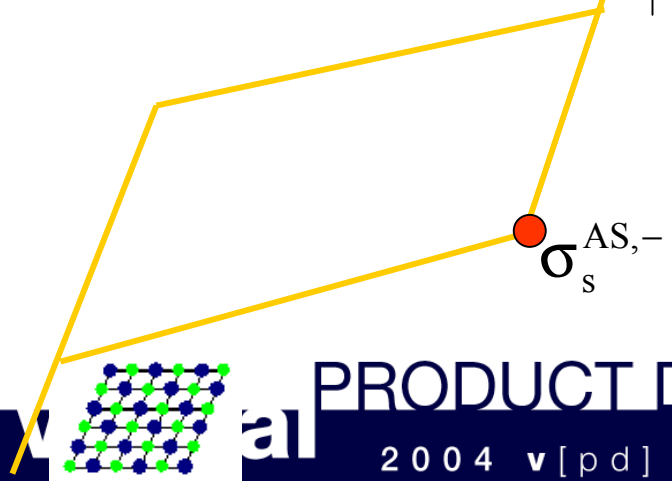
$$g_d = 2.75, \quad g_e \geq 0, \quad g_f = 3.0$$

# Input Data for Mechanical Shape Memory Alloy



Input

- |                 |                 |                 |                 |                   |
|-----------------|-----------------|-----------------|-----------------|-------------------|
| $\sigma_S^{AS}$ | $\sigma_f^{AS}$ | $\sigma_S^{SA}$ | $\sigma_f^{SA}$ | $\sigma_s^{AS,-}$ |
| $\epsilon_L$    | $T_0$           | $C_m$           | $C_s$           |                   |



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## Kinematics :

$$\mathbf{F} = \mathbf{F}^e \mathbf{F}^{\text{trT}}$$

$$\mathbf{b} = \mathbf{F}\mathbf{F}^T = \sum_{A=1}^3 (\lambda_A)^2 \mathbf{n}^A \otimes \mathbf{n}^A \quad \text{Then , } J = \lambda_1 \lambda_2 \lambda_3 \quad \text{and} \quad \bar{\lambda}_A = (J)^{-1/3} \lambda_A$$

$$\theta = \log(J), \quad e_A = \log(\bar{\lambda}_A)$$

## Drucker-Prager type loading function

$$F(\boldsymbol{\tau}) = \left\| \sum_{A=1}^3 t_A \mathbf{n}^A \otimes \mathbf{n}^A \right\| + 3\alpha p \quad \left| \begin{array}{l} t_A = 2G(e_A - \varepsilon_L \xi_S \mathbf{n}_A) \\ p = K(\theta - 3\alpha \varepsilon_L \xi_S) \end{array} \right.$$

$$\mathbf{R}^{AS} = (\mathbf{F} - \mathbf{R}_f^{AS}) \lambda_s - H^{AS} (1 - \xi_S)(\mathbf{F} - \mathbf{F}_n) = 0 \quad (A \rightarrow M)$$

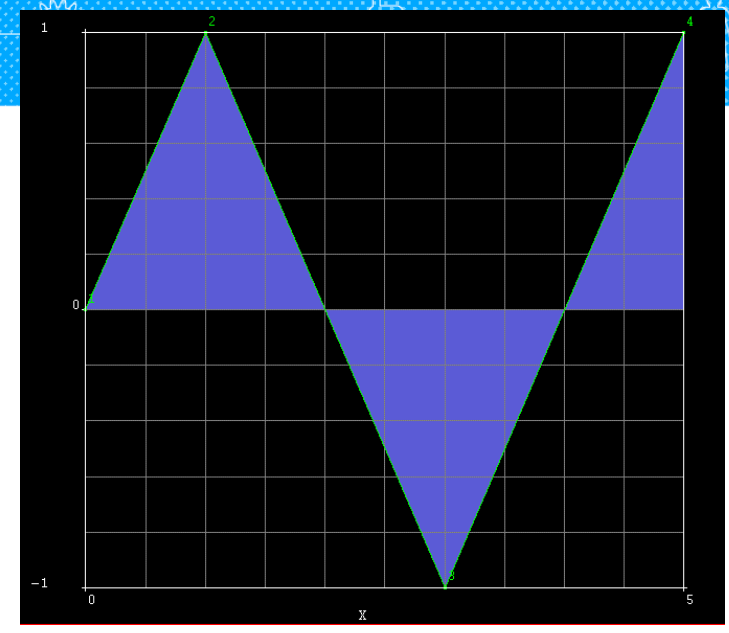
$$\mathbf{R}^{SA} = (\mathbf{F} - \mathbf{R}_f^{SA}) \lambda_s - H^{SA} \xi_S (\mathbf{F} - \mathbf{F}_n) = 0 \quad (M \rightarrow A)$$

where

$$\lambda_s = \int_{t_n} \dot{\xi} dt = \xi_S - \xi_{S,n} \quad \mathbf{R}_f^{SA} = \left[ \sigma_f^{SA} \left( \sqrt{\frac{2}{3}} + \alpha \right) \right] \quad \mathbf{R}_f^{AS} = \left[ \sigma_f^{AS} \left( \sqrt{\frac{2}{3}} + \alpha \right) \right]$$

# Cyclic Tension-Compression Tests for Mechanical SMA model

displacement



time

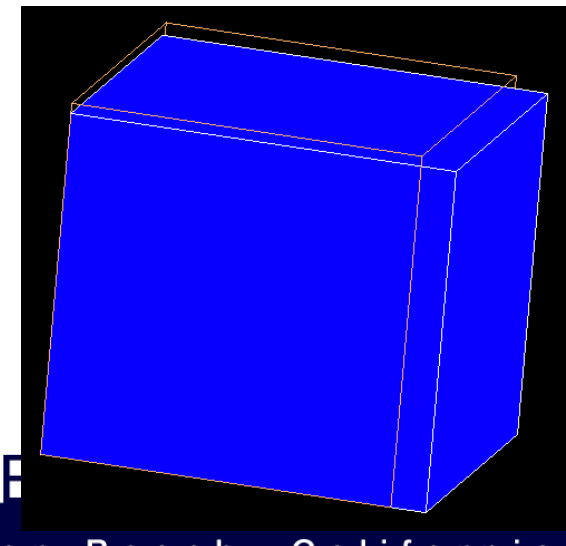
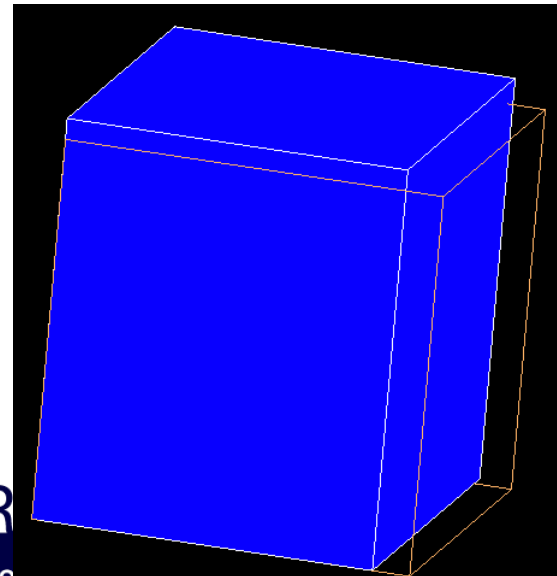
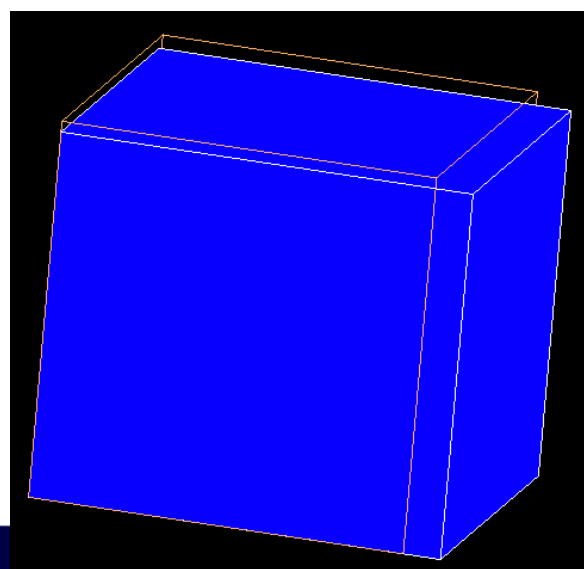
Tension(10%)

→

Compression(10%)

