STEERING PERFORMACE SIMULATION OF AGRICULTURAL TRACKED TRACTORS USING ADAMS

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Abstract

The development of rubber tracks has made attractive the use of tracked vehicles for agricultural purpose. One important point in the design of these vehicles is the steering system due to the high turning resistance of tracked machines. In this paper a model for steering performance simulation of agricultural tracked vehicles is presented. The model was developed using ADAMS (Automatic Dynamic Analysis of Mechanical System). A set of FORTRAN subroutines and macros was developed to create a parametric model of the vehicle to simulate the power train system and to calculate the forces in the track-soil interface. From the characteristics of the system and the soil, the user can predict the trajectory of the vehicle in the field as a function of the input to the steering wheel. This permits a designer to change components in the vehicle and see what influence this has on steering. The model has shown to be flexible and very ease to use. This model is going to be validated in the future based on experimental tests.

ADAMS Applications at John Deere

by
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Abstract

This oral only video presentation will briefly cover several recent ADAMS applications within John Deere with an emphasis on vehicle dynamics. Included will be examples of ride simulation, load prediction, lateral stability, handling, power hop, power train modeling, inclusion of friction forces in joints, hydraulic system modeling and clearance checking within the ProE environment.

Notes:

For each of the examples, I'd like to start with video footage of an actual machine and follow that with an animation of the ADAMS model of that machine.

ride simulation - row crop tractor on rough track followed by one third octave

acceleration plot and then animated tractor vibration modes

load prediction - use combine footage with actual test followed by simulation model

lateral stability - combine on tilt table (quasi static analysis followed by Gator making

a hard turn

handling - lane change maneuver, first of production tractor, seeder and cart

(stable) followed by a concept configuration that was unstable - then show related model of lightweight five gang fairway mower making

a 180 degree turn

power hop - animation of unstable and stable configurations, plot of root locus

for unstable mode and animation of unstable mode

power train

modeling - industrial four wheel drive loader model that had models of engine,

torque converter and axle differentials

friction - transmission shift analysis including joint friction effects

hydraulic system

modeling - model of bucket leveling system on backhoe loaders

clearance checking - use of MDI's MECHANISM/Pro product to define ADAMS model

from within ProE, resultant clearance checking analysis and animation of model using the log skidder grapple as an example

1995 INTERNATIONAL ADAMS CONFERENCE

INTRODUCING TERRAMECHANICS INTO ADAMS MODELS OF OFF-HIGHWAY VEHICLES

KELLY D. BOWLAND

ADAMS is a proven tool for design and analysis of vehicle dynamics. Specifically, there has been much success in modeling off-highway equipment to determine design parameters such as hydraulics, operator visibility, vehicle stability and much more.

In general, the designer and engineer are responsible for creating an off-road vehicle with superior performance, handling and ride characteristics. These characteristics determine the behavior of the vehicle but are impacted by inputs from the driver as well as the physical environment.

In many cases, the ADAMS model of these vehicles represent a validated prototype of the vehicle itself with all the suspension, linkage, hydraulic, tire and even driver elements; however, the physical environment such as soil characteristics is rarely included.

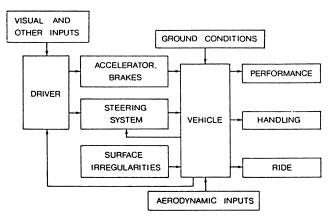


Fig. 1 The driver-vehicle-ground system.
(Reference: "Theory of Ground Vehicles", J.Y. Wong, Ph.D.)

Whether the running gear is a tire or track, an ADAMS model which incorporates the interaction between an off-road vehicle and its physical environment, a study called terramechanics, would create more realistic conditions and allow for better design evaluation of the overall system.

GENERAL OVERVIEW

ASSUMPTIONS

- -- Homogeneous Material/Soil
- -- Elasto-plastic Material

SOIL VARIATIONS

- -- Disturbed vs. Undisturbed
- -- Cohesion vs. Friction

SOIL CATEGORIZATION

- -- Hard/Dry
- -- Fairly Moist
- -- Wet

SOIL CHARACTERISTICS

- -- Elastic
- -- Plastic Equilibrium
- -- Plastic

TRACK ELEMENT

ASSUMPTIONS

- -- Non-flexible Track
- -- Homogeneous Material/Soil
- -- Uniform Pressure Distribution
- -- Plate

BEARING CAPACITY/CRITICAL LOAD

- -- Load Per Unit Contact Area at Failure
- -- Non-cohesive Soils / Width
- -- Cohesive Soils / Contact Area

MOTION RESISTANCE

- -- Sinkage / Soil Characteristics
- -- Bulldozing Resistance (Frontal Drag)

TRACTIVE EFFORT

- -- Non-cohesive Soil / Vehicle Weight
- -- Cohesive Soil / Contact Area
- -- Thrust and Slip
- -- Drawbar Pull

DESIGN APPLICATIONS

CUTTING BLADES

- -- Vertical Blade vs. Inclined
- -- Power Requirements / Blade Force

TRACK DIMENSIONS

- -- Contact Area
- -- Width
- -- Length

TIRE PARAMETERS

- -- Wheel Diameter
- -- Pressure Requirements

LUGS / GROUSER DESIGN

- -- Spacing
- -- Dimensions

MATERIAL SPECIFICATIONS

-- Smoothness of Surface

MODELING IN ADAMS

Introducing terramechanics into ADAMS models of off-road vehicles allows both the designer and engineer to predict and tune the performance characteristics of their system with an even more realistic environment.

DESIGN OF EXPERIMENTS / OPTIMIZATION

- -- Determine Soil Categories
- -- Design Objective Based on Sinkage Limit

WHEEL TORQUE / ENGINE INPUTS

-- Consideration of Soil and Sinkage

TIRE INTERACTION

-- Tapping into Current Tire Algorithms

FRICTION ANALYSIS

-- Model Friction of Surface and Soil

2D ANALYSIS IN COMPUTER

-- Bring to 3D with full vehicle