

ADAMS

Virtual Prototyping

Design Optimization Technique for Mechanical System

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Mechanical
Dynamics

Optimization Technology

- **Optimization of complex phenomenon**

Concept of Multidisciplinary Optimization

- **Development of New Methodology**

Genetic Algorithms

Response Surface Methodology

e.g. Crash Optimization by RSM



Optimization for Structural Design

- **Objective Function: Structural Weight**
- **Component, Stiffness, Crash**

Optimization for Fluid Dynamics Design

- **Objective Function: Lift, Drag**
- **Wing Section Design, Blade Design**



Optimization for Mechanical System Design

Few Achievement

Many design parameters

Strong nonlinearity

Difficult to define objective function

In order to clarify the benefit of design optimization technique,

we conducted case study of suspension design.



Suspension Design

<Analysis 1>

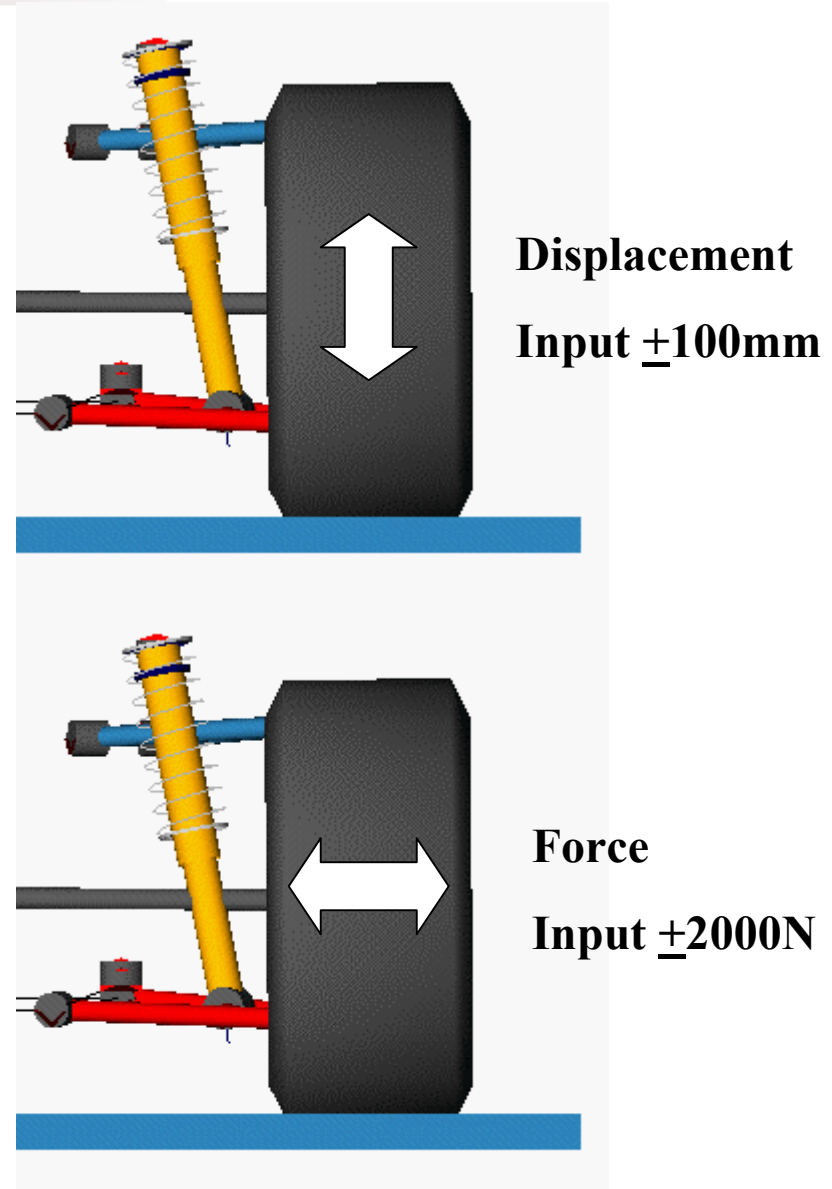
Vertical Motion $\pm 100\text{mm}$

Evaluate Toe Characteristic

<Analysis 2>

Static lateral Force $\pm 2,000\text{N}$

Evaluate Lateral Stiffness



Suspension Design

20 Design Variables

Geometry: 18 Variables