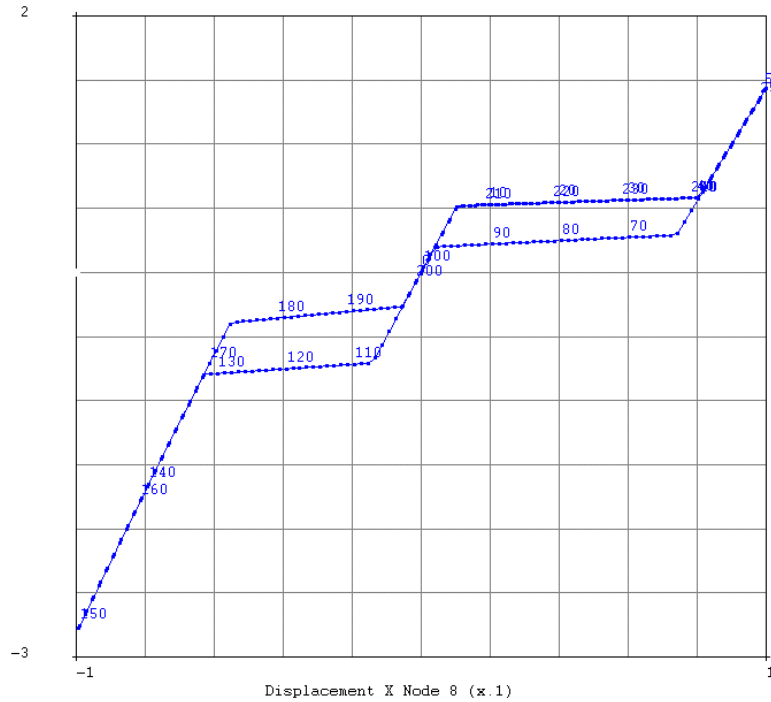
→

Tension (10%)



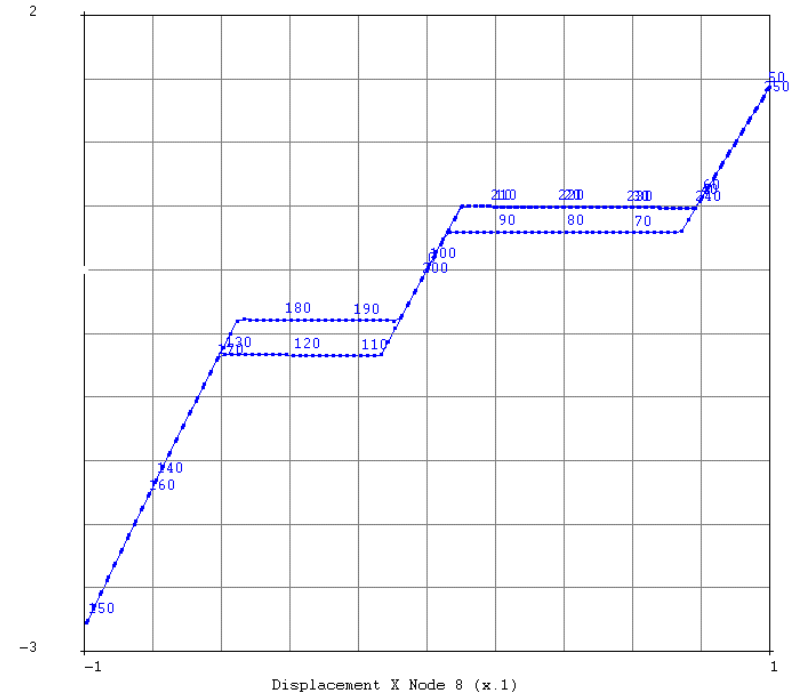
# \* Cyclic Tension-Compression Tests for Mechanical SMA model

prob e8.81a demonstration of mechanical shape memory alloy  
Comp 11 of Stress Node 8 (x1000)



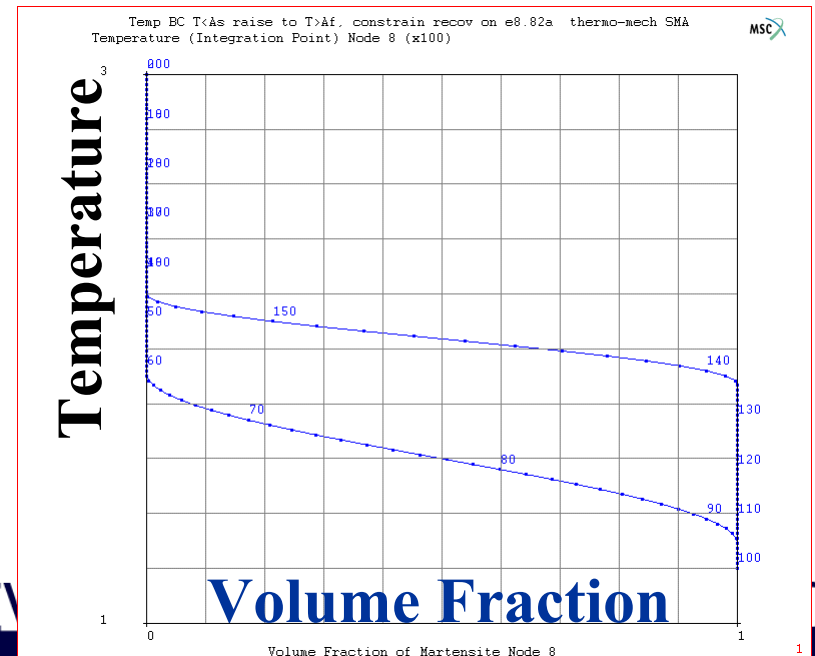
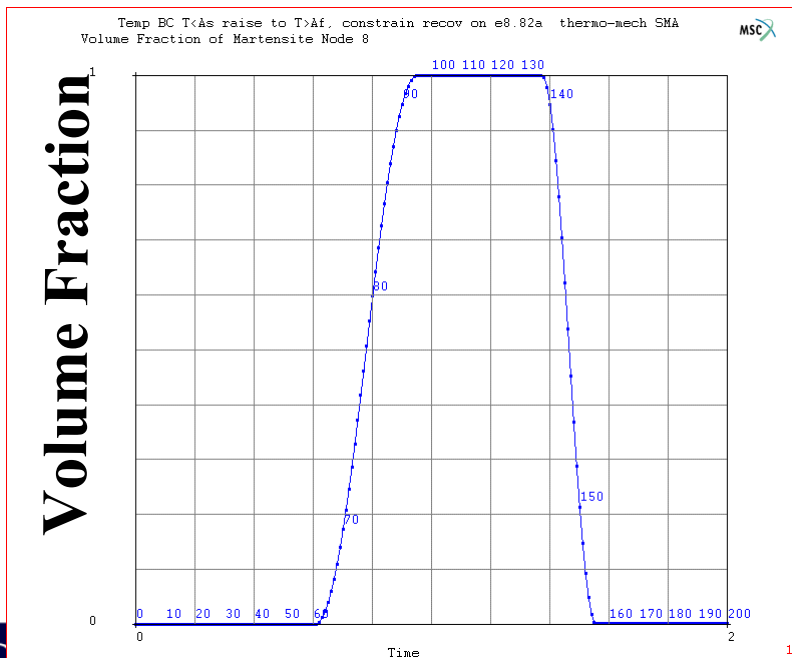
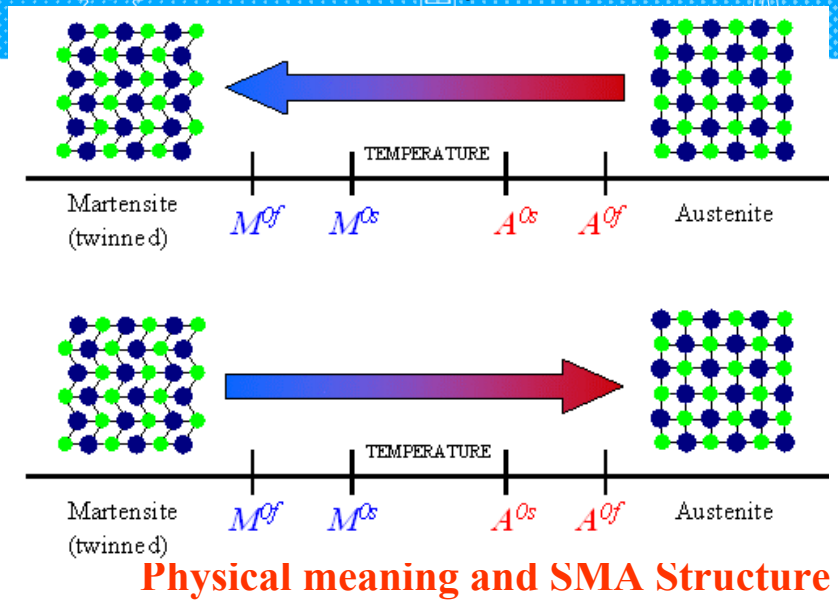
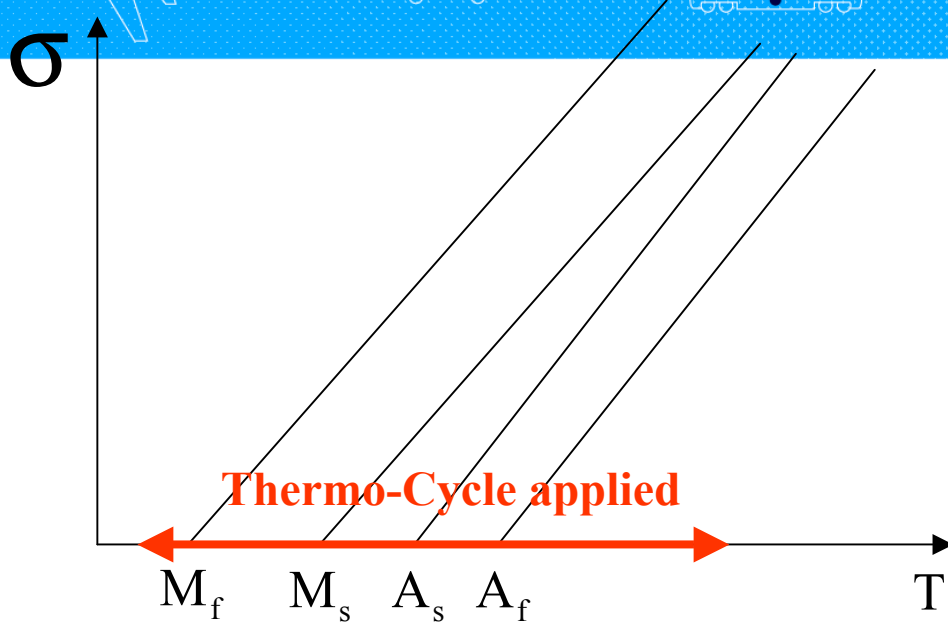
sigAS\_s=520, sigAS\_f=600  
sigSA\_s=300, sigSA\_f=200

