

# Simulation of the tilting train VT611/612

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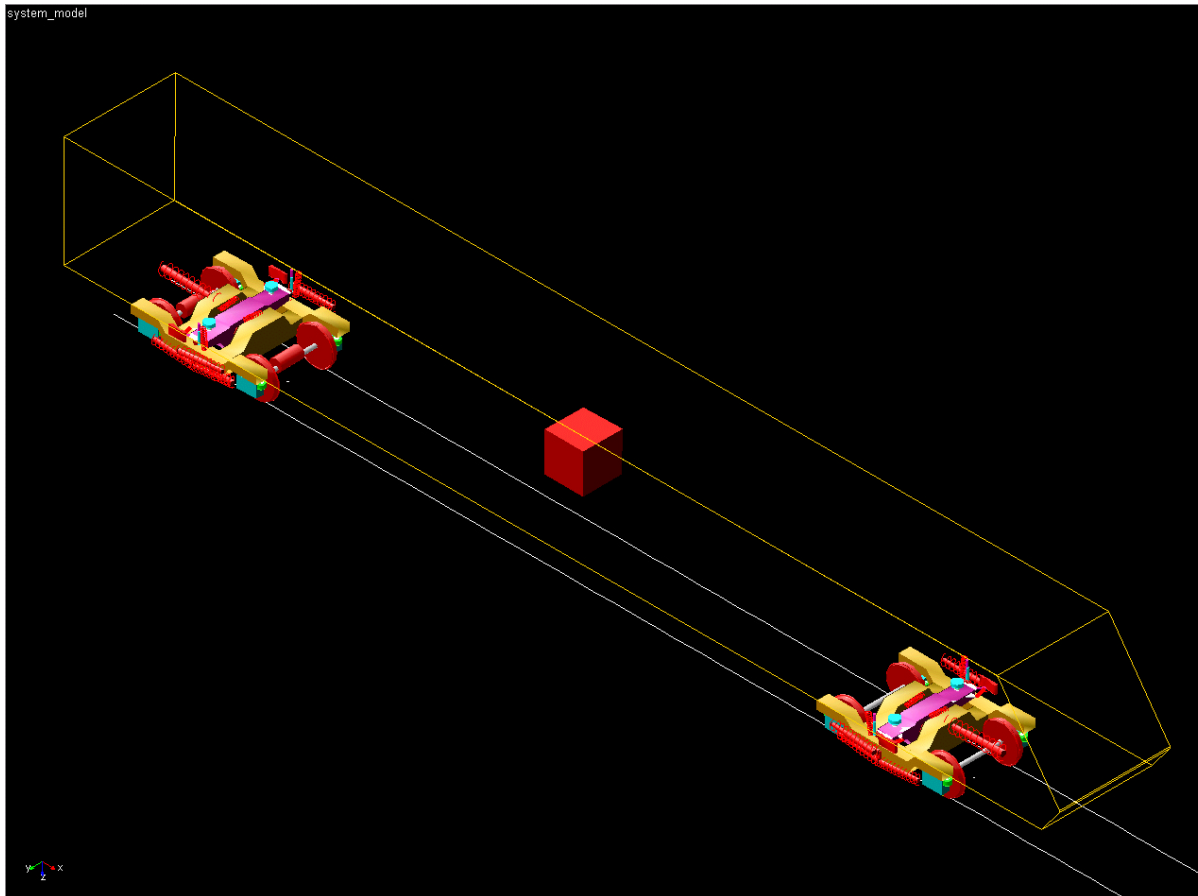
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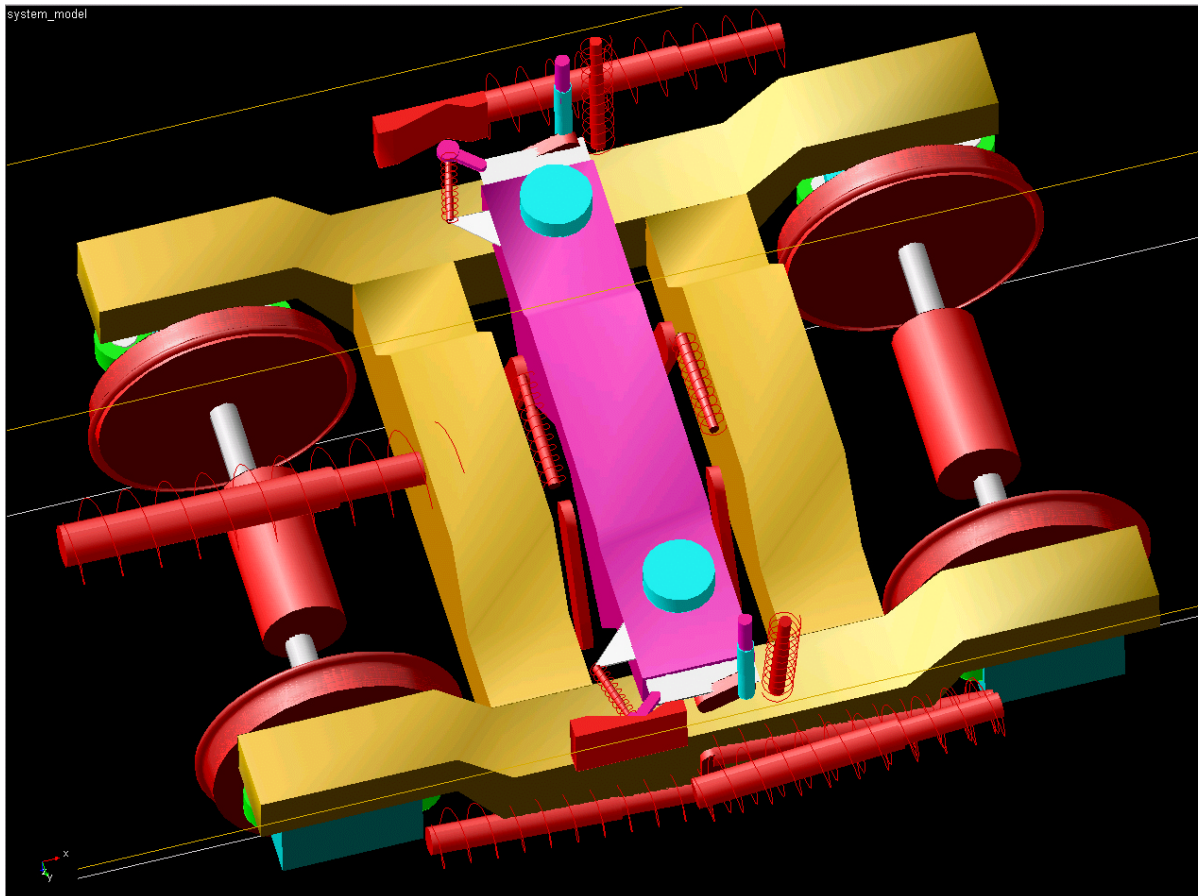
- Vehicle model:
  - ◆ Tilting system
  - ◆ Air spring
  - ◆ Lateral bumpstop
- Analysis scenarios:
  - ◆ Air spring defects
  - ◆ Wedge test
- Future model improvements