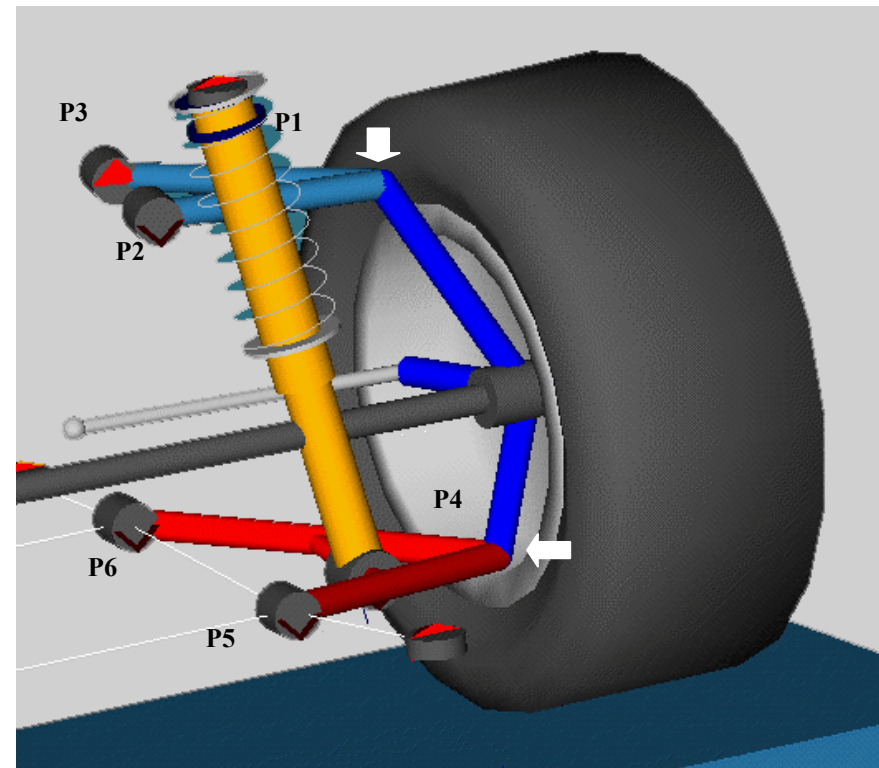
$P1(x,y,z)$ - $P6(x,y,z)$

Original ± 100 mm

Bush : 2 variables

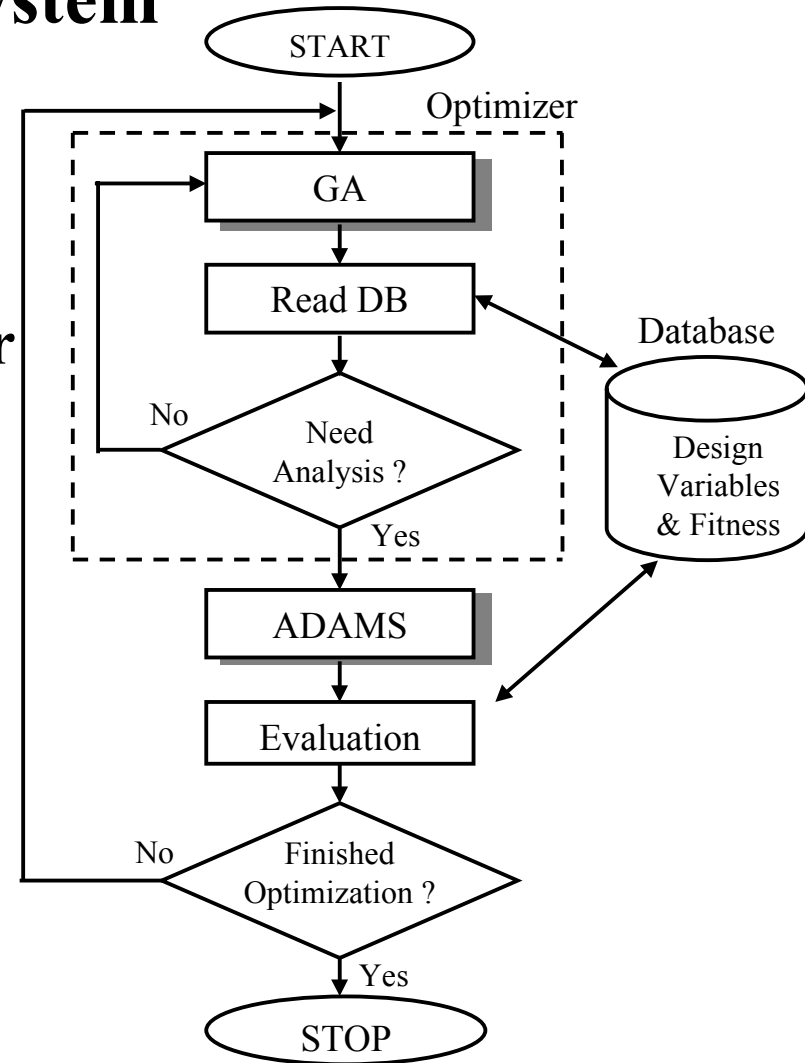
Bush_upr/Bush_lwr

40%-200% of original

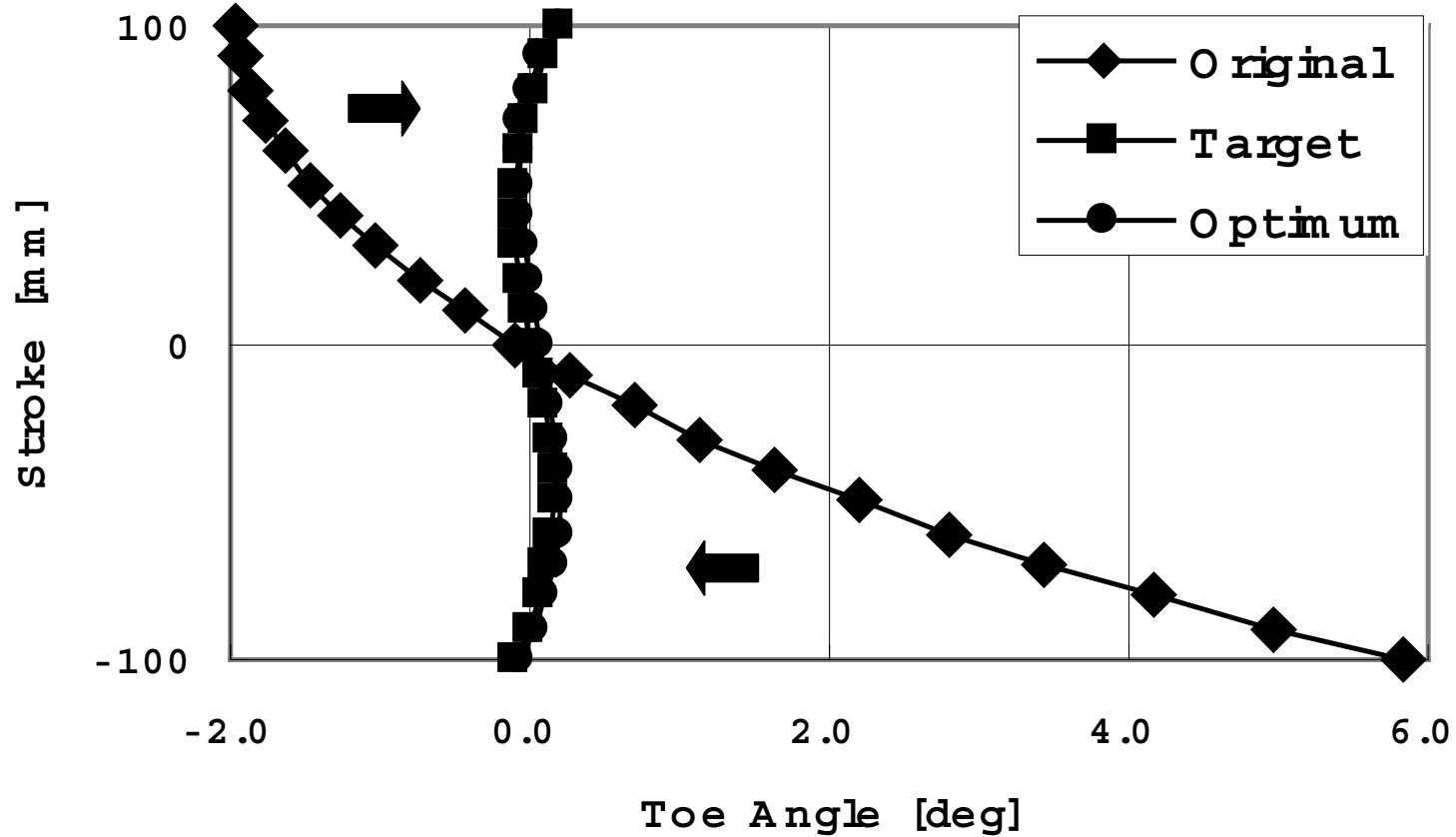


Developed Optimization System

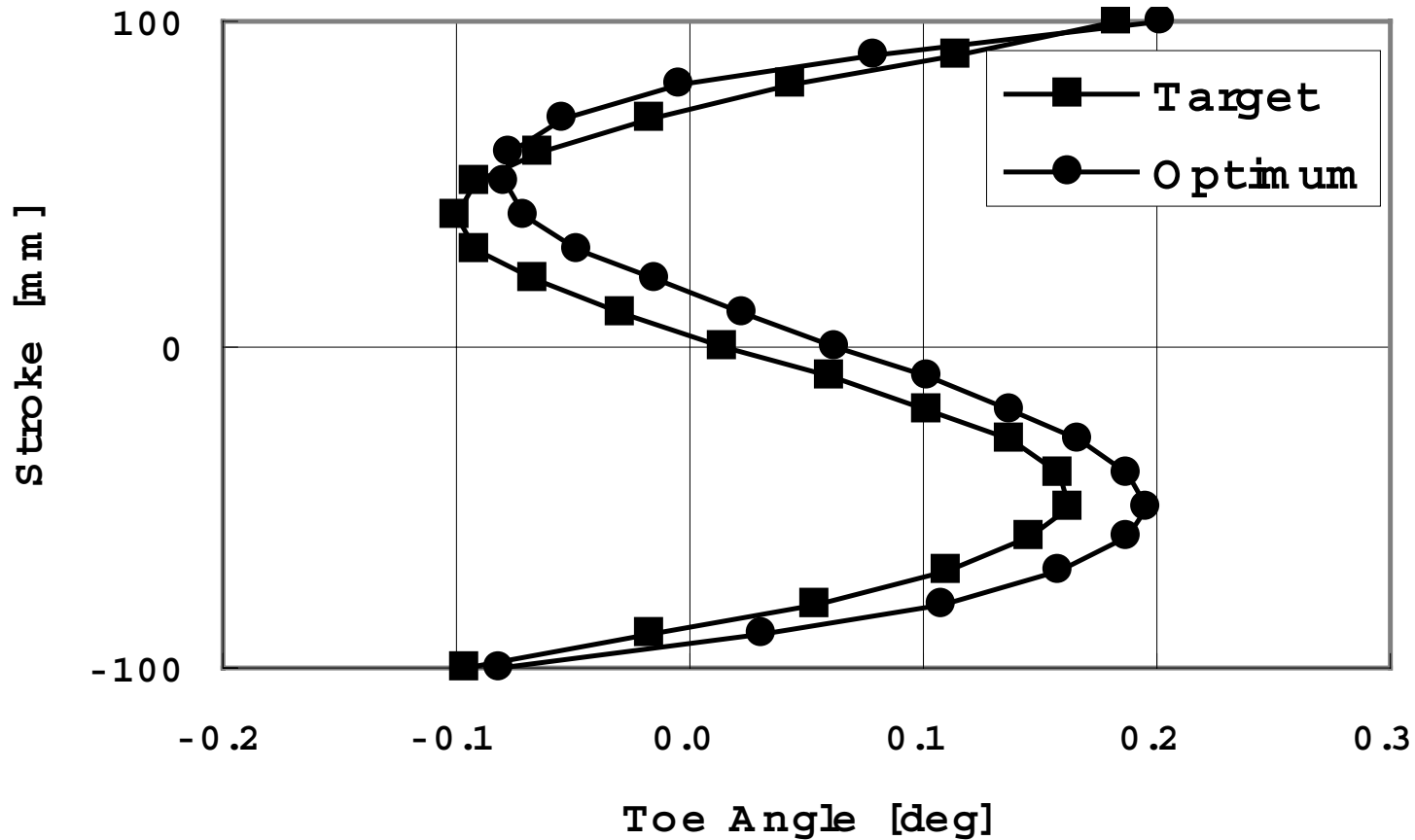
- **Optimization Algorithm**
 - **By Genetic Algorithms (GA)**
- **Interface with ADAMS/Solver**
 - **Generate ADAMS Solver file using GA information**
 - **Evaluate the request data file and save data into database**
- **Skip the ADAMS simulation if conducted previously**