prob e8.81b demonstration of mechanical shape memory alloy  
Comp 11 of Stress Node 8 (x1000)

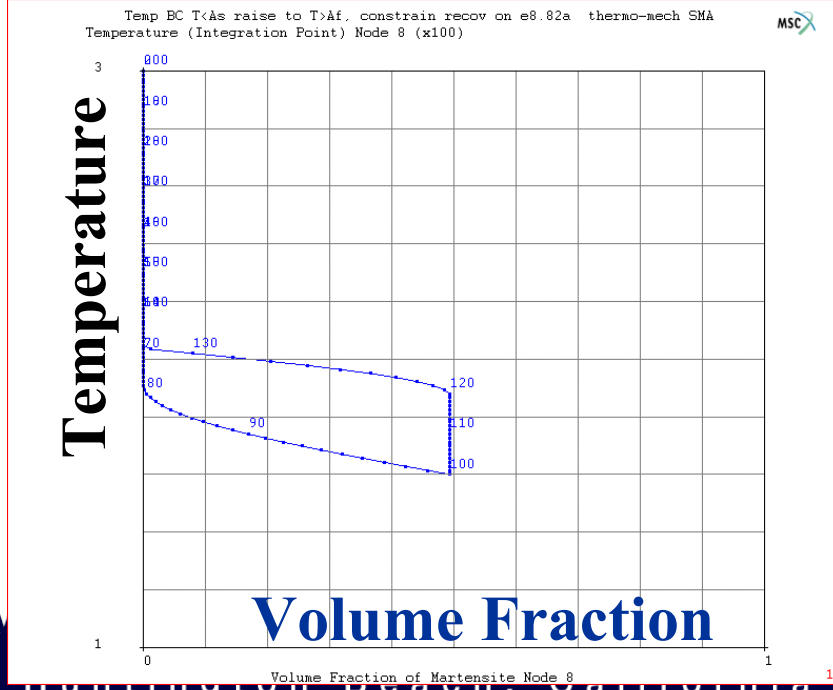
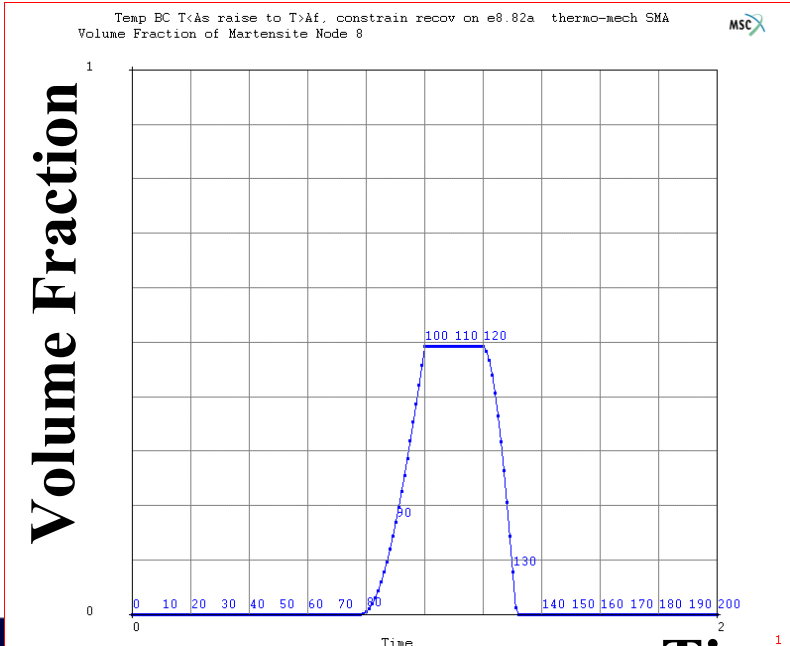
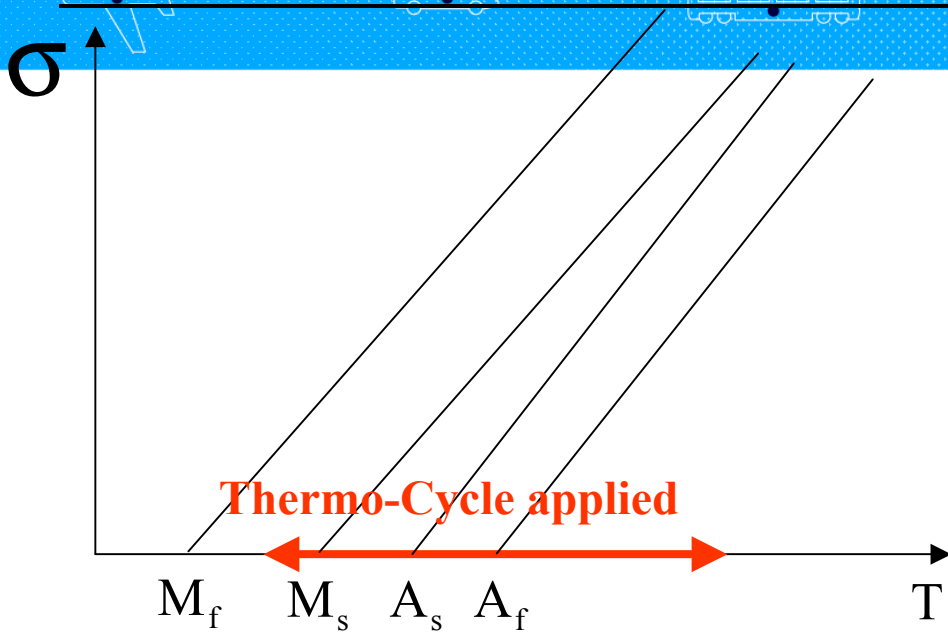


