

**EVALUATING MODAL CONTRIBUTORS IN A NASTRAN
FREQUENCY RESPONSE ANALYSIS**

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ABSTRACT

A special purpose (alter) program has been added to the MSC/NASTRAN modal frequency response rigid format (Solution 30), via the direct matrix abstraction program (DMAP) capability.

The DMAP program allows an in-depth analysis of the frequency response on a per-mode basis.

An example of how the program was applied to the modal frequency response analysis of Hughes Advanced Attack Helicopter is presented along with some unexpected results.

INTRODUCTION

The topic "Evaluating Modal Contributors in a NASTRAN Frequency Response Analysis" covers the follow-on work from that which was presented in the paper of Reference 1 at last year's conference. By way of introduction, a modal analysis was performed on Hughes' Advanced Attack Helicopter (AAH) (see Figures 1 and 2). At this time, the AAH is in the production phase of a contract with the U.S. Army where it is designated the AH-64A Apache. The AAH is a relatively large helicopter - 50 feet long, 12 feet high, and having a 12-foot wing span. It can carry up to a maximum of four pylons which contain a variety of missiles and rockets. In addition, it has a 30mm chain gun under its nose. Its weight is approximately 15,000 pounds.

The analysis was performed on the NASTRAN dynamic model shown in Figure 3. This relatively large model had 1632 grid points, 4357 structural elements, and 9792 dynamic degrees of freedom (DOF). The detail of this model, which is the same size as the structural model after a compatible mass representation was added, was maintained by solving for the modes and frequencies using Generalized Dynamic Reduction (GDR).

Modes and frequencies were then calculated up to 25 Hz using GDR. A partial NASTRAN frequency summary table is shown in Table 1. Fifty modes are shown up to 12.82 Hz. A total of 87 modes were calculated up to 25 Hz and all were used during the frequency response analyses.

Models containing this detail give rise to the term "high modal density," i. e., many modes within a given frequency range. This detail in the mode shapes allows a more thorough analysis of the modes. Figures 4 through 6 are but a few examples of typical mode shapes that illustrate the detail provided by large DOF dynamic models.

Table 2 is a summary of the major structural modes which were identified from the analysis along with a few major test modes that correlated with the analytical modes. The identification of the major structural modes from models with high modal density using the kinetic energy approach was the topic of last year's paper. This paper, which uses updated modal data for frequency response analysis in solution 30 of MSC/NASTRAN, presents a special direct matrix abstraction program (DMAP) which permits identification of primary contributing modes to a particular response and enhanced the understanding of the vibration characteristics.

In the helicopter industry, the comfort of the pilot is very important. Our goal is to give him the same smooth ride enjoyed by the airline pilot, but unfortunately the technology will not yet allow it.

It is common, in an attempt to give the pilot as smooth a ride as possible, to add vibration control devices; therefore, the response work presented here was performed to evaluate the vibration response at the pilot's seat in the vertical (Z) direction in the event that such a control device was deemed necessary.

In addition, helicopters generally have certain discrete forcing functions which cause the maximum structural response. In the case of the AAH, a major structural input force from the rotor occurs at the 4/rev or 18.85 Hz circular frequency, where 4/rev is defined as 4 times the main rotor speed.

Initial analyses calculated response at the pilot's seat for 6 independent orthogonal 4/rev forcing functions at the main rotor hub. These results did not compare favorably with the results of a previously run modal test performed on the AAH. The responses were too low. However, during the modal test the helicopter was suspended from the main rotor hub and the shaker inputs (forcing functions) were applied at the aircraft's nose and tail - not at the main rotor hub. When the analysis was repeated for these

conditions, i. e., the forcing was applied at the nose and tail, a much better correlation to the test results was achieved. In order to gain more insight into the response, a DMAP was written to obtain the frequency response on a per-mode basis. The DMAP was written for solution 30, Version 61B of MSC/NASTRAN. Figure 7 shows the standard frequency response equations which are solved in solution 30. Equation (1) is the standard modal summation equation for calculating physical, or discrete, displacements.

Equation (2) is an important variation of Equation (1). Using a special element by element

$$\begin{pmatrix} E \\ X \\ E \end{pmatrix}$$

multiply, Equation (2) solves for the frequency response on a per-mode basis by multiplying but not summing as in the standard matrix multiply of Equation (1). The summation of the individual X_i 's in Equation (2) is then equal to the total X in Equation (1).

The DMAP solves for the response on the per-mode basis as shown in Equation (2) and contains a check that solves Equation (3) and allows the user to compare with the results of Equation (1) which is standard NASTRAN frequency response output.

DMAP PROGRAM

The DMAP written for Version 61B is shown in Figures 8 and 9. The program is automated, but requires certain user inputs that are outlined in the bulk data of Figure 9.

Execution of the program does not require an understanding of the DMAP (although it would increase the user's flexibility to further modify the program). Therefore the detailed steps will not be explained. However, a few features will be mentioned (see Note on Figure 8). Comment cards have been inserted to document major sections. The first output from the DMAP is the frequency summary table from solution 3. Upon restarting into solution 30 from solution 3, this table is not reprinted. The authors feel this information is important, and is printed by the "OFP LAMA//\$" statement.

Next the modal matrix is normalized (ZPSN) in order to quickly isolate the larger displacement values. Note "ZPSN" is a transposed single row matrix which represents the degree of freedom and all 87 modes of the pilot's seat in the "Z" direction.

Next, the modal displacement (TETAM) and physical displacement (TOTM) on a per-mode basis are calculated. This is followed by the acceleration (TOTMA) on a per-mode basis. Additional matrix outputs ending in letter "N" have normalized the preceding matrix to a maximum value of unity to assist the analyst in determining the largest contributors.

Figure 9 notes the required user input in the case control deck. Set 1 selects all six DOF of the grid point corresponding to the pilot's seat, i.e., 10013. The user must input his desired grid point at which the response will be determined.

Figure 9 also notes the user input required in the bulk data section. Matrix C6, see DM1 card 2, selects the user's desired response direction, which in this example is 3. The "PARAM, NCASE, 2," selects the number of subcases to be run. And finally, the frequency of the forcing function is input as $-\omega^2$ in complex form, where ω^2 is in $(\text{rad/sec})^2$.

APPLICATION

The 4/rev forcing function at 18.85 Hz is very close to some of the major structural modes as shown in Figure 10. Any shift in the frequency of these modes toward 18.85 Hz could greatly affect the response.

The forcing function (a 1000 pound vertical oscillating load) was then applied at the main rotor hub and aircraft tail, and the response at the pilot seat in the vertical direction was calculated for these independently applied loads.

Table 3 is the complex modal acceleration for all 87 modes, i.e., " \ddot{q} ". This is normal NASTRAN output in the complex form of Real and Imaginary parts. In reviewing Table 3, large values such as those for modes 73 through 75 are of interest. If one can match up large values of " \ddot{q} " with large values of " ϕ ", the resulting response (\ddot{X}_i) for that particular mode will be large.

The next output of interest is shown in Table 4. This again is normal solution 30 NASTRAN output. Here we have the total modal acceleration response, all 6 DOF, for selected grid points on the aircraft. Again our interest is the pilot's seat at point ID 10013. The third column represents the response in the "Z" direction. Later in the program, the individual modal responses are added, the sum of which should be equal to column 3 of Table 4. If this is the case, the calculation is verified.

Table 5 is the first calculated matrix output from the DMAP. This is the transposed row of the modal matrix which corresponds with the vertical response of the pilot's seat. This column has been normalized to "unity" such that the largest values may be easily established. Again a large modal value which matches with a large acceleration "q" will produce a large acceleration for that particular mode.

And finally, Table 6 is the output data of the response on a per-mode basis. Case 1 represents the 4/rev forcing function applied at the main rotor hub and Case 2 applied at the tail.