- *Optimized Toe Angle*
- *Target Toe : From Prof. Abe's Data*



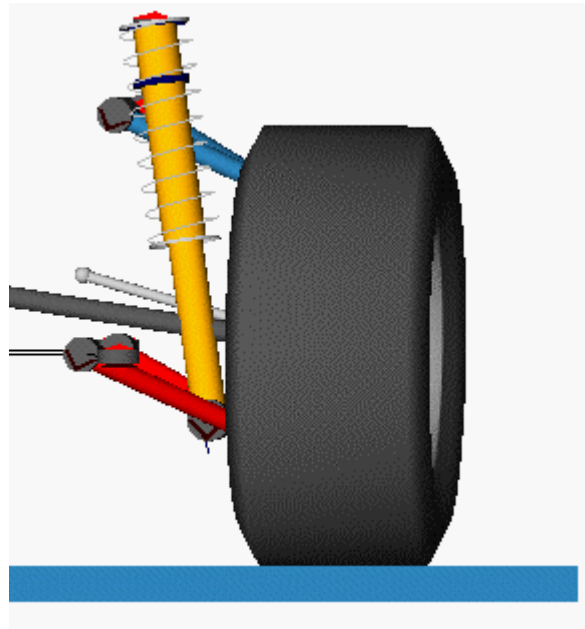
- *Optimized Toe Angle*
- *Target Toe : From Prof. Abe's Data*



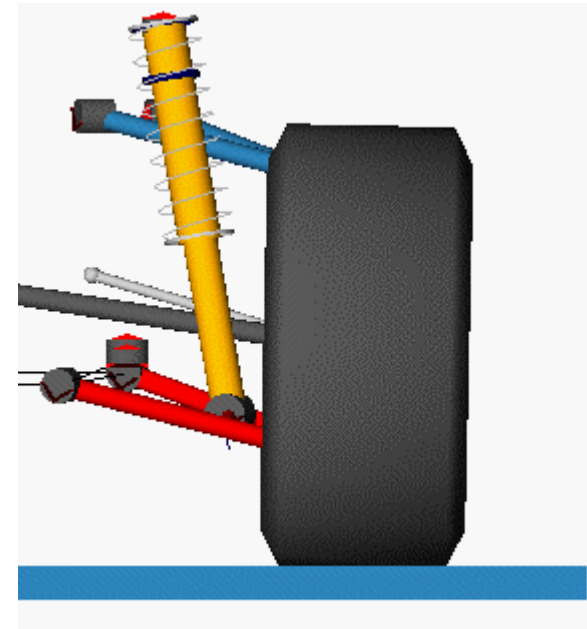
Maximum Error=0.05 deg after 3000 analyses