sigAS\_s=500, sigAS\_f=500  
sigSA\_s=300, sigSA\_f=300

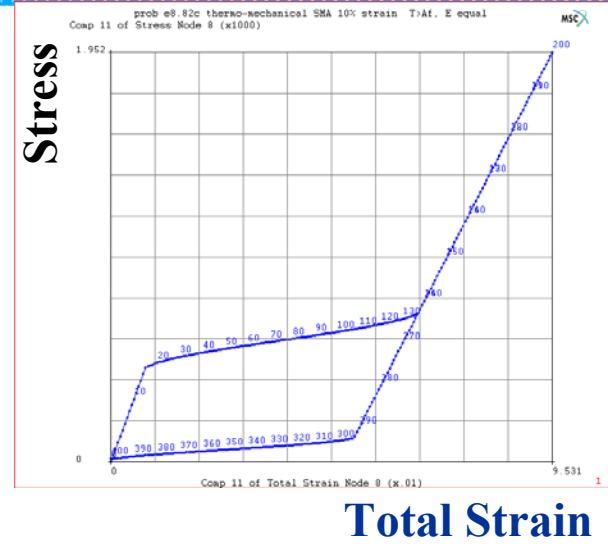
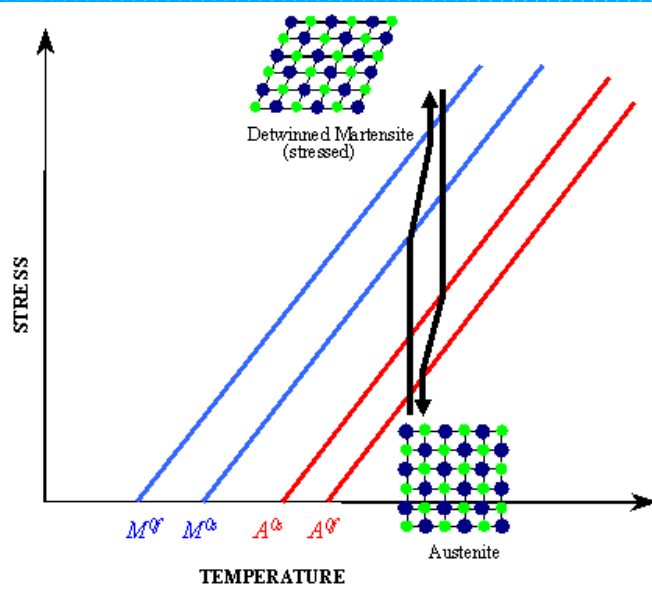
# \* Thermo-Mechanical Model Verification : Thermo-Cycle(1)



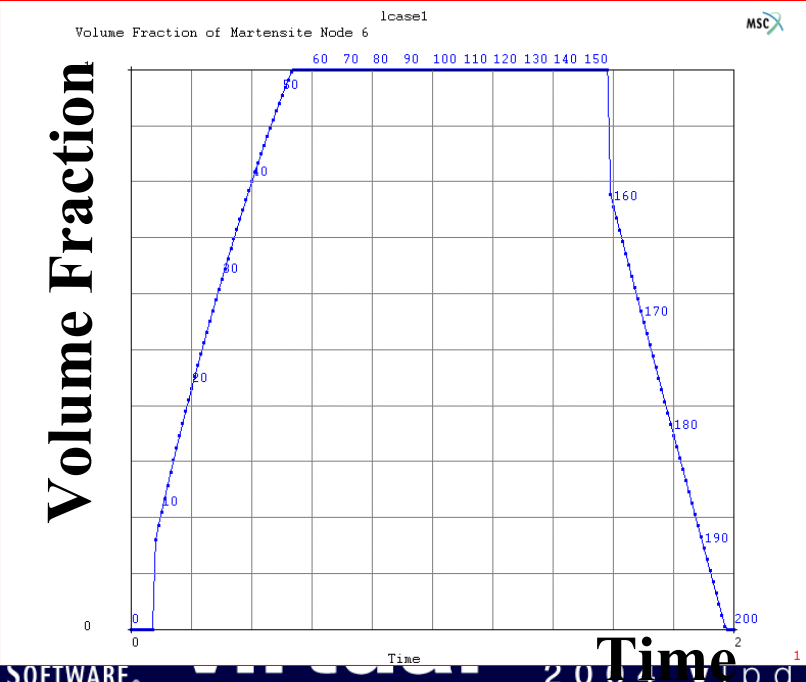
# \* Thermo-Mechanical Model Verification : Thermo-Cycle (2)



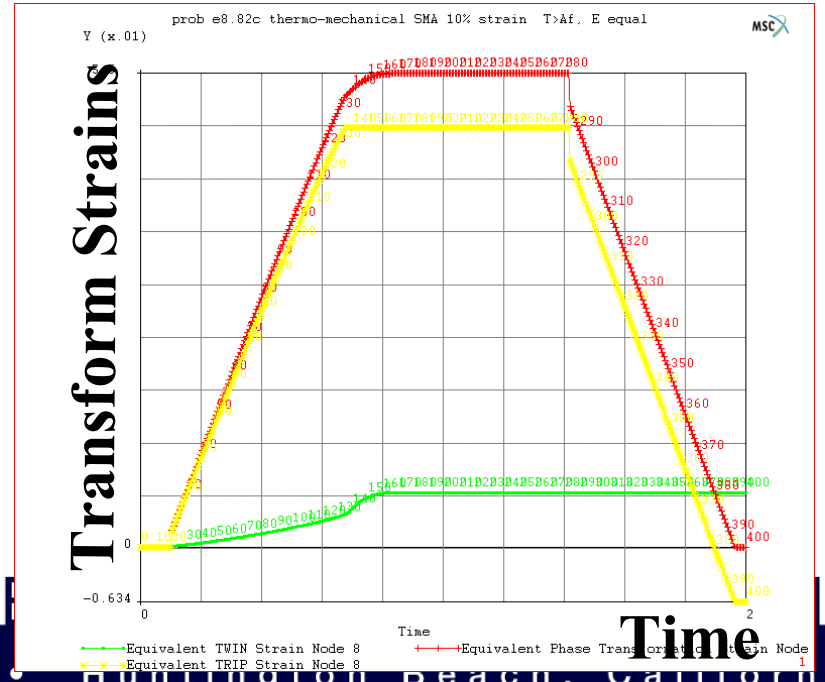
# \* Thermo-Mechanical Model Verification : Mechanical Cycle (1)



Total Strain



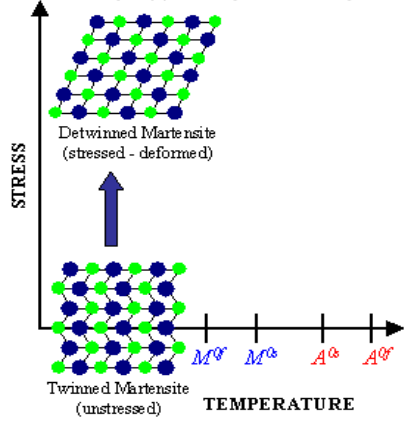
Time



Time

# Thermo-Mechanical Model Verification : $G$ -function's major effect (1)

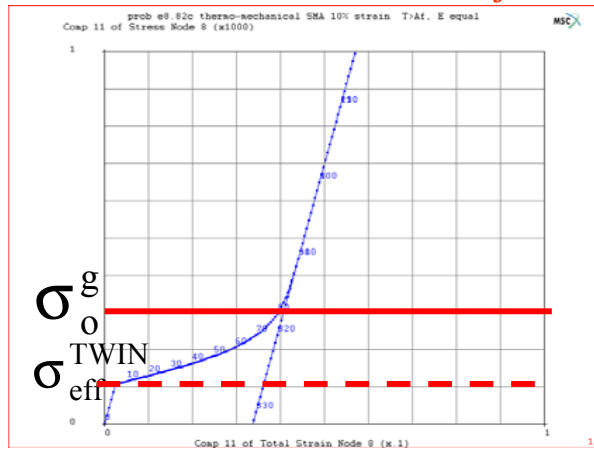
## (Contribution to Twinning Strain : Starting with $V_f = 1.0$ )



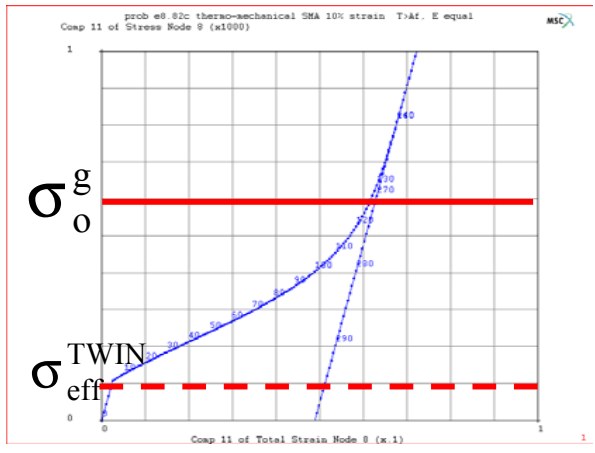
$$g(\sigma_{eq}) = 1 - \exp \left[ a \left( \frac{\sigma_{eq}}{\sigma_0^g} \right)^n \right]$$

$$\dot{\epsilon}^{TWIN} = f \dot{g}(\sigma_{eq}) \epsilon_{eq}^T \frac{3}{2} \frac{\sigma'}{\sigma_{eq}} \{ \sigma_{eq} \} \{ \sigma_{eq} - \sigma_{eff}^{Twin} \}$$