In order to gain a better understanding of the two cases, attention is turned to Equation (4). Equation (4) is similar to

$$\left\{ \begin{array}{c} \ddot{X}_{i_1} \\ \vdots \\ \ddot{X}_{i_2} \end{array} \right\}_{87 \times 2} = \left\{ \begin{array}{c} \text{CASE 1} \\ \phi_{PS}^T \\ \vdots \\ \text{CASE 2} \\ \phi_{PS}^T \end{array} \right\}_{87 \times 2} \begin{array}{c} E \\ \times \\ E \end{array} \left\{ \begin{array}{c} \text{CASE 1} \\ \ddot{q}_{i_1} \\ \vdots \\ \text{CASE 2} \\ \ddot{q}_{i_2} \end{array} \right\}_{87 \times 2} \quad (4)$$

Equation (2) except two cases have been formulated. The values of columns 1 and 2 of the "phi" (ϕ^T) matrix are identical. However, the columns of the "q" matrix are different, since the forcing function was applied at a different location for each case. " \ddot{X}_{i_1} " and " \ddot{X}_{i_2} " are the responses per mode for the two cases.

Table 7 summarizes the check matrix, i.e., the summation of the response per-mode matrix. This summation is a check on the method presented and should be equal to the normal frequency response output shown in Column 3 of Table 4. This check is a part of the DMAP.

The results of the root of the sum of the squares (RSS) magnitudes in g's for cases 1 and 2 are summarized in Table 8 from the results of Table 6. Column 1 is the number of the largest contributors on a per-mode basis. Column 2 is RSS response at the pilot's seat due to a force at the hub. Column 3 is mode number at which the response occurs, and column 4 is the corresponding frequency at which it occurs. Columns 5 through 7 are identical to 2 through 4 for a force applied at the tail.

Note, the largest contributor when the force was applied at the tail was the 75 mode at 18.97 Hz, but when the force was applied at the hub, this was only the third largest contributor.

The results of Table 8 were plotted as shown in Figure 11. As expected, the two largest responses when the forcing function was applied at the tail are very close to the forcing function. However, when the forcing function was applied at the main rotor hub, the largest response occurred at 14.56 Hz, the 60th mode. The 18.97 Hz mode was but the third largest contributor. What these unexpected results indicate is that if we wanted to add a vibration control device, we should work on the mode at 14.56 Hz - not 18.97 Hz, which is the mode closest to the forcing function.

Without these data, we could have spent a lot of time, money, and energy working on the more logical 18.97 Hz mode with little effect.

CONCLUSIONS

The identification of modal contribution to local response is very valuable in identifying the primary contributing modes of the total response. It provides the analyst with a far better understanding of the vibration characteristics of the system and points to areas where structural improvements may be beneficial. The application as presented to the AAH provides a good example. If a vibration control device had been designed to isolate the modes close to the frequency of the forcing function, little if any benefit would have been realized. The mode at 14.56 Hz was the one to isolate.

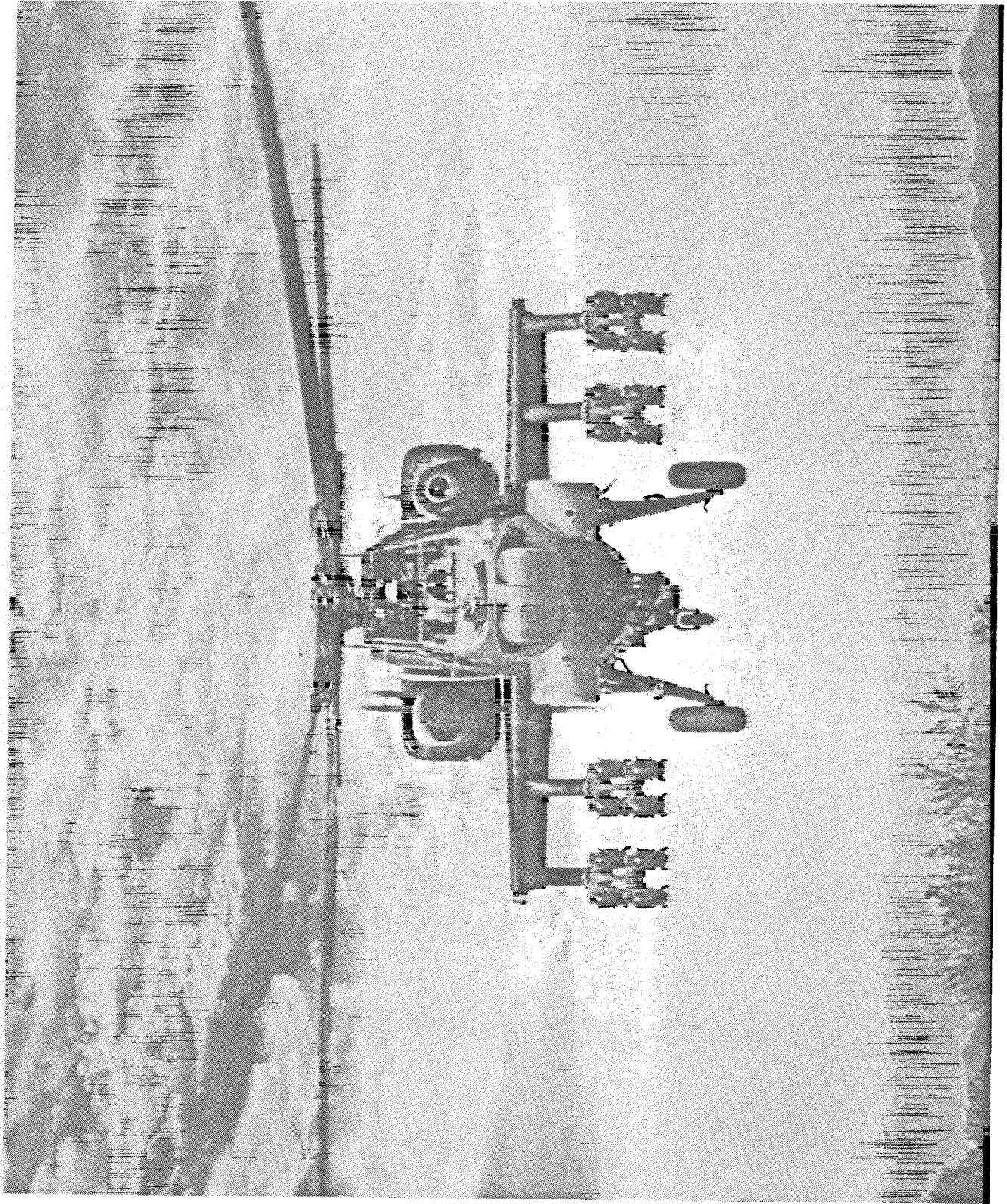
Although the DMAP presented was written for a specific application in the helicopter industry, the authors believe that it perhaps can be applied to the constant speed rotary machinery field as well.

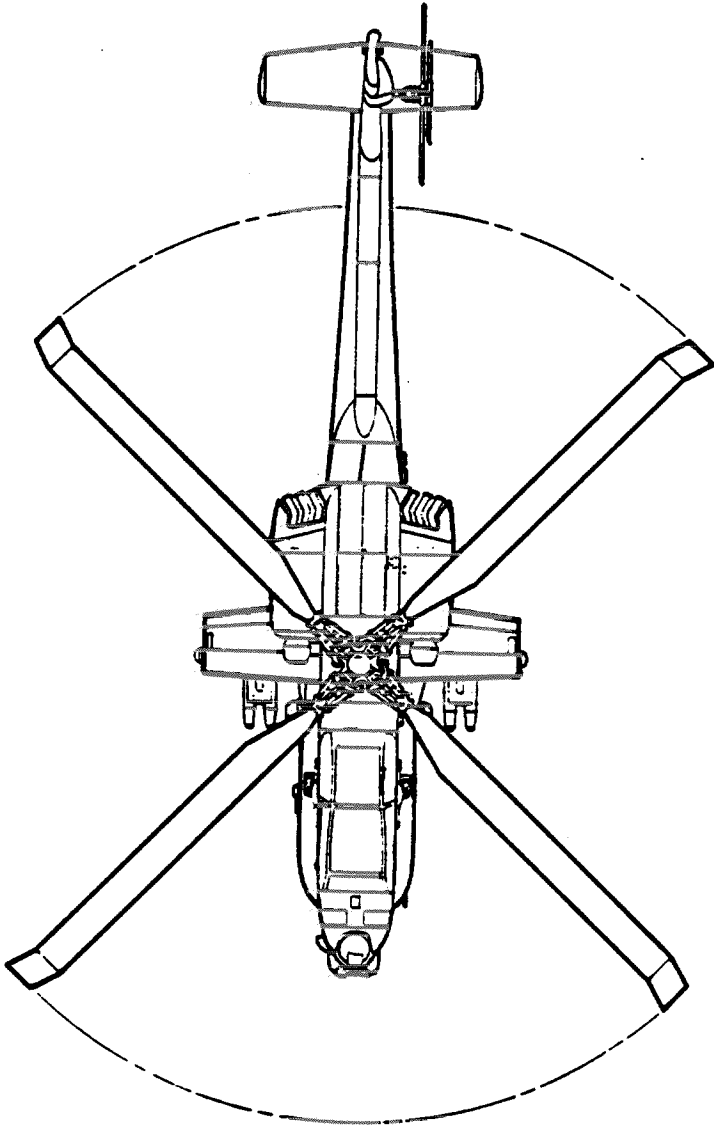
ACKNOWLEDGMENT

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REFERENCE

1. Parker, G. R. and J. J. Brown, "Kinetic Energy DMAP for Mode Identification," MSC/NASTRAN User's Conference Proceedings, Paper 8, March 1982.