# Overview vehicle model



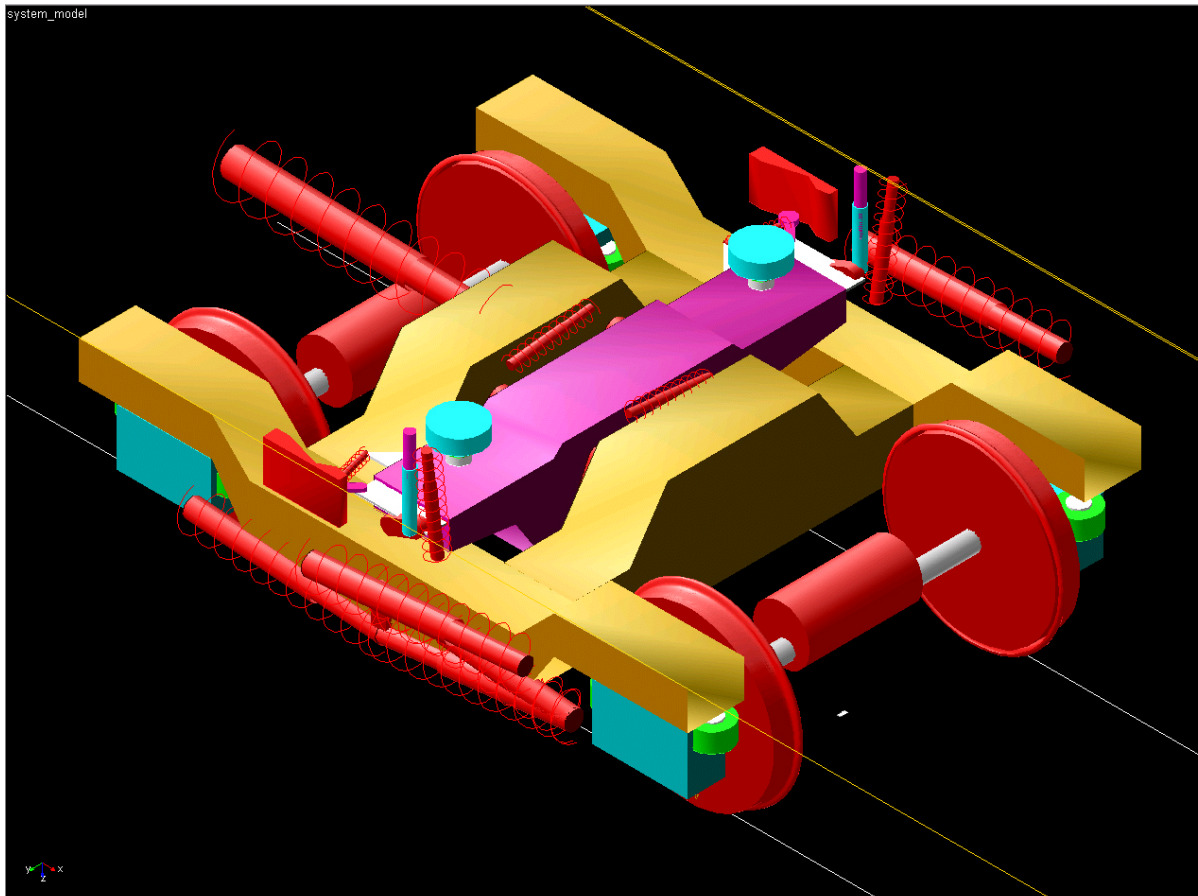
- Active/passive tilting system
- Physical air spring model
- Height control at each air spring
- Traction
- Car body with torsional elasticity
- 61 DOF

# Bogie (1)



- Tilting system:  
bearing of bolster  
beam, control
- Air spring,  
torsion bar
- Lateral bumpstop
- Draw rod

## Bogie (2)



- Primary suspension
- Wheelset linkage
- Traction
- Wheel-rail contact:
  - ◆ Testrig
  - ◆ Level III

## Air spring model (1): Physical description

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- Air spring model based on gas equation:

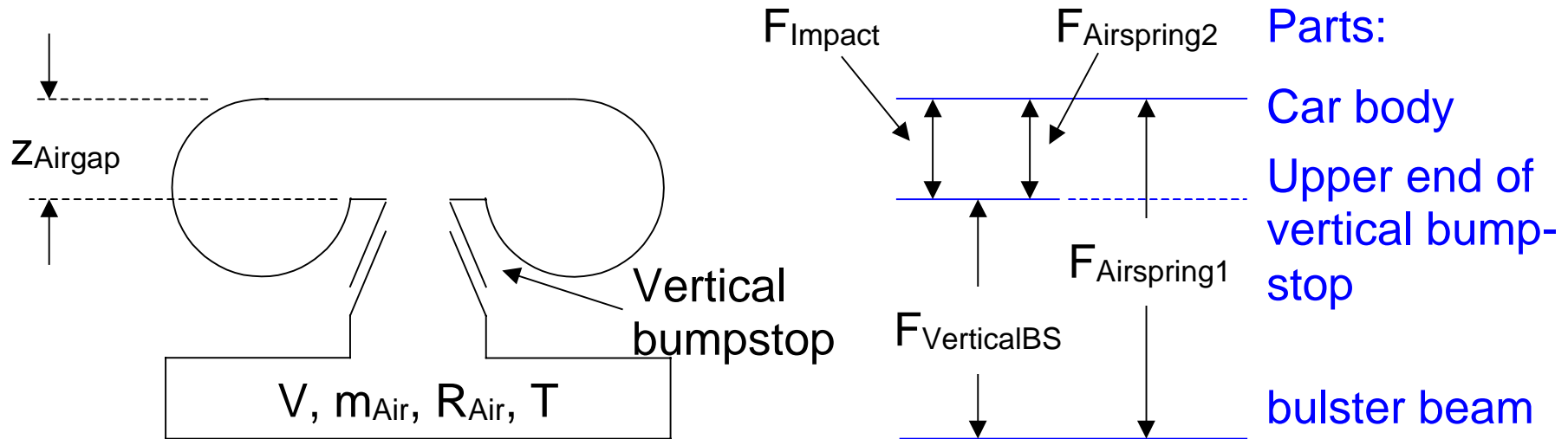
$$\frac{p \cdot V}{T} = R_{Air} \cdot m_{Air}$$

$$V = V_0 + \tilde{A} \cdot z_{Airgap}$$

$$\frac{F_{AirspringX}}{A_X} = [p - p_{atm}]$$

$$F_{AirspringX}(z_{Airgap}, m_{Air}) = A_X \cdot \left[ \frac{T \cdot R_{Air} \cdot m_{Air}}{V_0 + \tilde{A} \cdot z_{Airgap}} - p_{atm} \right]$$

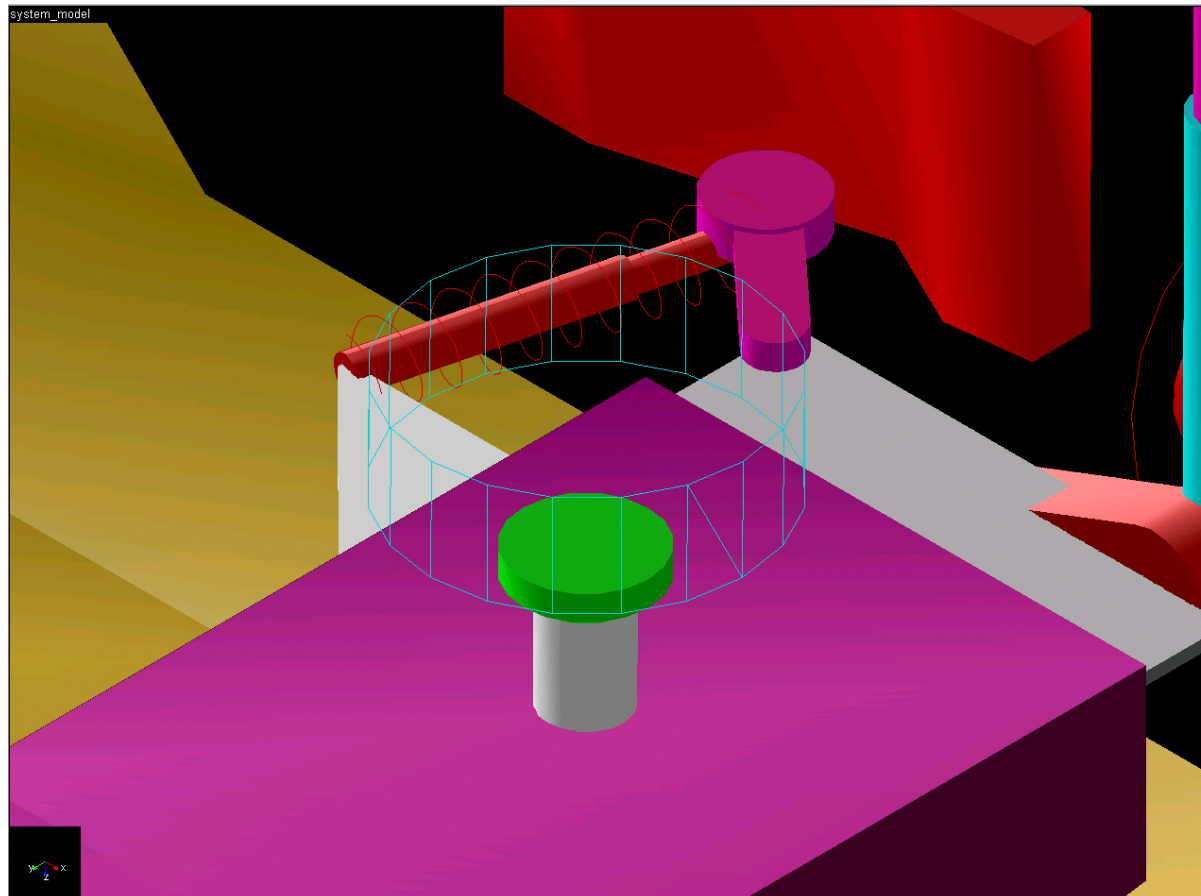
## Air spring model (2): Module air spring/vertical bumpstop



- Impact at zero air gap ( $z_{\text{Airgap}} = 0$ )
- Non-linear measured characteristics of vertical bumpstop
- Linear air spring characteristic in longitudinal and lateral direction

## Air spring model (3): Implementation in ADAMS/Rail

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## Air spring model (4): Change of air mass

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$$m_{Air} = \int [f_{Heightcontrol} + f_{Massequ} + f_{Hole}] \cdot dt + m_{Air0}$$