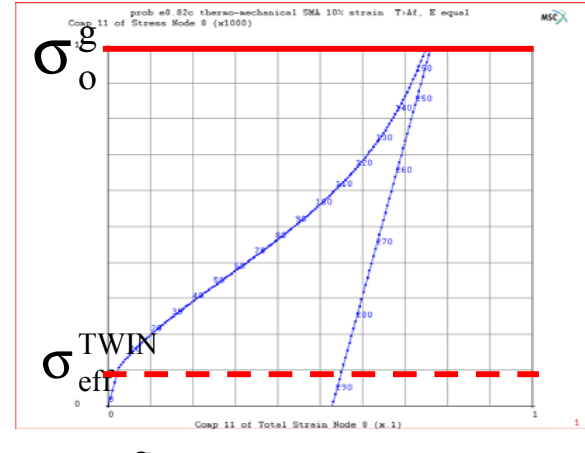
*$G$ -function values ( $a, n$  and  $\sigma_0^g$ ) should be selected to fit Exp. Curve Under  $M_f$  (Under  $M_f$ , Phase Transformation Strain = Twin Strain)*



$\sigma_0^g = 300 \text{ Mpa}$



$\sigma_0^g = 600 \text{ Mpa}$



$\sigma_0^g = 1000 \text{ Mpa}$

# Thermo-Mechanical Model Verification: G-function's side effect (2)

## (Contribution to Trip Strain : Starting with $V_f = 0.0$ )

$$g(\sigma_{eq}) = 1 - \exp \left[ a \left( \frac{\sigma_{eq}}{\sigma_o^g} \right)^n \right] \quad \dot{\epsilon}^{TRIP} = \dot{f}^{(+)} g(\sigma_{eq}) \epsilon_{eq}^T \frac{3}{2} \frac{\sigma'}{\sigma_{eq}} + \dot{f}^{(+)} \epsilon_v^T \mathbf{I} + \dot{f}^{(-)} \epsilon^{Ph}$$

**Upper  $M_f$  , Phase Transformation Total Strain = Trip Strain + Twin Strain**

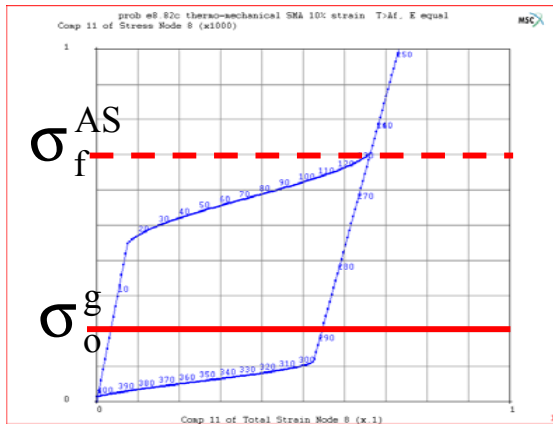
$\sigma_o^g$  effects the strain after the transformation (from Austenite to Martensite).

However, g-function value (a, n) also effect the strain during the transformation.

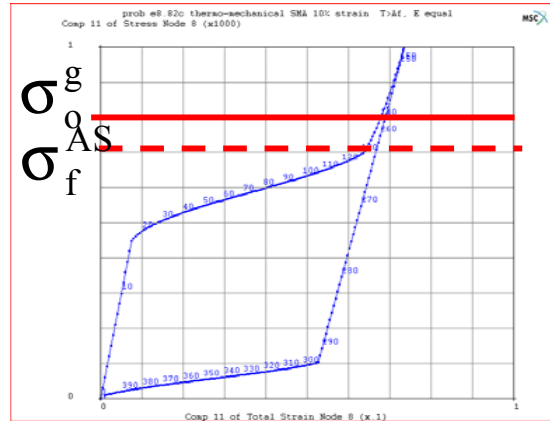
$\sigma_o^g < \sigma_f^{AS}$  (No effect)

$\sigma_o^g > \sigma_f^{AS}$

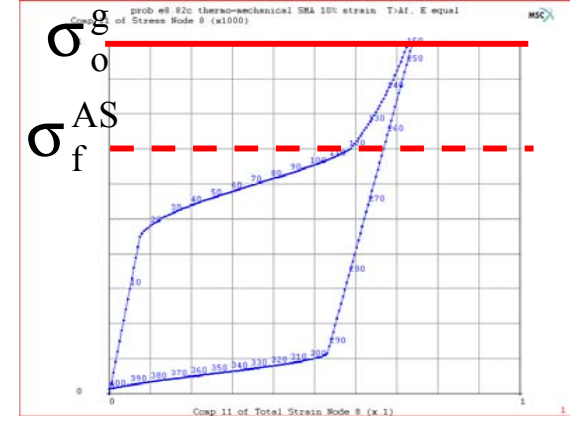
$\sigma_o^g > \sigma_f^{AS}$



$\sigma_o^g = 300 \text{ Mpa}$



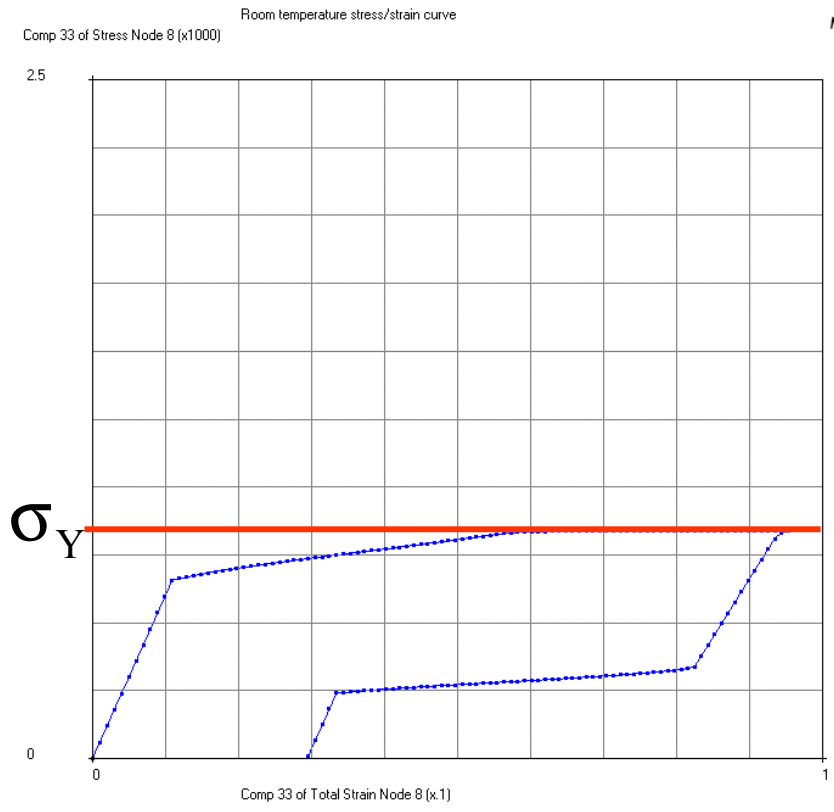
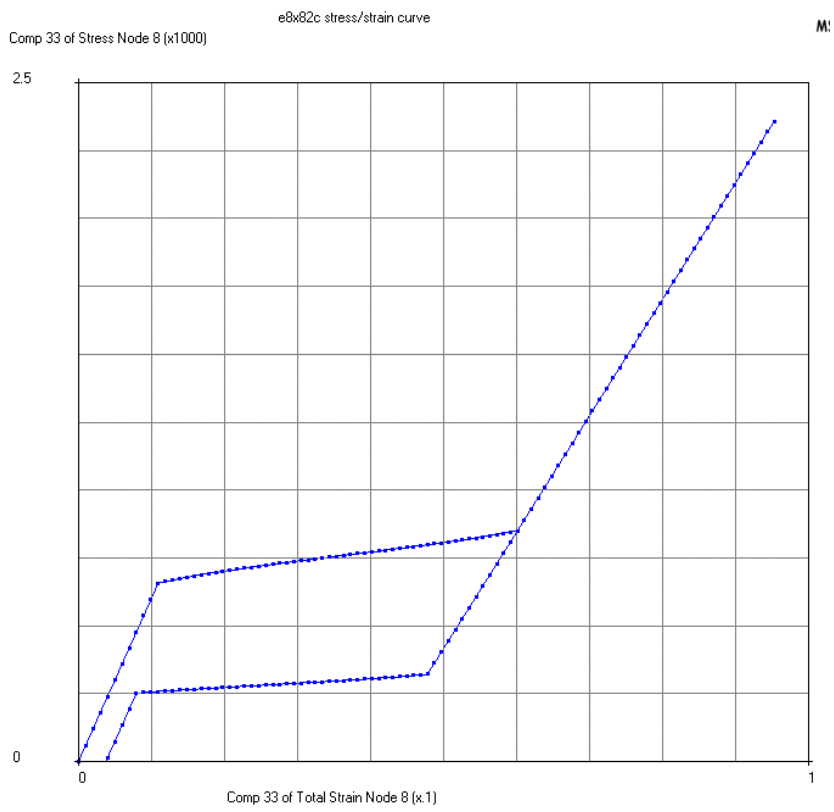
$\sigma_o^g = 800 \text{ Mpa}$