SCALE IN FEET
0 1 2 4 6 8 10

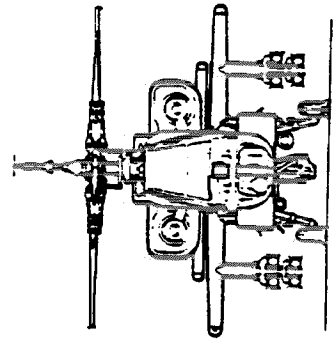
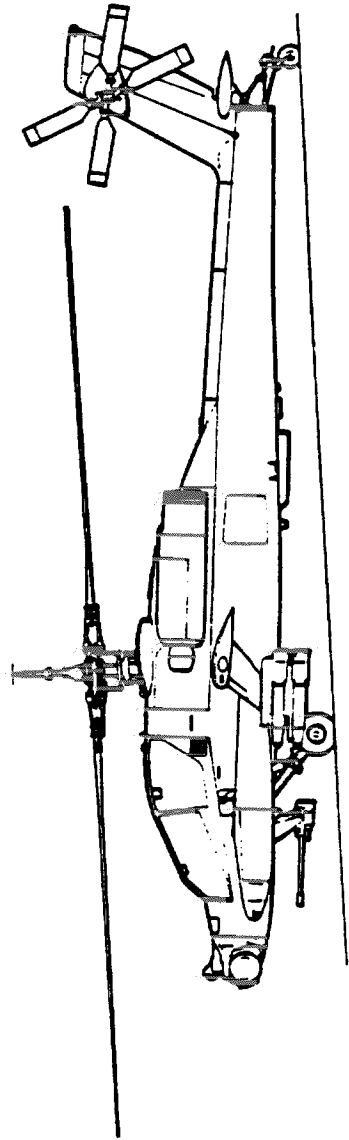
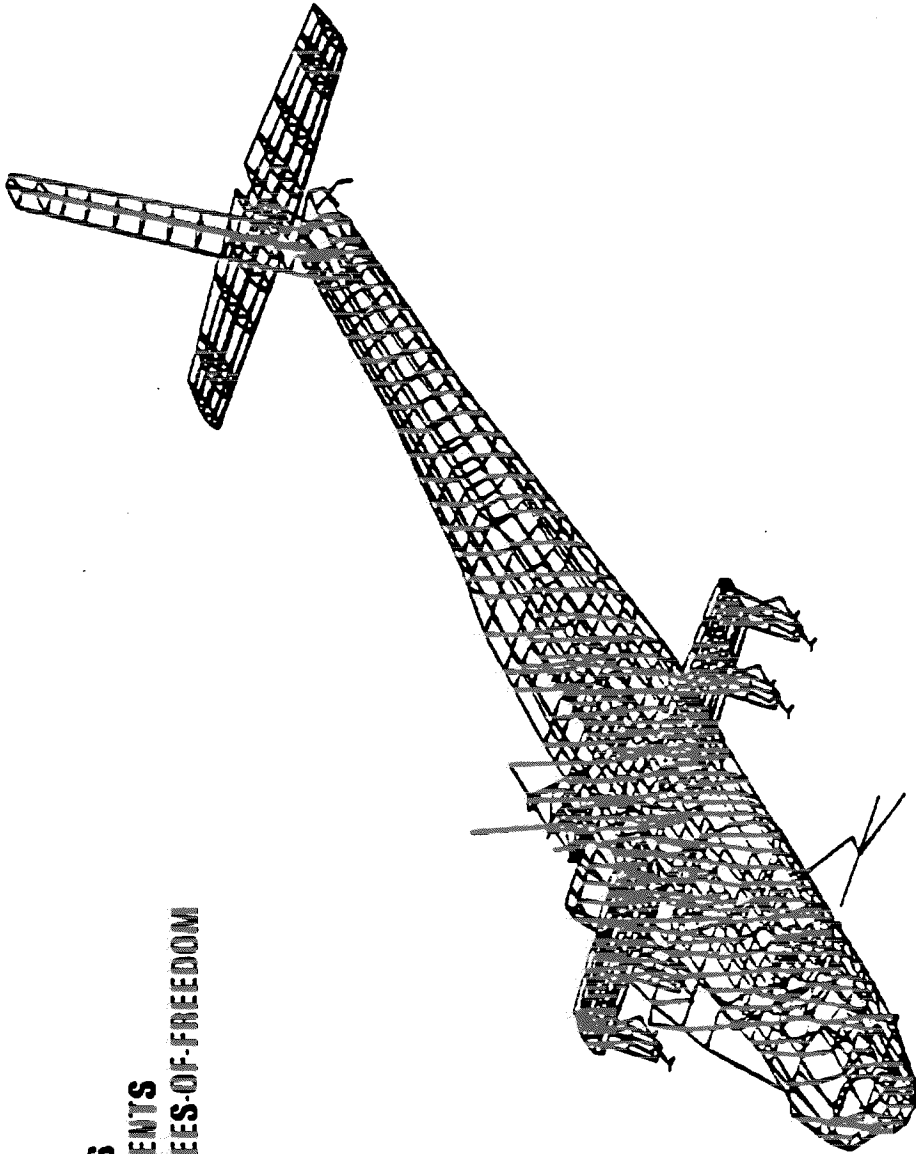