■ *Optimized Toe Angle*



Original Model

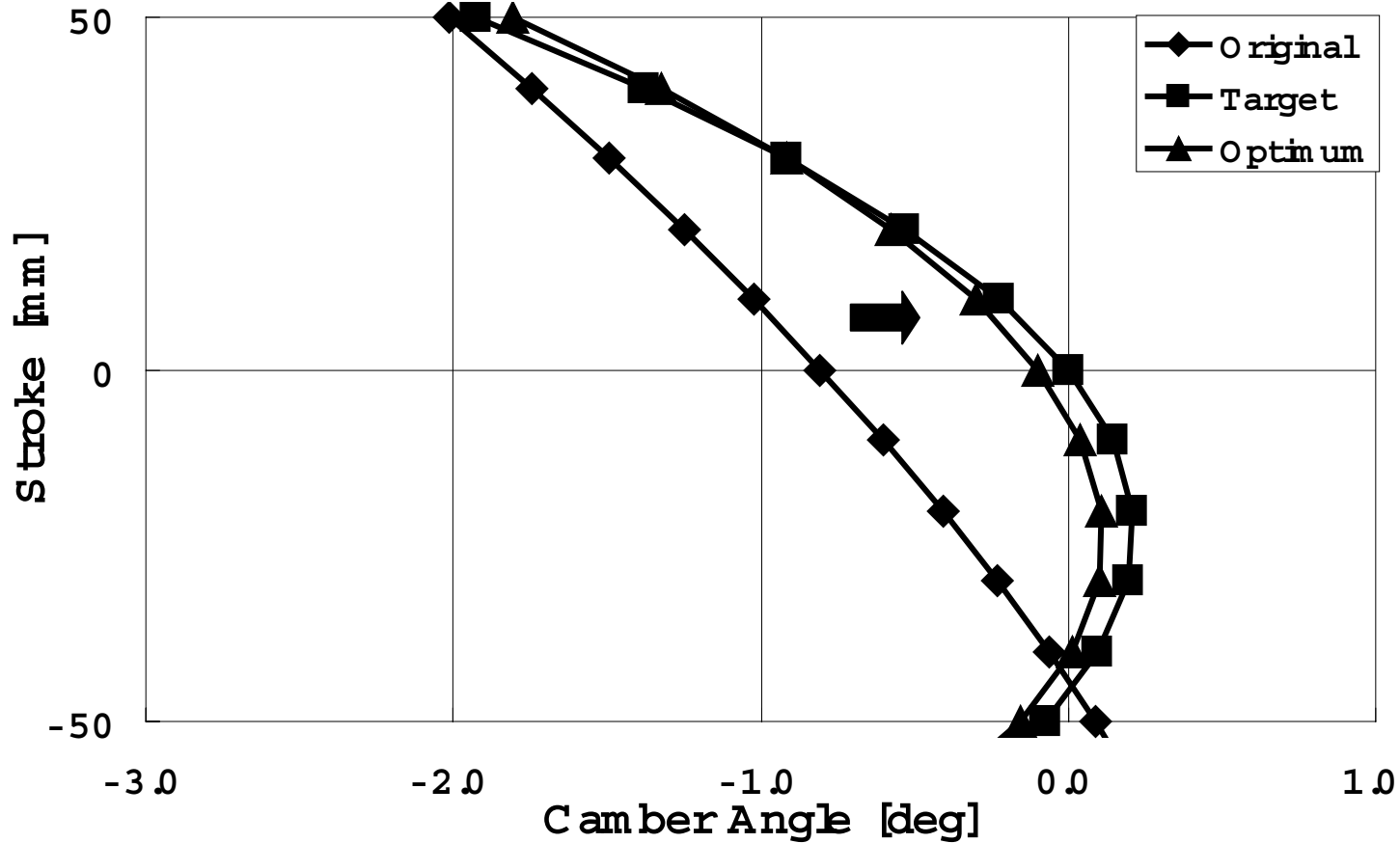


Optimized Model

Comparison Toe Angle at Vertical Displacement -100mm



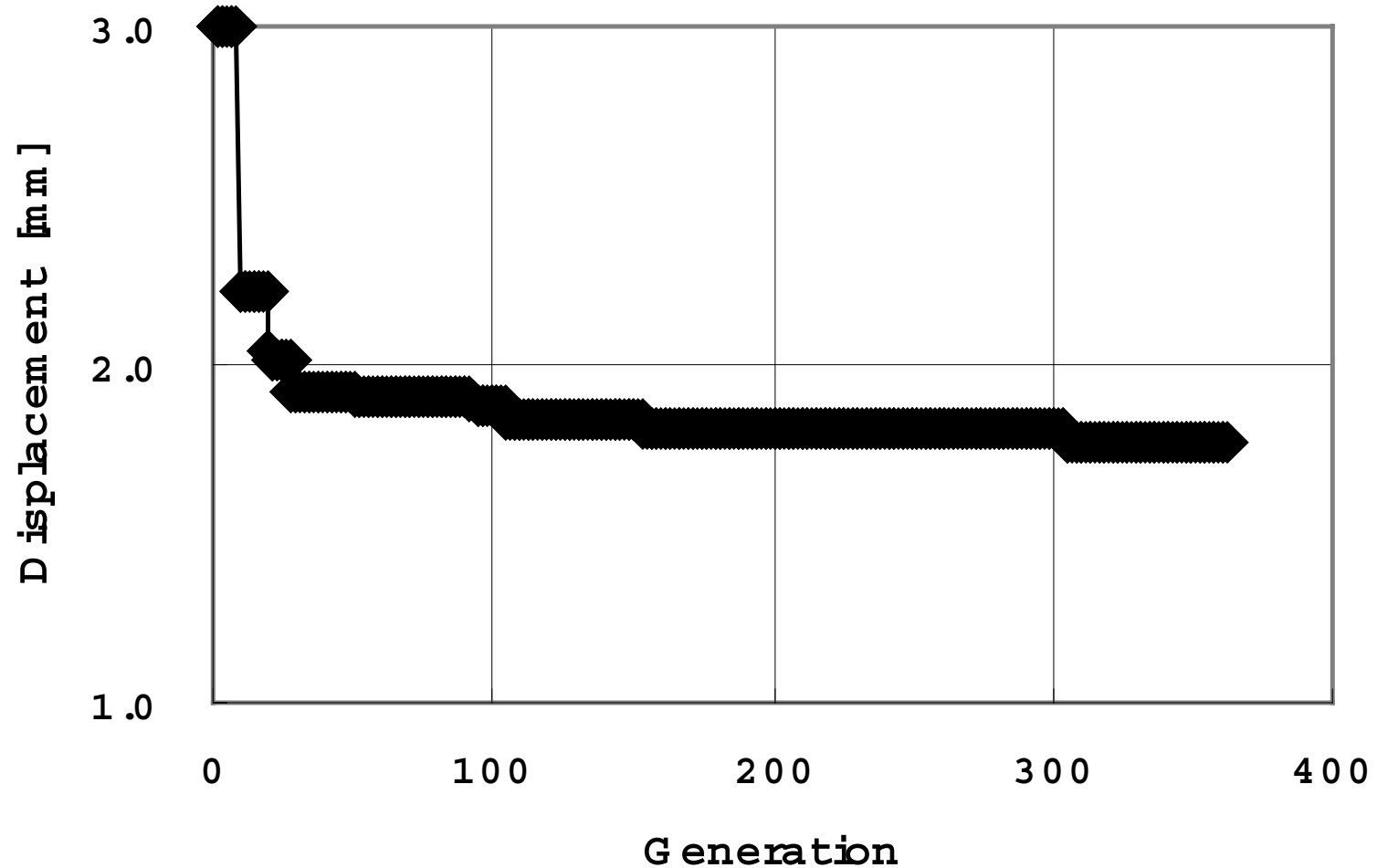
- *Optimized Camber Angle*
- *Target Camber : From Prof. Abe's Data*



Maximum Error=0.05 deg after 3000 analyses



■ *Minimized Lateral Displacement*



Constraint: Toe Error less than 0.1 deg
Objective Function: Maximize Lateral Stiffness



- 1) We have developed optimization system based on Genetic Algorithms for Mechanical System Design.**
- 2) Using this system, we have optimized suspension system. Through the case study, the validity of the system was clarified.**