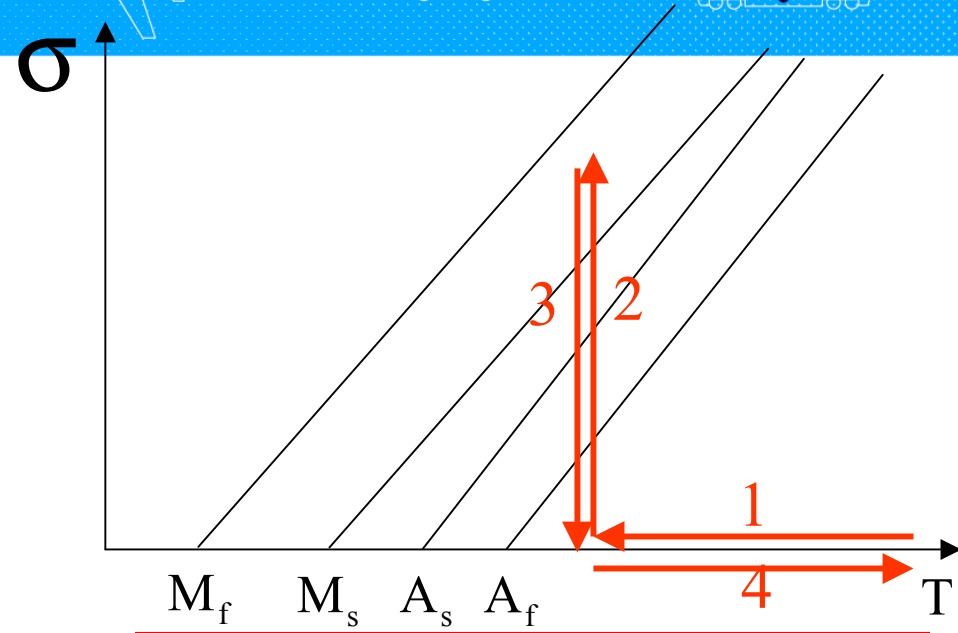
$\sigma_o^g = 1000 \text{ Mpa}$

No yielding for plasticity

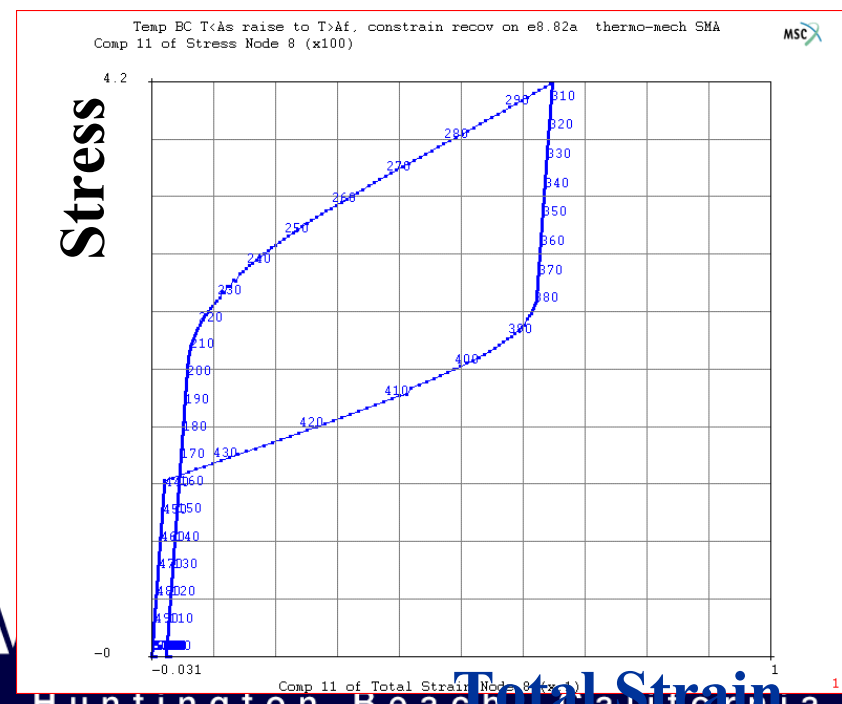
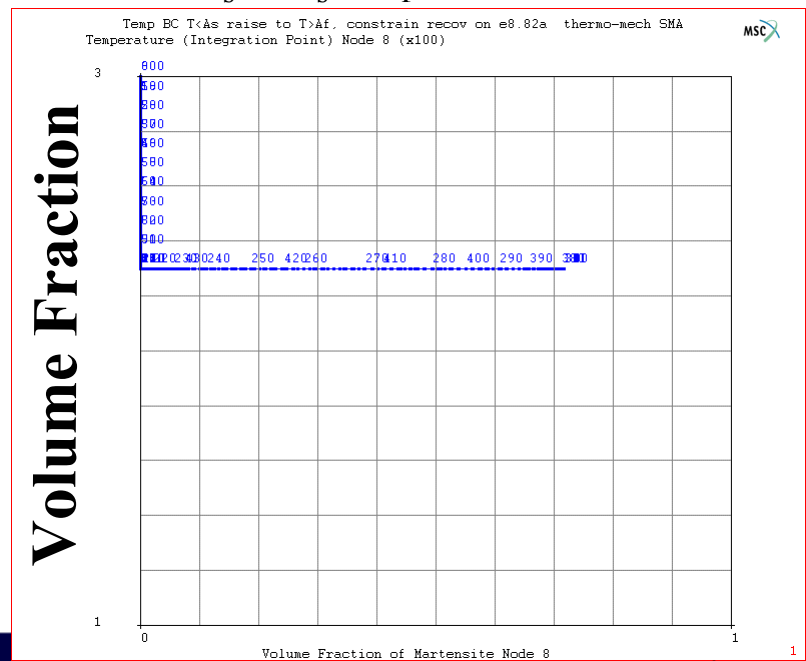
Yielding for Plasticity : 800 Mpa



# \* Thermo-Mechanical Model Verification : **Complex Coupled Cycle**



- 1 and 4 : Thermo Cycle
- 2 and 3 : Mechanical Cycle (Loading between  $M_s$  and  $M_f$ )



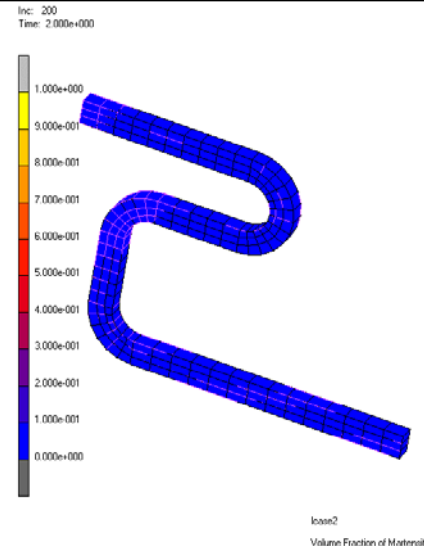
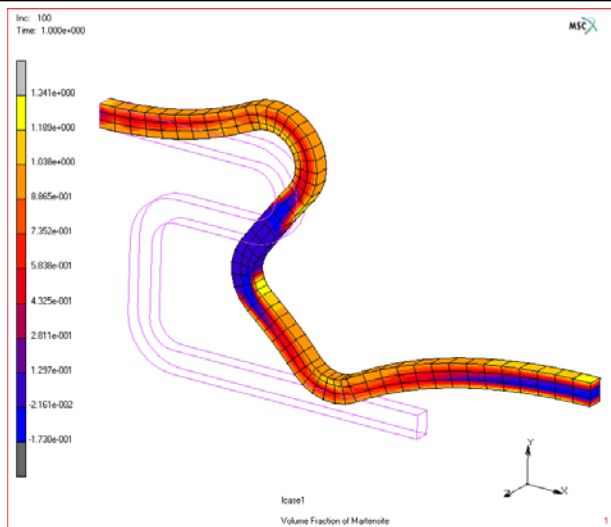


**Martensite fraction**

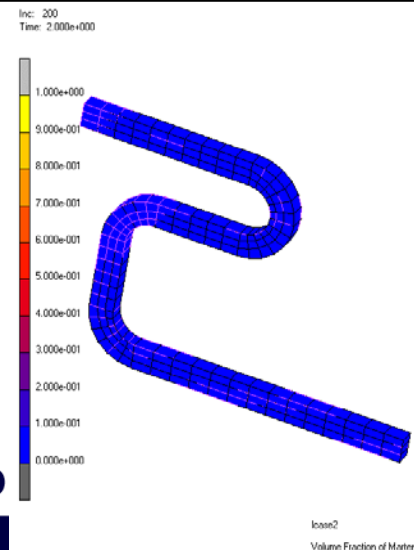
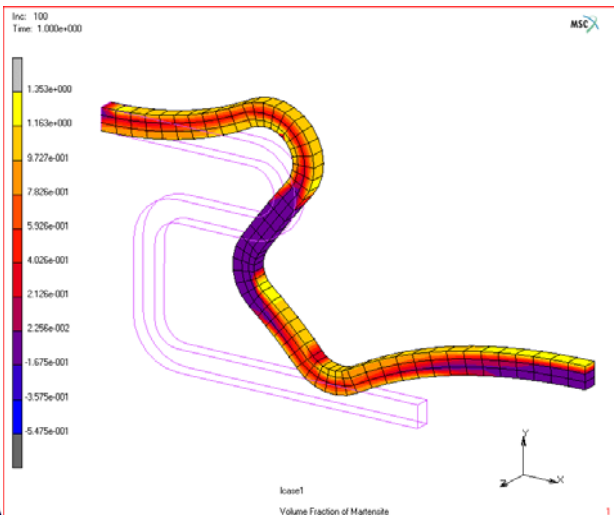
**Max. deformation**