Figure 2. Hughes Advanced Helicopter

820229-3

1632 GRIDS
4357 ELEMENTS
9792 DEGREES-OF-FREEDOM



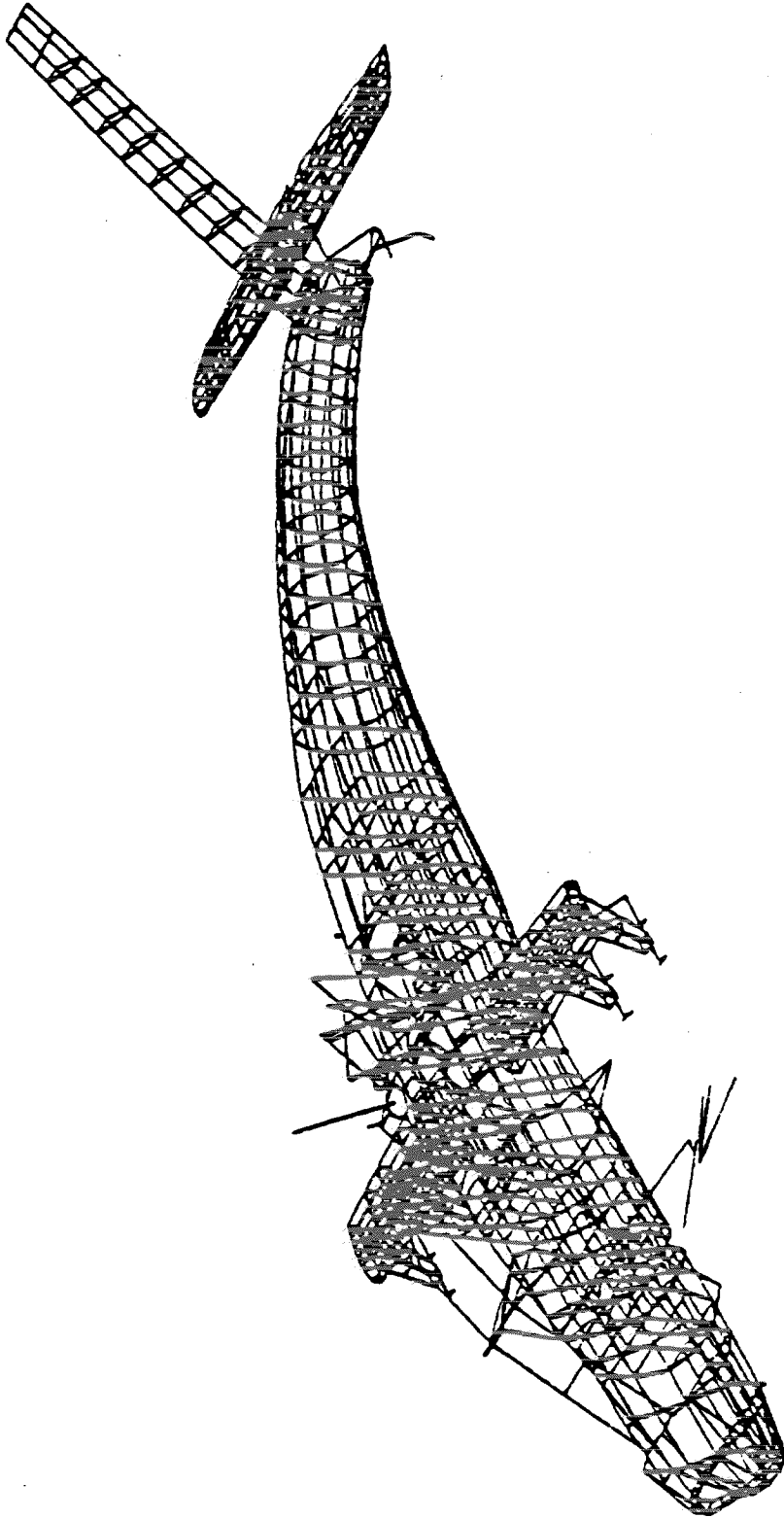
620006 8

Figure 3. AAH Dynamic NASTRAN Model

TABLE 1. DYNAMIC NASTRAN

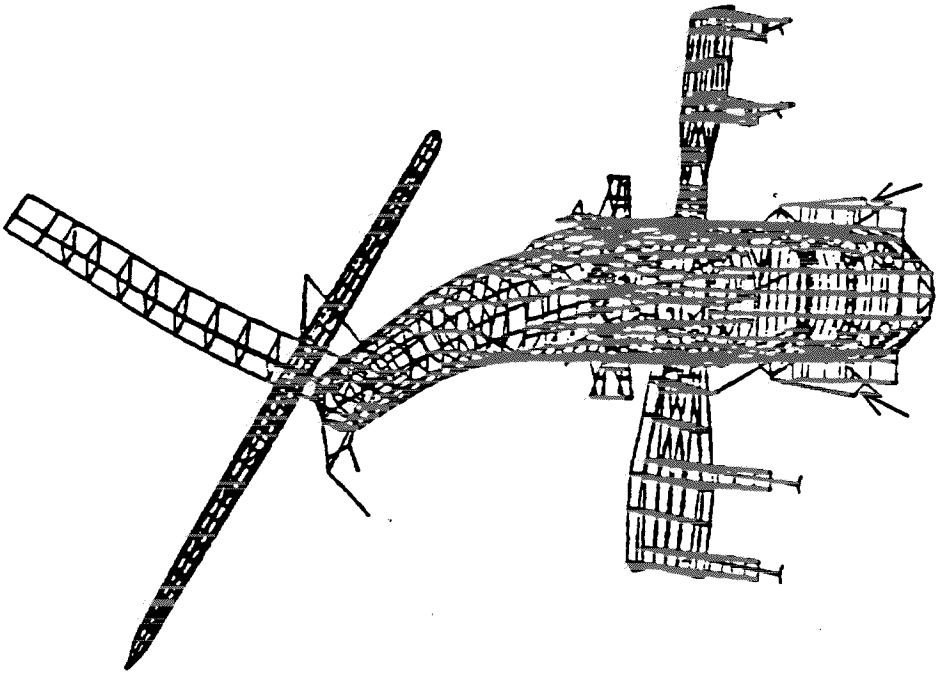
● NASTRAN CAN IDENTIFY MANY MODES IN SMALL FREQUENCY RANGE

MODE NO.	EXTRACTION ORDER	EIGENVALUE	R E A L R A D I A N S	I M A G I N A R Y R A D I A N S	GENERALIZED MASS	GENERALIZED STIFFNESS
1	154	1.501159E-06	1.226034E-03	1.951294E-04	1.000000E+00	1.501159E-06
2	153	2.077224E-06	1.696413E-03	2.699294E-04	1.000000E+00	2.077224E-06
3	152	-4.397833E-05	2.097101E-03	1.897640E-04	1.000000E+00	-4.397833E-05
4	151	-1.043335E-05	4.043394E-03	6.436144E-04	1.000000E+00	-1.043335E-05
5	149	-1.042269E-04	1.020914E-02	1.628134E-03	1.000000E+00	-1.042269E-04
6	148	-1.124452E-02	1.064022E-02	1.627602E-03	1.000000E+00	-1.124452E-02
7	147	2.516975E-02	1.506430E+01	2.529990E+00	1.000000E+00	2.516975E-02
8	146	3.394329E+02	1.642370E+01	3.932224E+00	1.000000E+00	3.394329E+02
9	145	3.671488E+02	1.916113E+01	3.049580E+00	1.000000E+00	3.671488E+02
10	144	7.442222E+02	1.933499E+01	3.074647E+00	1.000000E+00	7.442222E+02
11	143	4.154079E+02	2.038154E+01	3.243821E+00	1.000000E+00	4.154079E+02
12	142	4.159104E+02	2.038154E+01	3.243821E+00	1.000000E+00	4.159104E+02
13	141	6.591513E+02	2.567394E+01	3.243821E+00	1.000000E+00	6.591513E+02
14	140	7.393546E+02	2.956274E+01	4.086135E+00	1.000000E+00	7.393546E+02
15	138	8.995762E+02	2.999294E+01	4.723524E+00	1.000000E+00	8.995762E+02
16	141	1.046563E+03	3.219570E+01	4.723524E+00	1.000000E+00	1.046563E+03
17	143	1.054047E+03	3.247147E+01	5.124105E+00	1.000000E+00	1.054047E+03
18	144	1.025294E+03	3.505440E+01	5.124105E+00	1.000000E+00	1.025294E+03
19	145	1.025294E+03	3.505440E+01	5.124105E+00	1.000000E+00	1.025294E+03
20	146	1.125348E+03	3.949097E+01	5.266682E+00	1.000000E+00	1.125348E+03
21	147	1.127778E+03	3.949097E+01	5.266682E+00	1.000000E+00	1.127778E+03
22	148	1.455454E+03	3.409657E+01	5.933065E+00	1.000000E+00	1.455454E+03
23	149	1.455454E+03	3.409657E+01	5.933065E+00	1.000000E+00	1.455454E+03
24	151	1.675495E+03	3.802032E+01	6.511222E+00	1.000000E+00	1.675495E+03
25	150	1.675495E+03	3.802032E+01	6.511222E+00	1.000000E+00	1.675495E+03
26	148	1.822649E+03	4.259666E+01	6.791515E+00	1.000000E+00	1.822649E+03
27	149	1.962234E+03	4.292632E+01	6.791515E+00	1.000000E+00	1.962234E+03
28	151	1.973064E+03	4.429734E+01	7.050193E+00	1.000000E+00	1.973064E+03
29	150	2.293396E+03	4.561092E+01	7.050193E+00	1.000000E+00	2.293396E+03
30	152	2.352103E+03	4.774302E+01	7.594537E+00	1.000000E+00	2.352103E+03
31	151	2.402795E+03	4.869931E+01	7.594537E+00	1.000000E+00	2.402795E+03
32	153	2.502292E+03	4.909935E+01	7.789058E+00	1.000000E+00	2.502292E+03
33	152	2.502292E+03	4.909935E+01	7.789058E+00	1.000000E+00	2.502292E+03
34	154	3.062738E+03	4.972719E+01	7.944632E+00	1.000000E+00	3.062738E+03
35	153	3.062738E+03	4.972719E+01	7.944632E+00	1.000000E+00	3.062738E+03
36	155	3.201632E+03	5.038005E+01	8.083593E+00	1.000000E+00	3.201632E+03
37	154	3.201632E+03	5.038005E+01	8.083593E+00	1.000000E+00	3.201632E+03
38	156	3.705135E+03	5.412748E+01	8.905455E+00	1.000000E+00	3.705135E+03
39	155	3.705135E+03	5.412748E+01	8.905455E+00	1.000000E+00	3.705135E+03
40	157	4.000422E+03	6.148605E+01	9.765800E+00	1.000000E+00	4.000422E+03
41	156	4.000422E+03	6.148605E+01	9.765800E+00	1.000000E+00	4.000422E+03
42	158	4.098191E+03	6.324292E+01	9.765800E+00	1.000000E+00	4.098191E+03
43	157	4.098191E+03	6.324292E+01	9.765800E+00	1.000000E+00	4.098191E+03
44	159	4.512302E+03	6.395460E+01	1.007869E+01	1.000000E+00	4.512302E+03
45	158	4.512302E+03	6.395460E+01	1.007869E+01	1.000000E+00	4.512302E+03
46	160	4.607151E+03	6.717370E+01	1.076645E+01	1.000000E+00	4.607151E+03
47	159	4.607151E+03	6.717370E+01	1.076645E+01	1.000000E+00	4.607151E+03
48	161	4.762547E+03	6.841274E+01	1.089413E+01	1.000000E+00	4.762547E+03
49	160	4.762547E+03	6.841274E+01	1.089413E+01	1.000000E+00	4.762547E+03
50	162	5.001460E+03	6.980372E+01	1.088347E+01	1.000000E+00	5.001460E+03
51	161	5.001460E+03	6.980372E+01	1.088347E+01	1.000000E+00	5.001460E+03
52	163	5.261135E+03	7.128426E+01	1.109461E+01	1.000000E+00	5.261135E+03
53	162	5.261135E+03	7.128426E+01	1.109461E+01	1.000000E+00	5.261135E+03
54	164	5.532776E+03	7.263708E+01	1.134524E+01	1.000000E+00	5.532776E+03
55	163	5.532776E+03	7.263708E+01	1.134524E+01	1.000000E+00	5.532776E+03
56	165	5.825801E+03	7.510027E+01	1.156055E+01	1.000000E+00	5.825801E+03
57	164	5.825801E+03	7.510027E+01	1.156055E+01	1.000000E+00	5.825801E+03
58	166	6.092215E+03	7.662746E+01	1.174700E+01	1.000000E+00	6.092215E+03
59	165	6.092215E+03	7.662746E+01	1.174700E+01	1.000000E+00	6.092215E+03
60	167	6.304311E+03	7.805244E+01	1.192246E+01	1.000000E+00	6.304311E+03
61	166	6.304311E+03	7.805244E+01	1.192246E+01	1.000000E+00	6.304311E+03
62	168	6.497400E+03	8.066651E+01	1.212820E+01	1.000000E+00	6.497400E+03
63	167	6.497400E+03	8.066651E+01	1.212820E+01	1.000000E+00	6.497400E+03