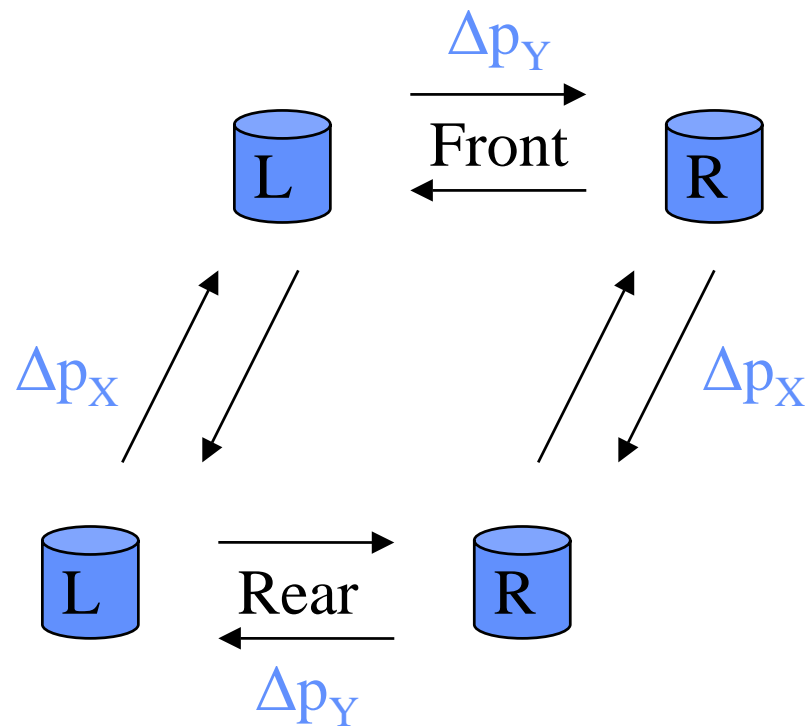
- Height control  $f_{Heightcontrol}(\alpha)$  of the air gap of each spring (Real valve characteristics)
- Mass flow  $f_{Massequ}(\Delta p)$  between air spring bellows for  $\Delta p > \Delta p_0$
- Alternatively pressure equalisation between two bellows
- Holes/leaking bellows as error scenario ( $f_{Hole} < 0$ )
- Air masses are implemented as differential equations (DIFF-statements)



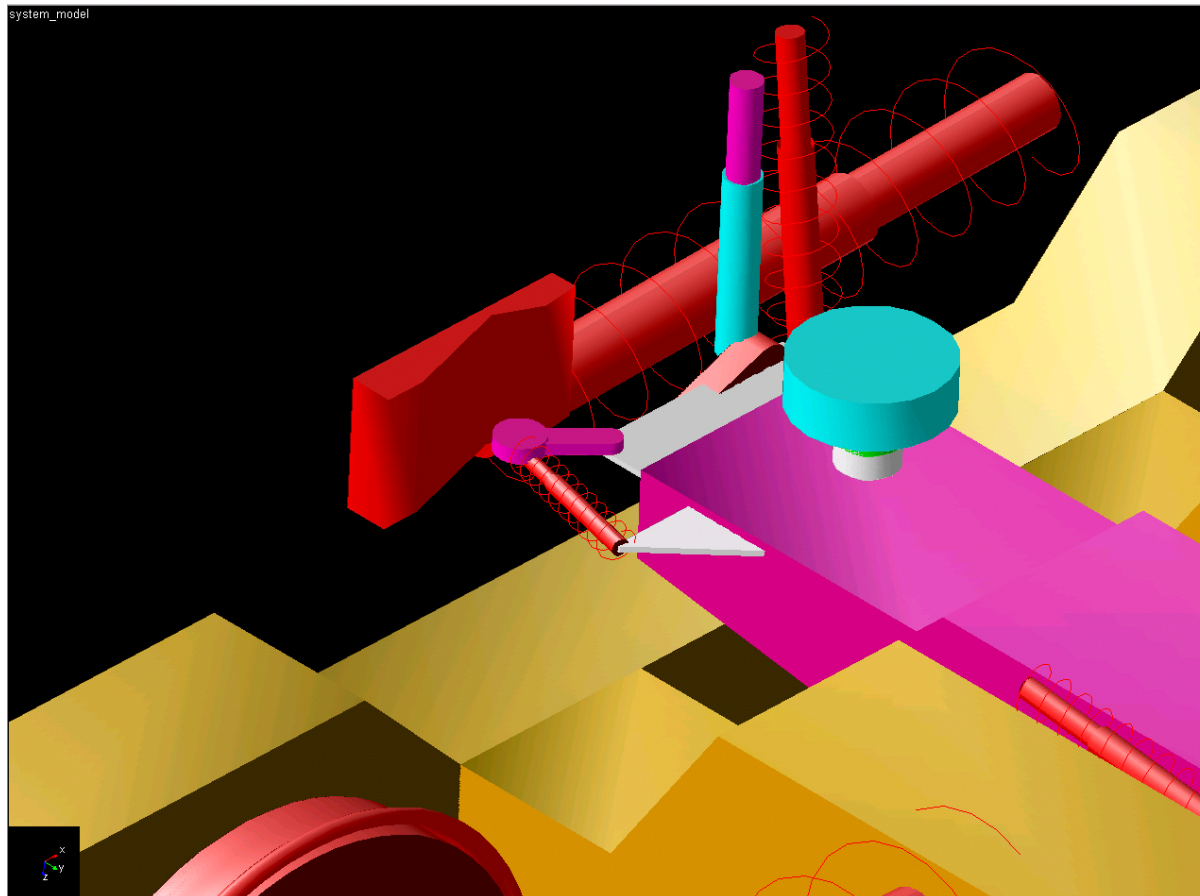
Air spring model (5):