**Unloaded**

**Thermo-mechanical model**



**Mechanical model**



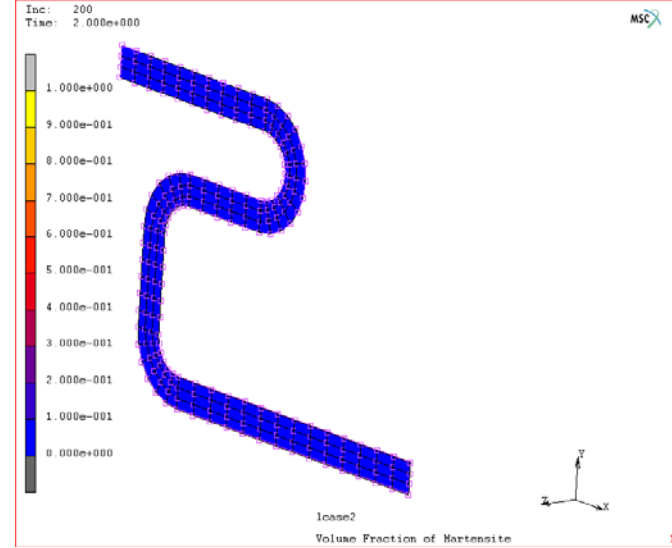
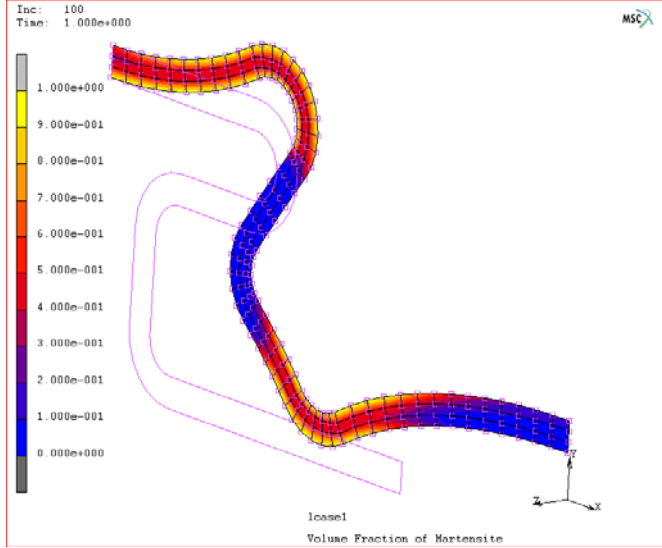
# Simulation with different type of elements : Shell Element

**Martensite fraction**

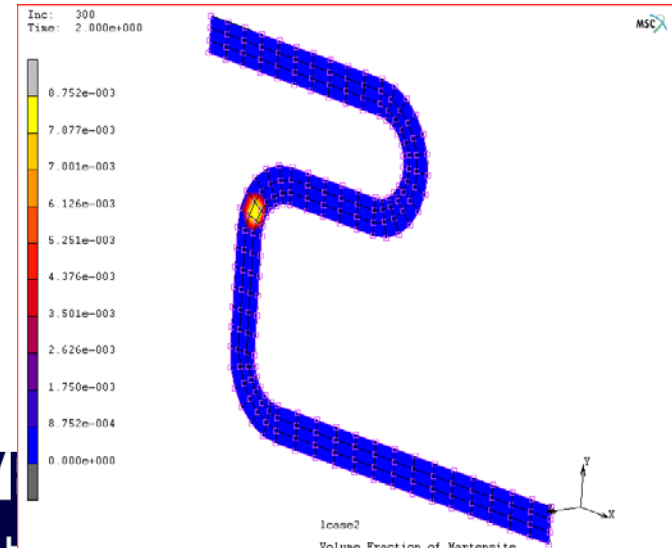
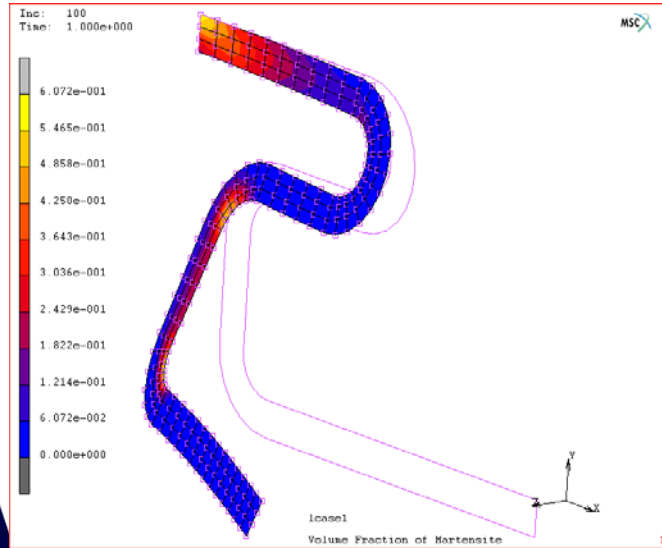
**Max. deformation**

**Unloaded**

**In-Plane Bending**



**Out of Plane Bending**

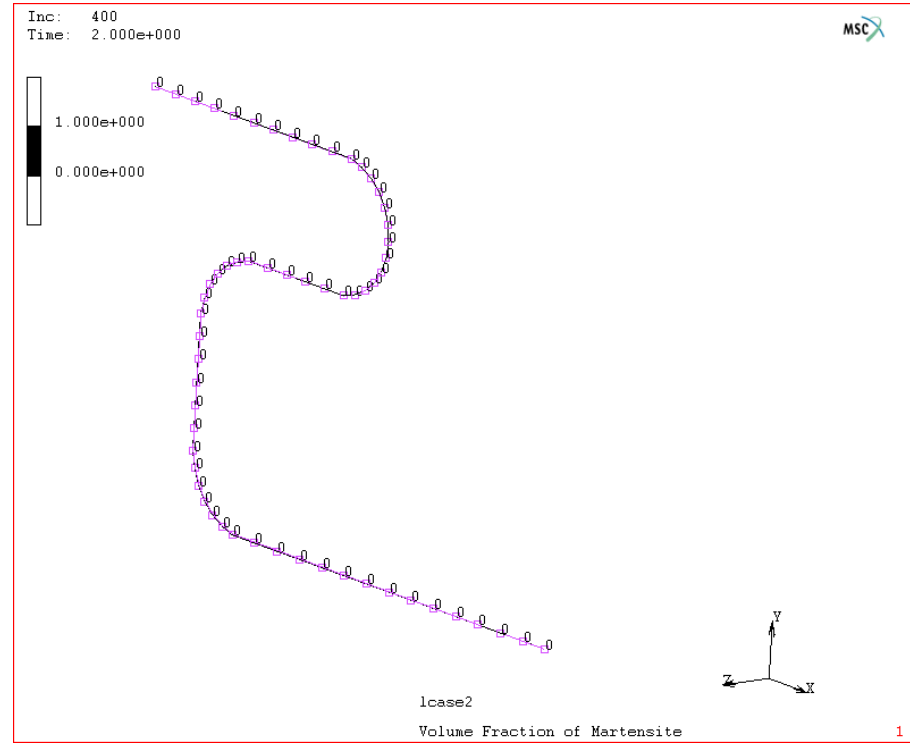
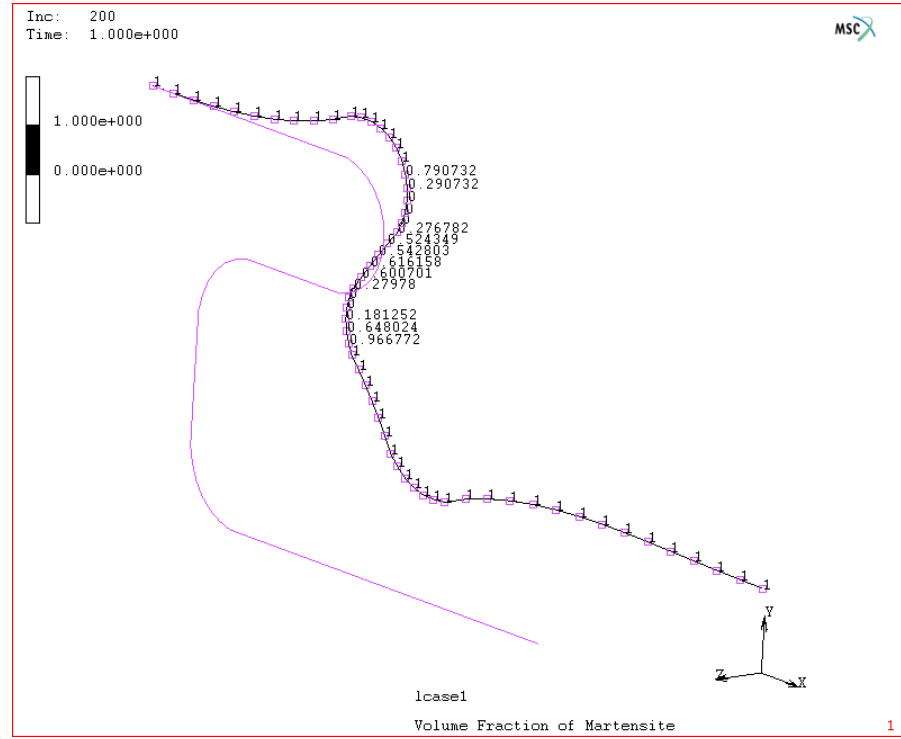