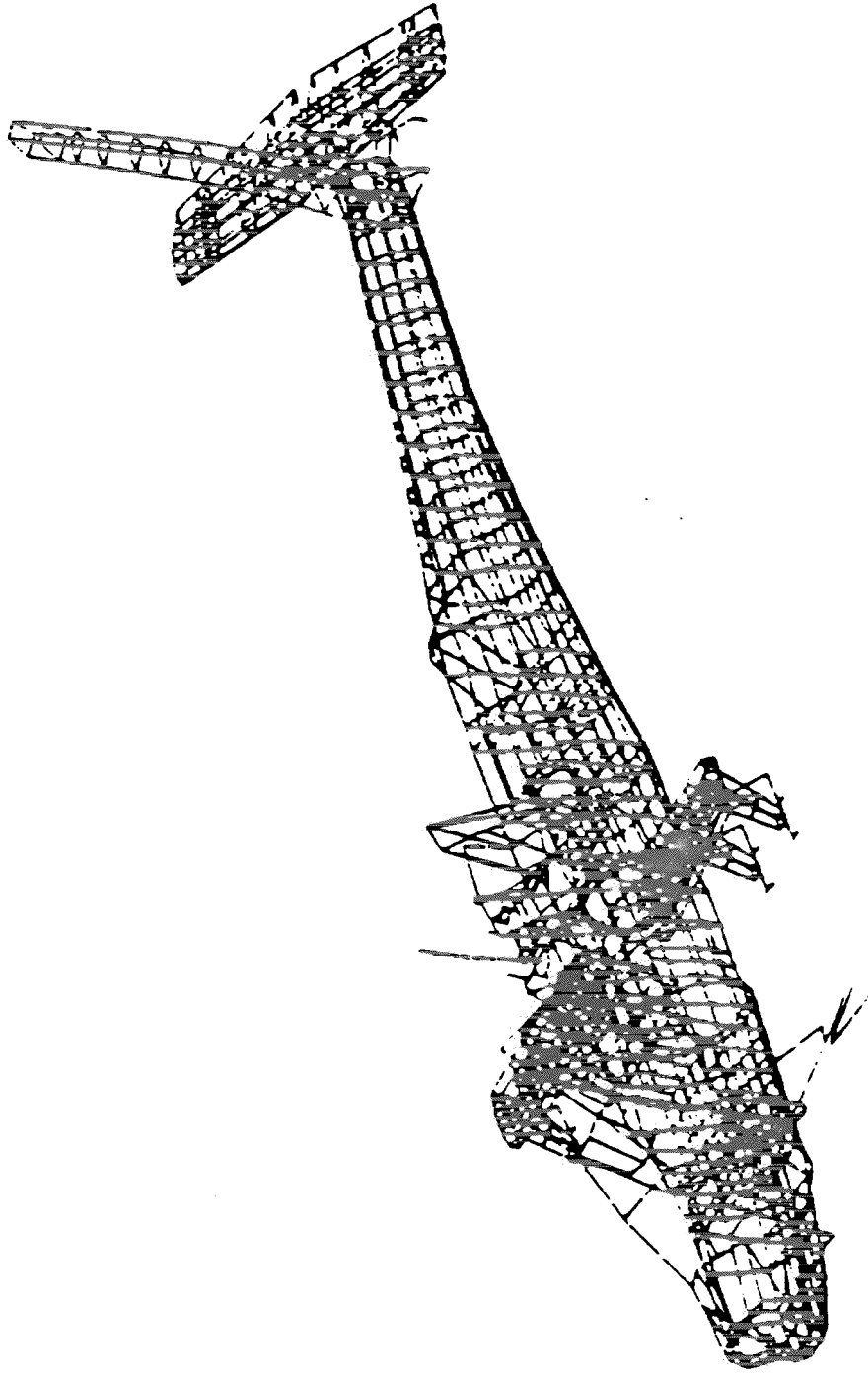
820096 4

Figure 4. AAH Dynamic NASTRAN Model First Vertical Bending Mode (5.55 Hz)



820019-24A

Figure 5. AAH Dynamic NASTRAN Model First Antisymmetric Wing/Pylon
Torsion Mode (7.59 Hz)



830056-3

Figure 6. AAH Dynamic NASTRAN Model Second Vertical Bending Mode (22.3 Hz)

TABLE 2. AAH DYNAMIC NASTRAN MODEL MODE IDENTIFICATION SHOWING
COMPARISON WITH TEST DATA

NASTRAN MODE NO.	NASTRAN FREQUENCY	DESCRIPTION	TEST MODE, FREQUENCY
13	4.08	LATTORSION	LAT/TOR 4.59
14	4.70	SYM WING BEND	
17	5.17	VERT + ENG	
20	5.40	ANTI/SYM WING BEND	
21	5.55	1ST VERT	VERT 5.76
25	6.83	WING/TOR	
28	7.59	ANTI/SYM WING/PYLON TOR	
30	7.81	SYM WING TOR	
31	7.91	SYM WING/PYLON TOR	
33	8.85	1ST LAT BEND	1ST LAT BEND 9.37
35	9.30	VERT + TAIL	
47	12.2	STAB YAW	
48	12.5	STAB YAW	
53	13.5	WING RIGID BODY	
57	14.2	WING TOR ROLL	
59	14.3	WING TOR ROLL	
60	14.5	WING SYM	
63	15.7	STAB ROLL	
64	15.8	STAB/WING ROLL	
66	16.4	STAB YAW	
69	17.3	TAIL/STAB MODE	
74	18.7	VERTICAL	
75	18.97	2ND VERT	2ND VERT 19.39
78	20.2	LAT/TOR WING/STAB	
81	21.2	2ND LAT/TOR	2ND LAT/TOR 20.6
85	22.3	VERT + STAB	
86	22.7	TAIL/STAB	