- 3) We will apply optimization technique for complex systems.**
- 4) Design optimization technique will supply outstanding contribution for the mechanical system engineering.**





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**Comparison of Gradient
Search with Genetic
Algorithms for Nose
Landing Gear**

Patrick McNally, MDI



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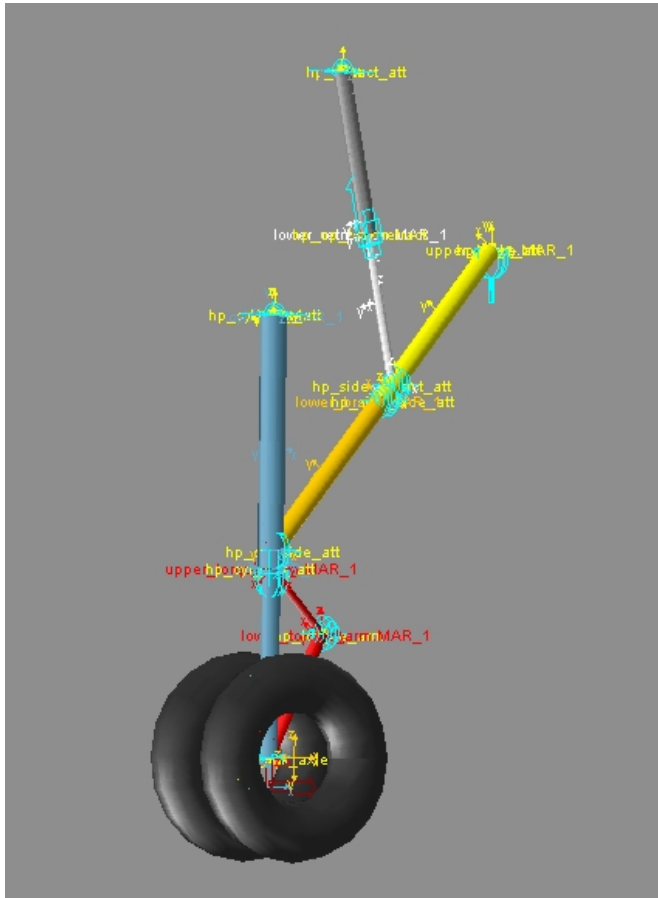
Comparison of Genetic Algorithms with Gradient Search for Landing Gear Optimization

- Optimize geometric layout
- Maximize retraction efficiency
 - ◆ used in actuator sizing
 - ◆ ensures constant demand on hydraulic system
- Optimization constraints to ensure full retraction and avoid lockup conditions