Mass flow between bellows for  $\Delta p > \Delta p_0$

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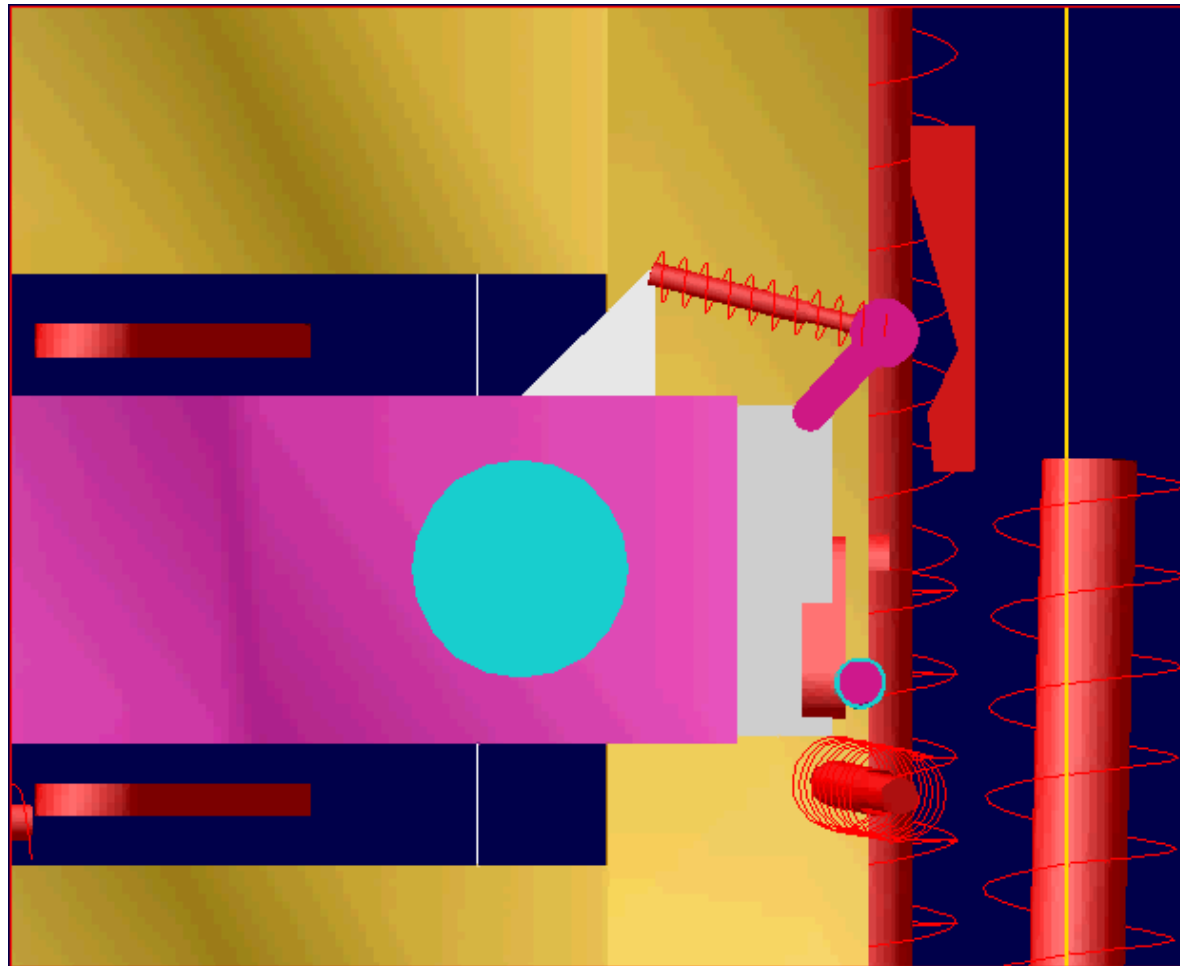
## Lateral bumpstop car body bogie (1)



- Bearing of guide roller
- Form and position of contour plate
- Contact force at impact

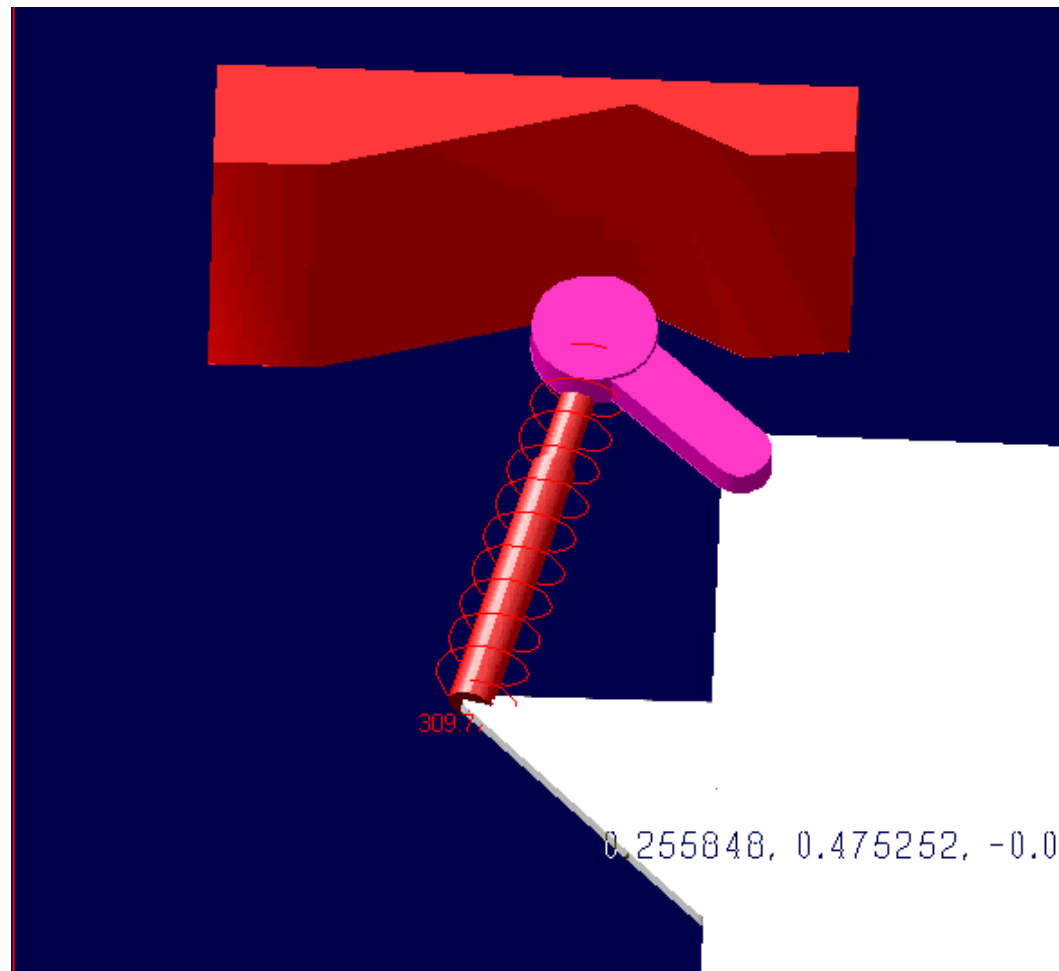
## Lateral bumpstop car body bogie (2): Lateral force on the car body