DISCRETE

$$[M] \{\ddot{X}\} + [C] \{\dot{X}\} + [K] \{X\} = \{f(t)\} = \{F e^{i\omega t}\}$$

LET $\{X\} = [\phi] \{q\}$,

$$\{\dot{X}\} = [\phi] \{\dot{q}\} , \quad \dot{q} = i\omega q$$

$$\{\ddot{X}\} = [\phi] \{\ddot{q}\} , \quad \ddot{q} = -\omega^2 q$$

⋮
↓

MODAL (GENERALIZED COORDINATES)

$$\{q_o\} = \underbrace{\left[I \quad - \left[\left(\frac{\omega}{\omega_N} \right)^2 \right] + i \left[\left(\frac{\omega}{Q \omega_N} \right) \right] \right]^{-1}}_{[T_p]} \left[\omega_N^2 \right]^{-1} [M]^{-1} [\phi]^T \{F_o\}$$

$$\{q_o\} = [T_p] [\omega_N^2]^{-1} [M]^{-1} [\phi]^T \{F_o\} \quad \text{COMPLEX MODAL RESPONSE}$$

87 x 1 87 x 87 87 x 87 87 x 87 87 x 1 1 x 1

COMPLEX DISCRETE RESPONSE

$$\{X\} = [\phi] \{q\} \quad \text{MODAL SUMMATION} \quad (1)$$

1 x 1 1 x 87 87 x 1

$$\begin{matrix} \left\{ X \right\} \\ 87 \times 1 \end{matrix} = \begin{matrix} \left\{ \phi^T \right\} \\ 87 \times 1 \end{matrix} \begin{matrix} E \\ X \\ E \end{matrix} \begin{matrix} \left\{ q \right\} \\ 87 \times 1 \end{matrix} \quad (2)$$

$$X_{TOTAL} = \sum_{i=1}^m X_i = \sum_{i=1}^m \phi_i q_i \quad (3)$$

Figure 7. Dynamic NASTRAN Dynamic Equations

```

$ EXPAND MODE TO NUMBER OF CASES
MATGEN ,/IC/1/C.Y,NCASE $
MATMOD IC,./././R3./7 $
TRNSP R3/C3 $
MPYAD ZPST,C3,/ZPST3 $
$ FORM COMPLEX CONJUGATE OF ETA
MATMOD UHUI,./././ETA,./10 $
ADD UHUI,ETA,./TETA,./1 $
DIAGONAL TETA,./TETA,./UHOLE/0.5 $
MATPRN TETA,./ $
$ NORM TETA,./TETA,./ $
MATPRN TETA,./ $
$ FORM PHI X ETA
ADD ZPST3,UHUI/TOT,./1 $
MATPRN TOT,./ $
$ FORM COMPLEX CONJUGATE
MATMOD TOT,././TOTC,./10 $
ADD TOT,./TOTC,./TOTMD,./1 $
$ SQUARE ROOT
DIAGONAL TOTMD,./TOTM,./UHOLE/0.5 $
MATPRN TOTM,./ $
NORM TOTM,./TOTM,./ $
MATPRN TOTM,./ $
$ SUM MODES
MATGEN ,/IDENT/1/C.Y,./LNODES $
MATMOD IDENT,./././COL,./7 $
MPYAD COL,./TOT,./SUM,./1 $
MATPRN SUM,./ $
$ FORM PHI X ETADD
ADD ZPST3,UHUI/TOTA,./C.Y,U2,./1 $
MATPRN TOTA,./ $
$ FORM COMPLEX CONJUGATE
MATMOD TOTA,./././TOTAC,./10 $
ADD TOTA,./TOTAC,./TOTMDA,./1 $
$ SQUARE ROOT
DIAGONAL TOTMDA,./TOTMA,./UHOLE/0.5 $
NORM TOTMA,./ $
MATPRN TOTMA,./TOTMA,./ $
MATPRN TOTMA,./ $
$ SUM MODES
MPYAD COL,./TOTA,./SUMA,./1 $
MATPRN SUMA,./ $
EXIT $
TITLE - AMH FREQUENCY RESPONSE / MODE CHECK

```

```

$ EXPAND MODE TO NUMBER OF CASES
MATGEN ,/IC/1/C.Y,NCASE $
MATMOD IC,./././R3./7 $
TRNSP R3/C3 $
MPYAD ZPST,C3,/ZPST3 $
$ FORM COMPLEX CONJUGATE OF ETA
MATMOD UHUI,./././ETA,./10 $
ADD UHUI,ETA,./TETA,./1 $
DIAGONAL TETA,./TETA,./UHOLE/0.5 $
MATPRN TETA,./ $
$ NORM TETA,./TETA,./ $
MATPRN TETA,./ $
$ FORM PHI X ETA
ADD ZPST3,UHUI/TOT,./1 $
MATPRN TOT,./ $
$ FORM COMPLEX CONJUGATE
MATMOD TOT,././TOTC,./10 $
ADD TOT,./TOTC,./TOTMD,./1 $
$ SQUARE ROOT
DIAGONAL TOTMD,./TOTM,./UHOLE/0.5 $
MATPRN TOTM,./ $
NORM TOTM,./TOTM,./ $
MATPRN TOTM,./ $
$ SUM MODES
MATGEN ,/IDENT/1/C.Y,./LNODES $
MATMOD IDENT,./././COL,./7 $
MPYAD COL,./TOT,./SUM,./1 $
MATPRN SUM,./ $
$ FORM PHI X ETADD
ADD ZPST3,UHUI/TOTA,./C.Y,U2,./1 $
MATPRN TOTA,./ $
$ FORM COMPLEX CONJUGATE
MATMOD TOTA,./././TOTAC,./10 $
ADD TOTA,./TOTAC,./TOTMDA,./1 $
$ SQUARE ROOT
DIAGONAL TOTMDA,./TOTMA,./UHOLE/0.5 $
NORM TOTMA,./ $
MATPRN TOTMA,./TOTMA,./ $
MATPRN TOTMA,./ $
$ SUM MODES
MPYAD COL,./TOTA,./SUMA,./1 $
MATPRN SUMA,./ $
EXIT $
TITLE - AMH FREQUENCY RESPONSE / MODE CHECK

```

```

NASTRAN(P10,MR01400,CM250000,L020)
ACCOUNT(C1556A,RAHDD)
CID(C PARKER)
BANNERS(OP-SDT)RAH FREQ RESPONSE#MSCB3R
FORMATL,DEST-PR453,SYS-A,RECIP-C,PARKER K20-2
#####
$ NASTRAN INPUT FILE - MSCB3R
$ DEF OUT FILE - DMSCB3R
$ DAYFILE FILE - DMSCB3R
$ RESTART YFM - MSC1
#####
BANNERS.#INPUT#
REWIND,INPUT.
COPYSEF,INPUT.
REWI,INPUT.
SKIPR,INPUT.
BANNERS.#END OF INPUT#
#####
SYSCALL(MNASTRN/MONOTES,VERSION=610,NOSCAN,CTM,RESTART-TAPE,
RTFN=AD25,RLABEL=AD25,RIID=AD25,RFILES=80PTP,PUNCH0)
GOTO(1)HOST)
EXIT.
1)HOST, $
SYSCALL(ROUTE/SAVE,PFN=DMSCB3R)
DAYFILE(DMSCB3R)
REPLACE(DMSCB3R)
RETURN,PUNCH.
/EO
NASTRAN FILES-(OPTP)
ID FREQ DYNAMIC
TIME 20
DIAG.8,19.22
SOL 30
$ READ DICT
#####
$ DMAP ALTER TO CALCULATE FREQUENCY RESPONSE
CONTRIBUTION PER MODE
$ INPUTS
$ SEE BULK DATA SECTION FOR
PROGRAM INPUTS
#####
ALTER 572
$ PRINT FREQUENCY TABLE
OFF LAMA,./ $
$ EXTRACT PILOT SEAT MODESHAPES (6 DOF G-SET)
PRTPRN // $
MATMOD EQEXIN,./SET,SIL,CASECC,./UECX,./17/0/1/S,N,NOVEC $
PARTN PHIGH,./UECX,./PHIP,./1/0/ $
MPYAD C6,PHIP,./ZPS,./1 $
TRNSP ZPS/ZPST $
MATPRN ZPST,./ $
$ PRINT NORMALIZED MODESHAPE
NORM ZPST/ZPSN $
MATPRN ZPSN,./ $