Martensite fraction contour

Max. deformation

Unloaded



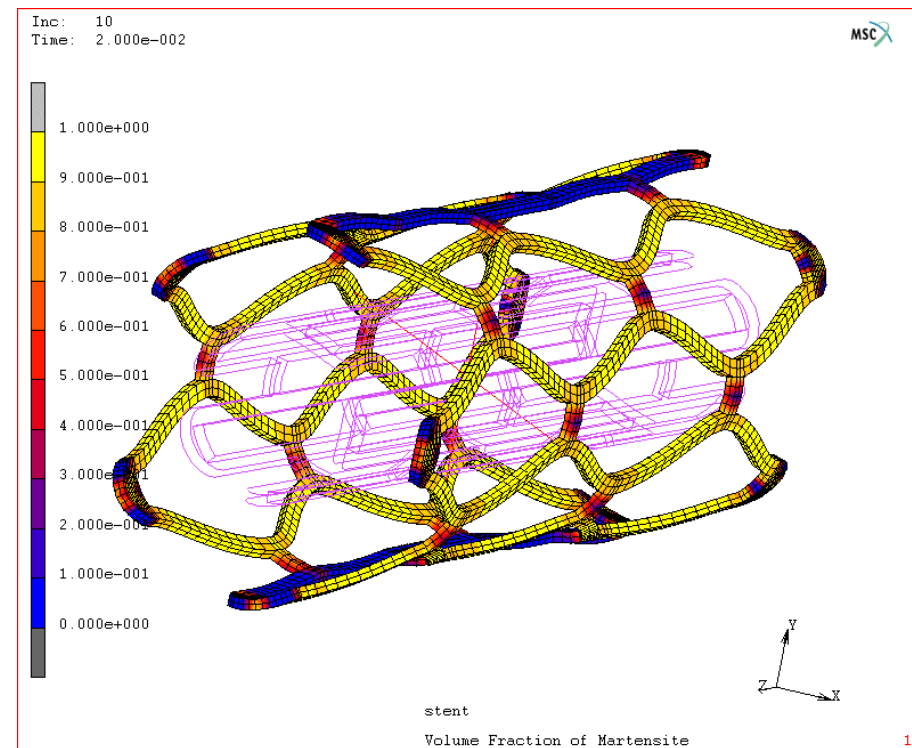
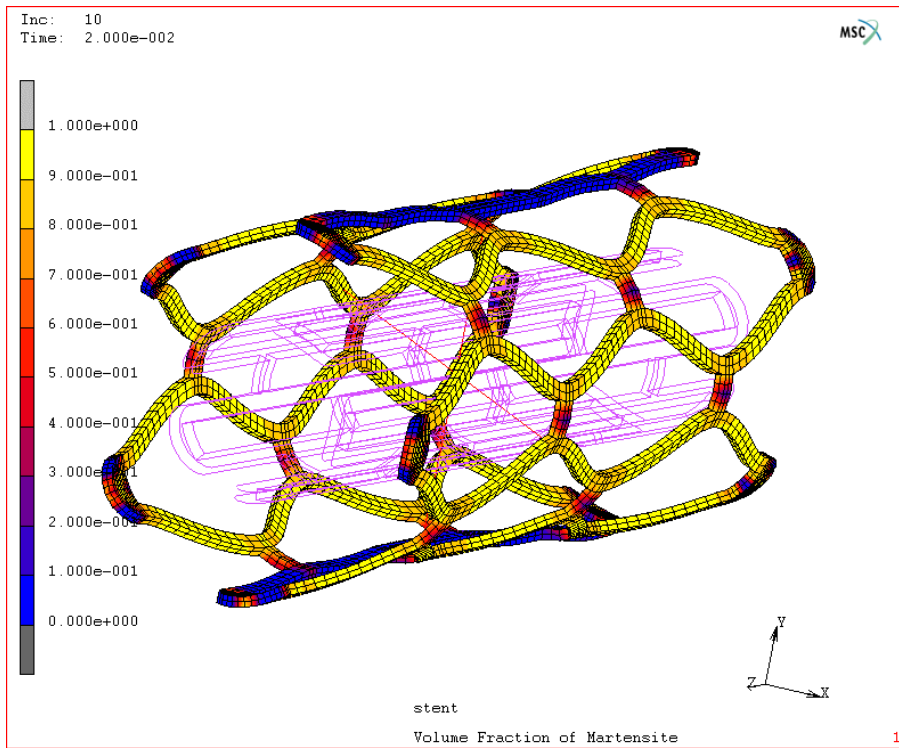


# Stent example with Solid Element

## Martensite fraction contour

### Thermo-mechanical model

### Mechanical model

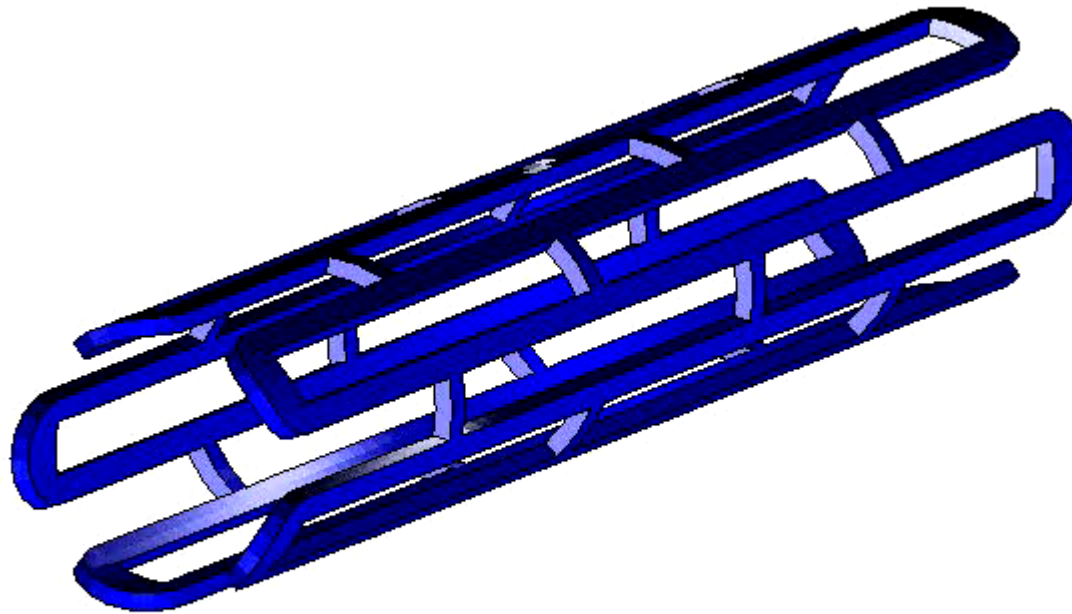




# Stent Simulation



MSC





## Implementation of two SMA models in MSC.Marc 2003

### 1. Thermo-Mechanical SMA Model :

- An Accurate Model including Trip, Twin and Plastic Strains
- Applied to Complex Thermo-Mechanical Coupling Analysis
- Support Solid, Shell and Beam Elements
- General Purpose Applications

### 2. Mechanical SMA Model

- Peuso-Elasticity Simulation over  $A_f$  Temperature
- Simple Input Data
- Support Solid Elements only
- Useful for Initial Verification