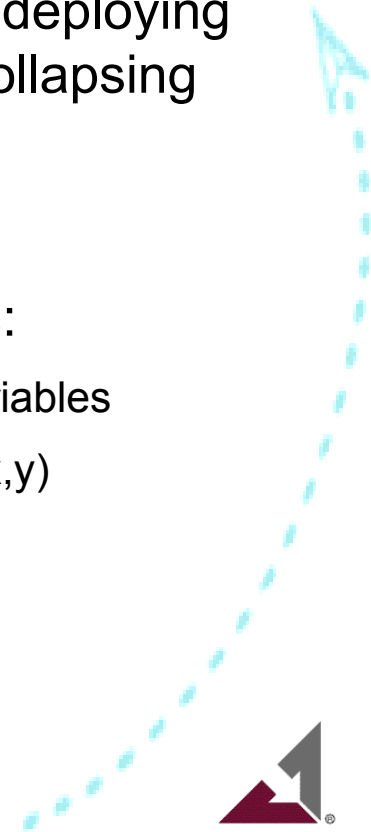


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Nose Landing Gear for Optimization



- Conventional aft-deploying nose gear with collapsing brace
- Rigid Model only
- Design Variables:
 - ◆ 20 geometry variables
 - ◆ $P1(x,y) \rightarrow P10(x,y)$





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Retraction Efficiency Function

$$\left| \max(F_R) \cdot \theta_{\max} \right| - \int_{\theta_0}^{\theta_{\max}} F_R(\theta) \cdot d\theta$$

Where

F_R ~ retraction force
 θ ~ retraction angle

Rewritten as time function:

$$\left| \max(F_R) \cdot \theta_{\max} \right| - \int_{t_0}^{t_{\max}} F_R(\theta) \cdot \dot{\theta} \cdot dt$$

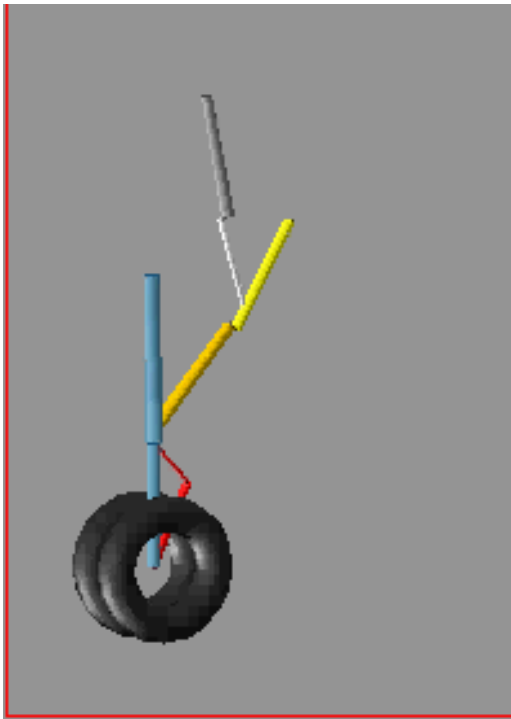
Solver language:

- `fun = (MAX(ABS(MOTION(.nosegear.MOT1, 0, 1, 0)) , 0) * ABS(AZ(.nosegear.cylinder.MAR1100, .nosegear.PAR99.MAR_1)) - DIF(.nosegear.DIFF_1))`
- `DIFF_1=MOTION(.nosegear.MOT1, 0, 1, 0)
*VZ(.nosegear.lower_retraction.MAR507,
.nosegear.upper_retraction.MAR407)`

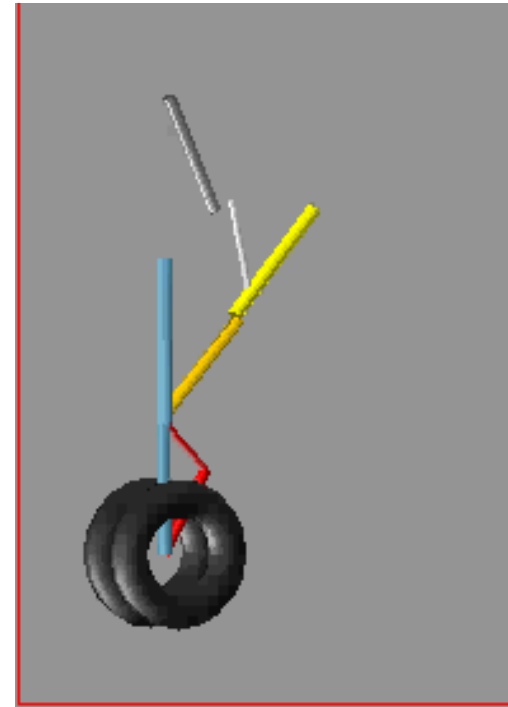


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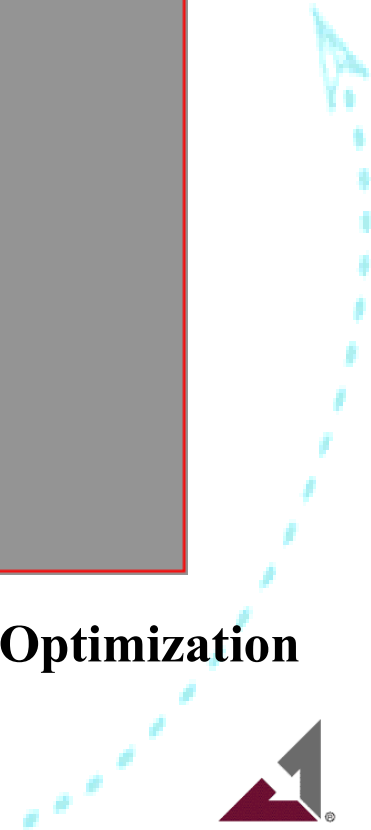
Initial Results Show Different Optimums Found through Different Searches