```

NOTE →

NOTE →

NOTE →

NOTE →

Figure 8. Modal Frequency Response Contribution Per Mode DMAP

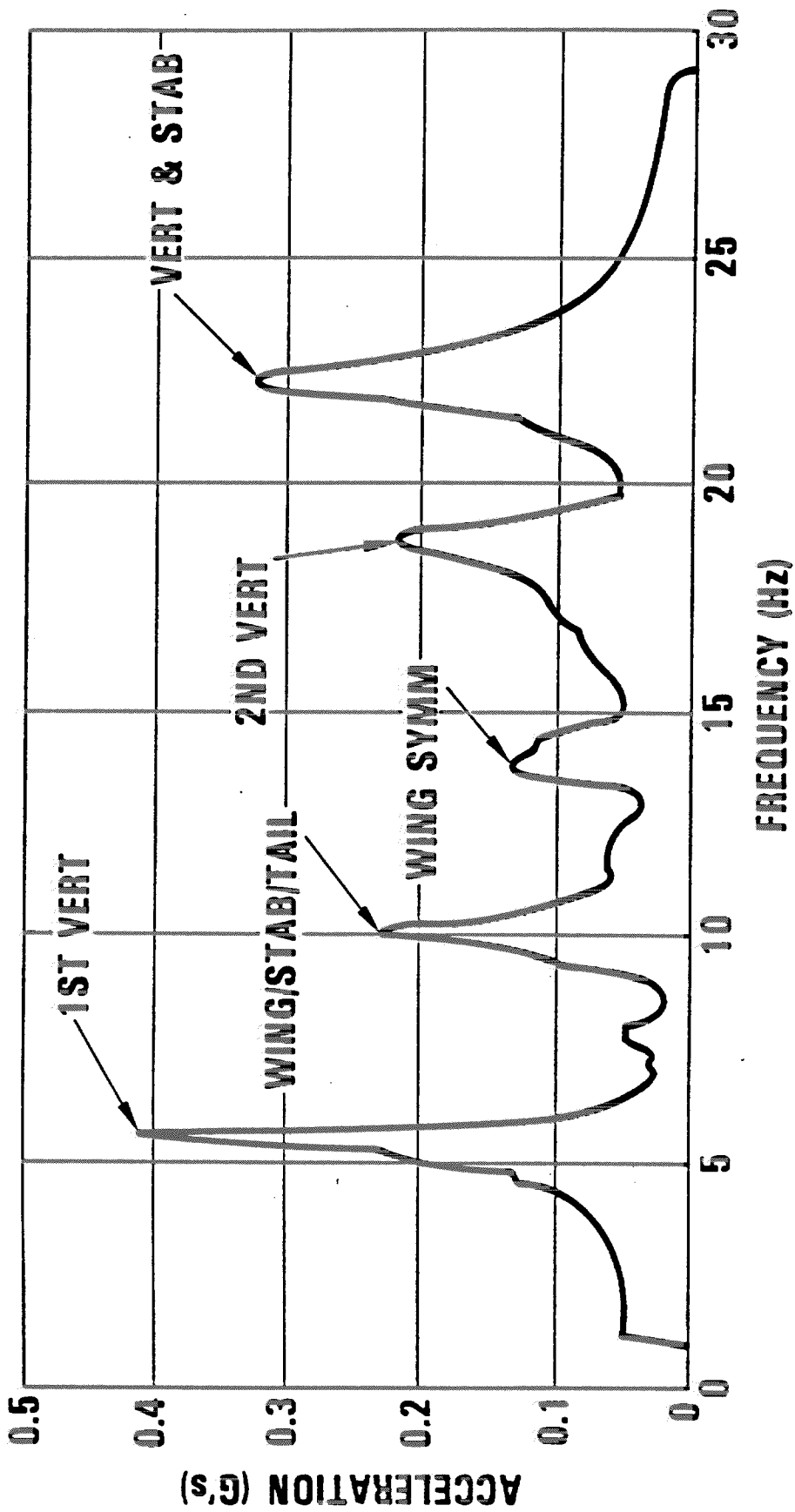


Figure 10. AAH Dynamic NASTRAN Model Frequency Sweep Showing Response at Pilot's Seat Due to Excitation at Tail

TABLE 3. DYNAMIC NASTRAN MODAL FREQUENCY RESPONSE ANALYSIS

POINT ID.	TYPE	COMPLEX ACCELERATION VECTOR (SOLUTION SET)					
		T1	T2	T3	R1	R2	R3
1	M	1.408802E-04 5.833394E-11	3.206251E-02 1.836955E-08	-1.266728E-02 -8.971534E-09	-1.584343E-02 -2.163830E-08	-1.318453E+00 -4.545936E-06	-5.407066E-01 -1.936426E-06
7	M	-5.096182E-05 -2.780459E-07	-1.170967E-03 -7.466695E-06	1.972044E-03 1.310463E-05	1.132520E-03 7.604055E-06	-6.949435E-05 -4.929592E-07	-6.267619E-07 -4.445860E-09
13	M	2.668100E-03 2.427537E-05	-9.711008E-02 -1.033987E-03	-4.117037E-03 -4.456117E-05	1.785697E-01 2.096593E-03	-4.009015E-01 -4.755020E-03	5.495019E-02 6.572737E-04
19	M	-2.169022E-01 2.625904E-03	1.248664E-02 1.559828E-04	-8.372275E-01 -1.080526E-02	3.812314E-03 5.457644E-05	1.905305E-02 2.991339E-04	1.114313E-02 1.641119E-04
25	M	2.117021E-04 3.533201E-06	-8.409160E-03 -1.462650E-04	-2.163489E-02 -3.776796E-04	3.695763E-04 7.115326E-06	5.332581E-03 1.049429E-04	2.388587E-02 4.782782E-04
31	M	-1.267217E-01 -2.583655E-03	-3.037973E-02 -6.311142E-04	1.734037E-02 4.151743E-04	9.629617E-02 2.384407E-03	6.357238E-01 1.657244E-02	-5.227338E-02 -1.485970E-03
37	M	-7.633489E-01 -2.281154E-02	2.347115E-01 7.156246E-03	2.526677E-02 6.450440E-04	-1.187755E-01 -4.124452E-03	-2.116510E-03 -7.468695E-05	-1.369042E-02 -4.945242E-04
43	M	3.555234E-02 1.342079E-03	-3.738940E-02 -1.470207E-03	-5.362630E-02 -2.281030E-03	9.124712E-04 4.022980E-05	-4.205567E-03 -1.873165E-04	6.041088E-02 2.815060E-03
49	M	3.053847E-03 1.452975E-04	-2.033576E-02 -1.031202E-03	-1.739341E-01 -1.004981E-02	1.065681E-01 6.237596E-03	-5.657314E-01 -3.323980E-02	3.491734E-02 2.196170E-03
55	M	6.817407E-02 4.397839E-03	1.564360E-01 1.078465E-02	-1.391251E-01 -9.412735E-03	1.236751E-01 8.728679E-03	-7.257126E-02 -5.274594E-03	-1.050251E-01 -8.034523E-03
61	M	2.875370E-02 2.689651E-03	-9.962904E-02 -9.506251E-03	-1.778723E-01 -1.991099E-02	1.849171E-03 2.152962E-04	7.563513E-03 9.681246E-04	-6.349685E-03 -9.251840E-04
67	M	7.654929E-02 1.208314E-02	-6.306015E-03 -1.372581E-03	-4.363845E-03 -1.083911E-03	-1.018355E-01 -2.670767E-02	2.212055E-01 5.977532E-02	1.812456E-01 1.041907E-01
73	M	7.726559E-01 9.005753E-01	-8.909719E-01 -3.790209E+00	-1.535315E+00 4.704655E+00	-4.381344E-02 2.221796E-02	-1.820643E-01 6.056388E-02	3.263200E-01 -9.262296E-02
79	M	1.635985E-02 -3.186105E-03	1.020797E-01 -1.769188E-02	7.307423E-02 -1.224010E-02	1.850496E-02 -2.912429E-03	6.095145E-02 -8.708437E-03	-6.082948E-02 7.835138E-03
85	M	3.528446E-01 -4.179560E-02	4.298734E-02 -4.556823E-03	1.233902E-02 -1.207814E-03			