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## Lateral bumpstop car body bogie (3): Lateral impact

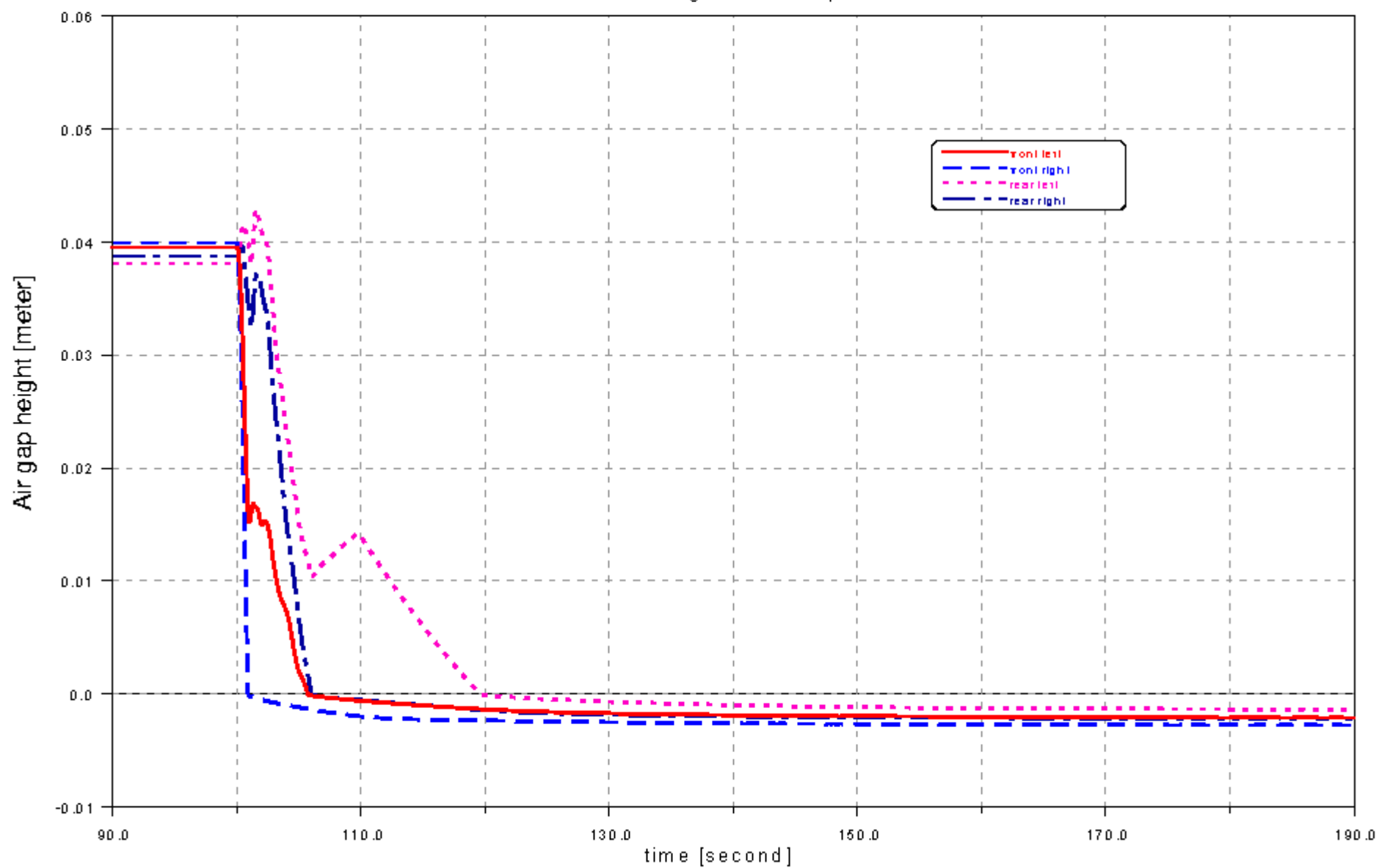
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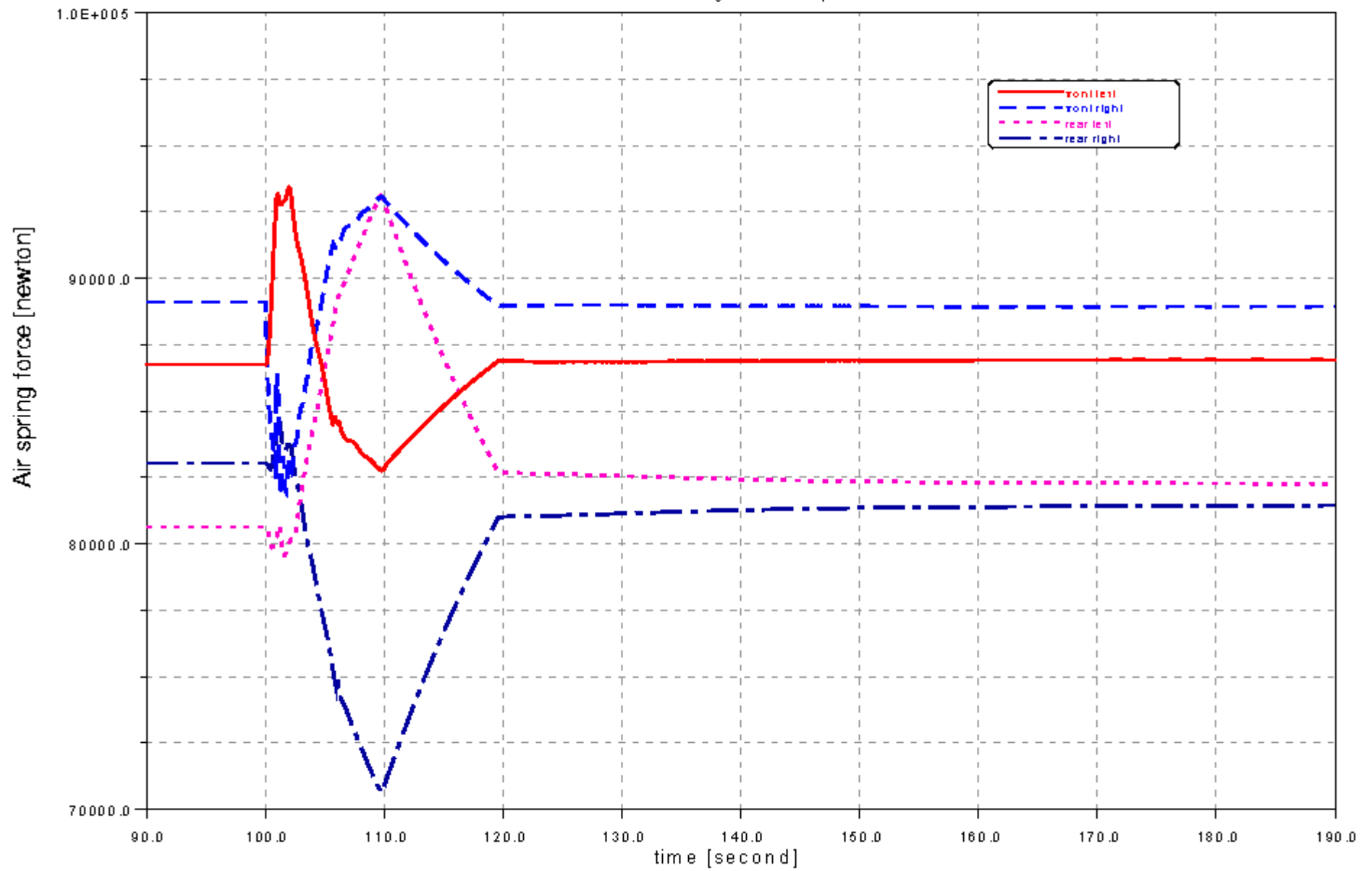
## Simulation scenarios