Gradient Search Optimization



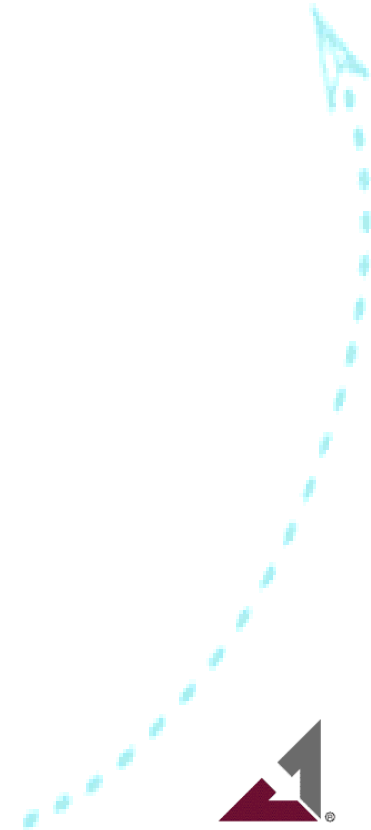
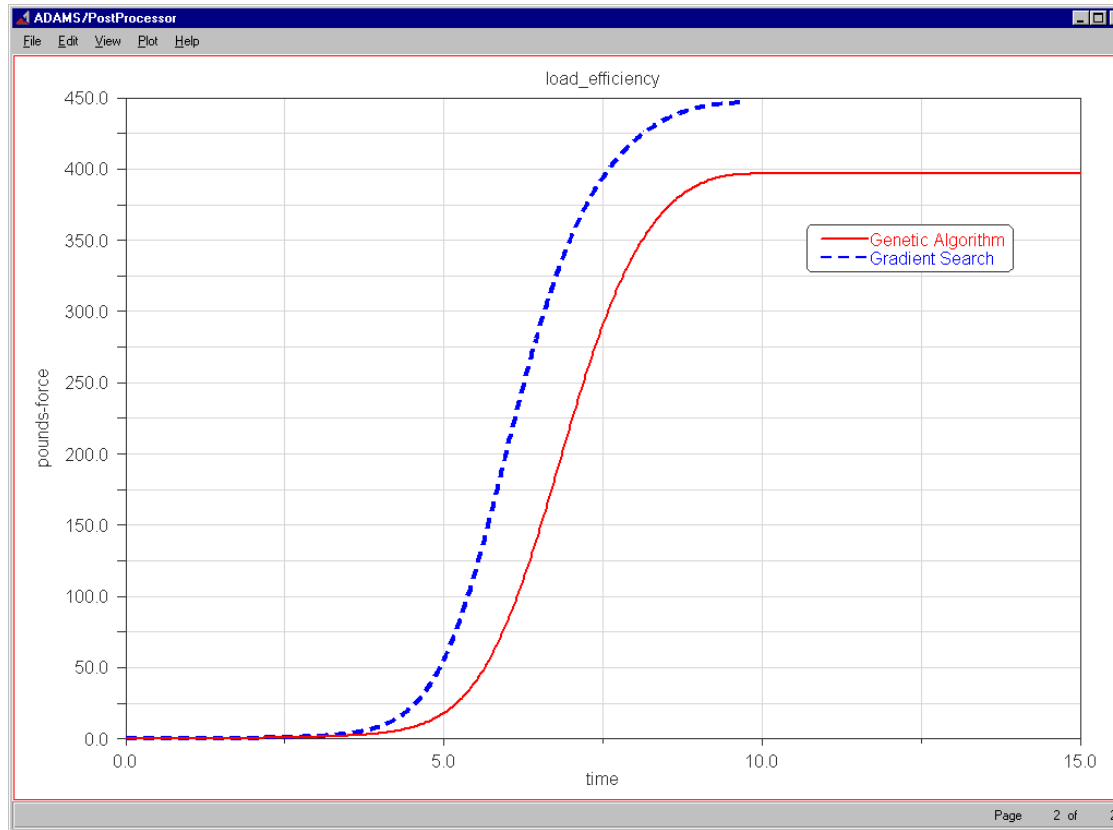
Genetic Algorithm Optimization





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Initial Results Show Gradient Search Found Optimal More Quickly





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Conclusions for Landing Gear Problem

- ADAMS architecture allows easy comparison between design study and optimization methods
- Simplified problem (kinematic/planar) means gradient search may find global optimum
- Hydraulic system effects to be added to understand effect on optimal
- Main gear (nonplanar) mechanism to explore effects of more complex layouts