- Adjustment of the air spring height control
- Error scenarios:
  - ◆ Defects of the air spring height control
  - ◆ Hole/leak in air spring bellows
- Wedge test
- Kinematics of the bogie
- Vehicle examination procedure
- etc.

Air gap height  
Hole front right A = 100 qmm

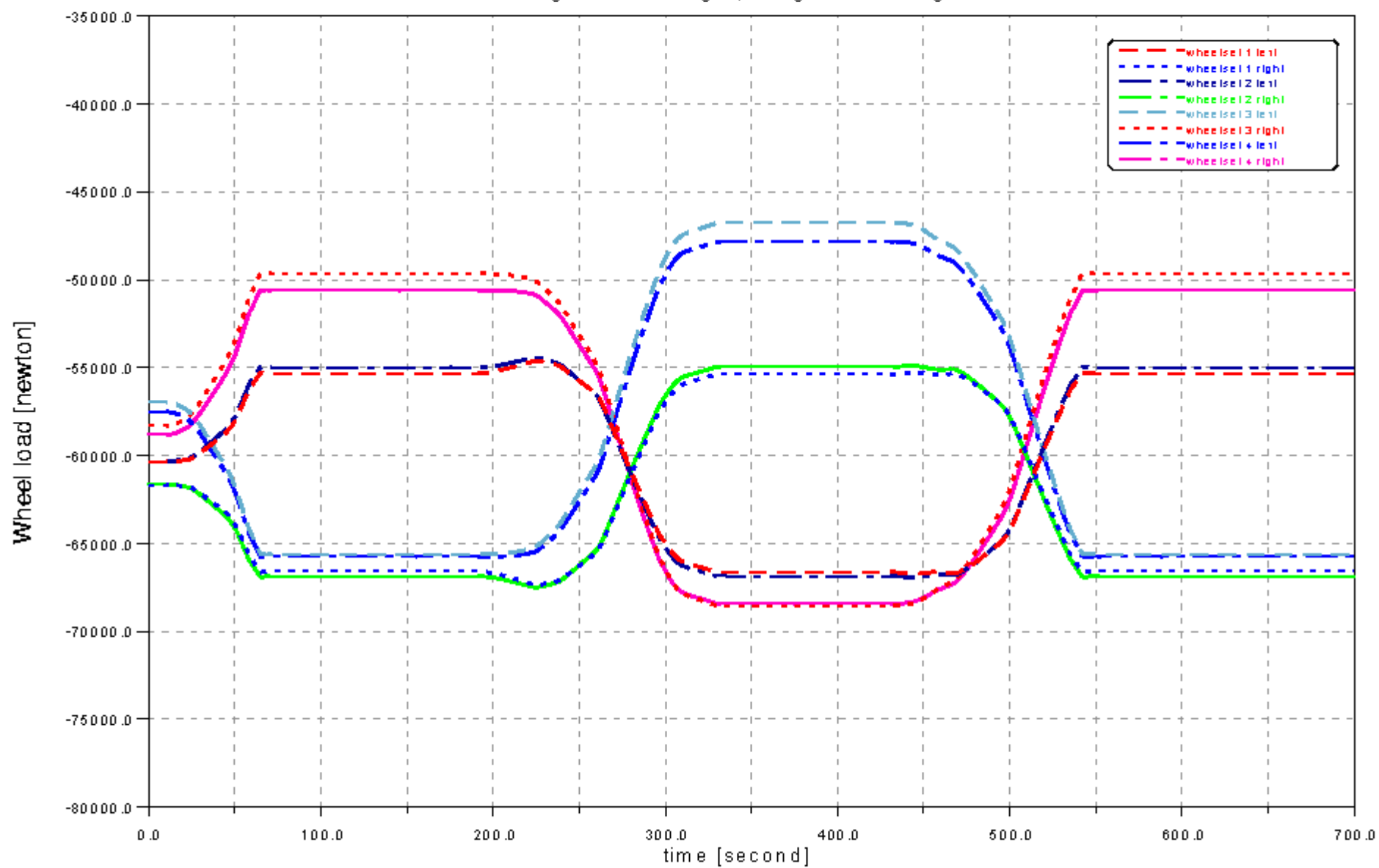


Air spring force  
Hole front right A = 100 qmm

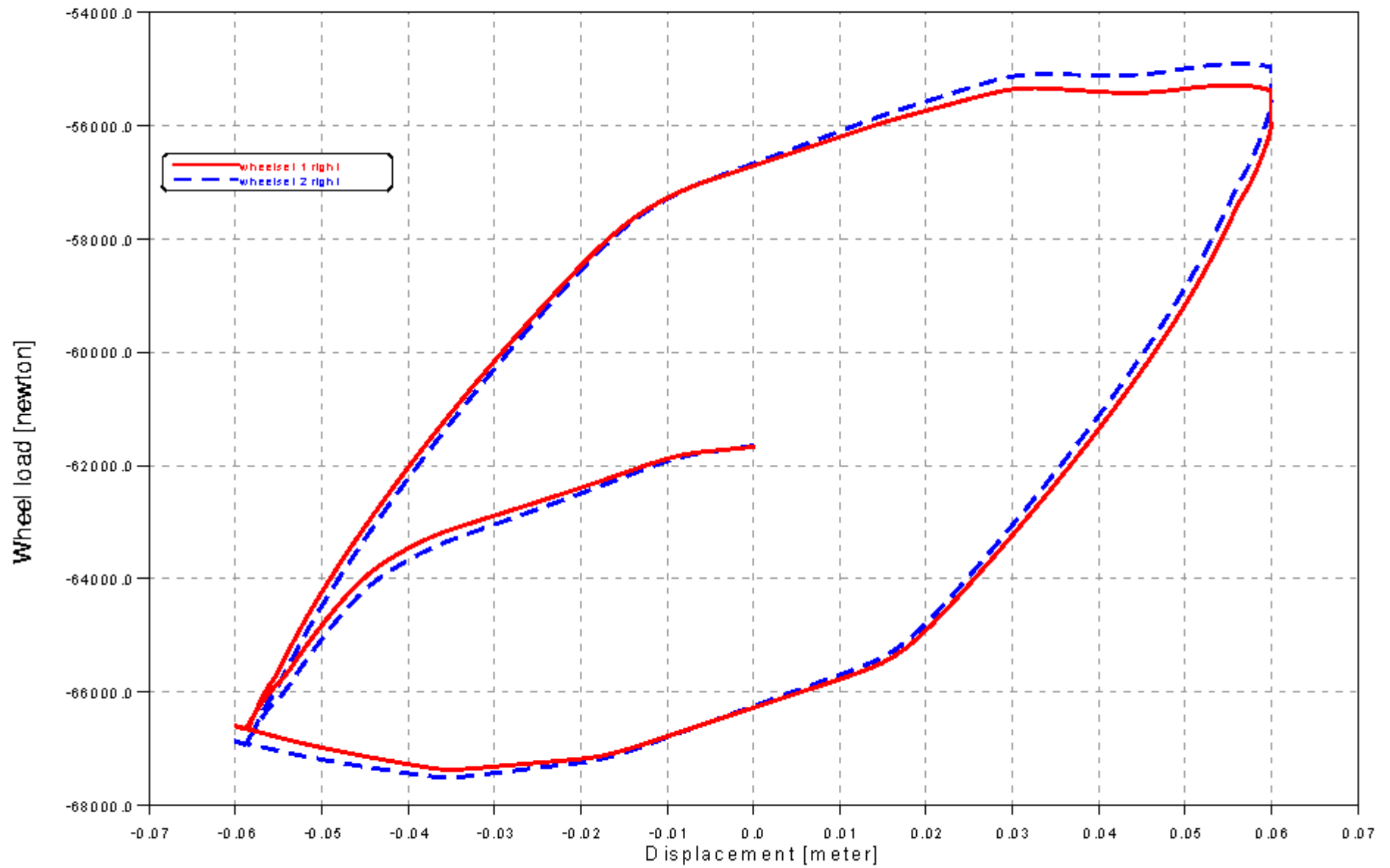




Wheel load  
Wedge test front right, tilting active 0 degree



Force-displacement-diagram  
Wedge test front right, tilting active 0 degree



## Future model improvements

- Test of “classical” vehicle dynamics calculation:
  - ◆ Vehicle model
  - ◆ Simulation environment
- Dynamical air spring model (stiffening at higher frequencies)
- Powertrain

# Summary

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- Development of a VT611/612 vehicle model with *detailed* description of:
  - ◆ Tilting system
  - ◆ Secondary suspension
  - ◆ Air spring model (based on the gas equation)
  - ◆ Bogie kinematics
- Analysis of:
  - ◆ Adjustment and error scenarios of air spring system
  - ◆ Bogie kinematics
  - ◆ Vehicle examination procedure
- Future improvements/analyses:
  - ◆ Implementation of the complete powertrain
  - ◆ “Classical” vehicle dynamics