TABLE 4. DYNAMIC NASTRAN MODAL FREQUENCY RESPONSE ANALYSIS

AAH FREQUENCY RESPONSE / MODE CHECK
 RESTART FROM ADE5 TAPE

MARCH 28, 1983 NASTRAN 12/14/81

FOR 4P FZ = 1000 LBS. AT TAIL NODE 54712
 FREQUENCY = 1.885000E+01

SUBCASE 5000

COMPLEX ACCELERATION VECTOR
 (REAL/IMAGINARY)

POINT ID.	TYPE	T1	T2	T3	R1	R2	R3
54	G	1.512239E-01 -1.392614E-02	2.041894E-02 4.958088E-02	-5.218275E-02 5.757180E-02	-4.189949E-04 -2.414039E-03	5.968174E-03 4.399776E-03	2.127246E-04 -6.687746E-04
10013	G	-1.459833E-02 -2.991421E-01	-1.213395E-03 6.477760E-03	-8.540148E-02 2.053571E-01	3.323403E-05 -4.933487E-05	-4.750295E-04 4.305886E-03	1.896063E-04 -6.682004E-04
54712	G	3.280976E-02 -3.133969E-01	1.907732E-02 1.481826E-02	1.442403E+00 6.611448E-01	0.0 0.0	0.0 0.0	0.0 0.0

PILOT →
SEAT →

TABLE 5. DYNAMIC NASTRAN MODAL FREQUENCY RESPONSE ANALYSIS

AAH FREQUENCY RESPONSE / MODE CHECK
 RESTART FROM AD25 TAPE

MATRIX ZPSN		(GINO NAME 101) IS A REAL		1 COLUMN X		87 ROW RECTANG		MATRIX.			
COLUMN	ROW	1	THRU	1	THRU	1	THRU	1	THRU		
11)	11)	8.6473E-01	1.0000E+00	4.6657E-01	-7.8704E-02	2.7189E-01	7.2498E-02	2.7964E-05	6.3521E-04	-8.8450E-04	-1.0639E-03
11)	21)	-8.0171E-05	6.4390E-05	-1.0236E-02	-1.0017E-01	1.8669E-03	8.3999E-02	-1.0485E-01	1.2212E-02	-2.9061E-02	-1.5111E-02
21)	11)	-1.7139E-01	4.0826E-03	9.9303E-03	3.6915E-04	-2.5443E-03	-4.3860E-02	-6.1289E-02	8.1181E-03	1.0122E-02	-1.5383E-02
31)	21)	1.7124E-01	2.7804E-02	-2.4163E-02	5.6960E-03	5.9975E-02	1.0784E-01	1.4685E-01	8.5533E-03	-3.7397E-02	-4.9452E-02
41)	31)	-1.4179E-05	8.9547E-03	-6.8971E-02	7.1415E-02	-4.4750E-02	7.4259E-03	6.6571E-02	6.5602E-02	9.4345E-02	-3.2040E-02
51)	41)	-6.4236E-02	-1.0154E-01	8.4719E-02	2.8993E-02	9.6125E-02	1.6542E-01	9.9032E-02	-3.0783E-02	-6.4009E-02	-4.3463E-01
61)	51)	6.7608E-03	-3.7126E-02	8.2515E-03	3.1683E-02	2.3827E-02	-1.5492E-02	1.6231E-01	4.7628E-03	1.4119E-02	-2.2733E-02
71)	61)	1.6435E-01	4.3671E-02	8.5817E-02	-1.0931E-01	2.1629E-01	1.8624E-02	8.2138E-02	-6.5391E-02	-1.2998E-01	-1.1300E-01
81)	71)	-3.4094E-02	-3.9672E-02	-7.7608E-02	1.3541E-01	-6.7059E-01	-9.7823E-02	1.1194E-01			

TABLE 6. DYNAMIC NASTRAN MODAL FREQUENCY RESPONSE ANALYSIS

AAH FREQUENCY RESPONSE / MODE CHECK
RESTART FROM AD25 TAPE

MARCH 28, 1983 NASTRAN 12/14/81

MATRIX TOTMA (GINO NAME 101) IS A REAL 2 COLUMN X 87 ROW RECTANG MATRIX.

COLUMN ROW	1	ROWS 1 THRU 87	2	COLUMN X 87 ROW RECTANG MATRIX.
1)	2.890E-02	3.8878E-02	8.9772E-03	2.5680E-04
11)	2.1029E-10	9.4429E-12	3.6310E-07	2.5443E-04
21)	2.6225E-03	1.3722E-07	3.9637E-06	1.6264E-09
31)	7.7815E-04	3.8496E-05	1.8209E-05	1.8198E-05
41)	4.4516E-10	5.7943E-06	4.5553E-04	5.0311E-04
51)	5.6110E-04	3.6021E-03	1.7931E-03	8.7041E-05
61)	6.0842E-06	4.3076E-04	5.2052E-06	1.8347E-04
71)	4.9196E-03	4.8484E-04	1.4970E-03	6.6275E-03
81)	2.2585E-05	2.9275E-05	1.7793E-04	9.9003E-04
1)	4.2804E-04	5.8839E-05	7.5217E-08	4.2804E-04
11)	4.8410E-04	5.8839E-05	7.5217E-08	4.8410E-04
21)	1.0929E-04	3.2545E-03	2.3822E-06	1.0929E-04
31)	3.5673E-04	5.1710E-06	1.2251E-04	3.5673E-04
41)	4.2855E-05	1.4725E-03	7.1542E-03	4.2855E-05
51)	2.4355E-04	2.1963E-04	6.8290E-05	2.4355E-04
61)	3.7934E-06	5.4392E-05	1.0609E-02	3.7934E-06
71)	9.7132E-05	1.9330E-04	1.6387E-02	9.7132E-05
81)	2.0574E-03	4.6831E-04	1.2509E-03	2.0574E-03
1)	1.3090E-09	2.4139E-12	1.3090E-09	1.3090E-09
11)	7.7571E-06	4.8410E-04	7.7571E-06	7.7571E-06
21)	2.0389E-06	1.0929E-04	2.0389E-06	2.0389E-06
31)	3.4397E-06	3.2545E-03	3.4397E-06	3.4397E-06
41)	3.4643E-05	5.1710E-06	3.4643E-05	3.4643E-05
51)	9.0904E-06	1.4725E-03	9.0904E-06	9.0904E-06
61)	1.4355E-04	2.1963E-04	1.4355E-04	1.4355E-04
71)	9.7132E-05	1.9330E-04	9.7132E-05	9.7132E-05
81)	2.0574E-03	4.6831E-04	2.0574E-03	2.0574E-03
1)	1.8624E-10	5.1167E-03	4.6849E-02	1.8624E-10
11)	8.7748E-07	1.9604E-03	1.0045E-06	8.7748E-07
21)	3.9217E-07	4.6208E-05	7.0493E-08	3.9217E-07
31)	2.8249E-04	7.3699E-04	4.8183E-03	2.8249E-04
41)	3.6652E-05	8.6640E-07	3.1390E-04	3.6652E-05
51)	5.1849E-04	3.3899E-03	6.5821E-04	5.1849E-04
61)	1.7402E-03	1.2997E-05	2.3744E-05	1.7402E-03
71)	4.0171E-06	1.1956E-04	1.3949E-01	4.0171E-06
81)	2.9210E-03	5.5264E-04	3.1139E-02	2.9210E-03
1)	9.7209E-08	1.8624E-10	4.6849E-02	9.7209E-08
11)	8.7748E-07	5.4949E-03	1.0045E-06	8.7748E-07
21)	7.0552E-06	1.7332E-04	7.0493E-08	7.0552E-06
31)	1.2356E-04	1.6656E-02	4.8183E-03	1.2356E-04
41)	3.7756E-06	3.6652E-05	3.1390E-04	3.7756E-06
51)	6.0867E-06	1.7402E-03	6.5821E-04	6.0867E-06
61)	8.3024E-06	4.0171E-06	2.3744E-05	8.3024E-06
71)	2.8313E-04	2.9210E-03	3.1139E-02	2.8313E-04
81)	1.5299E-03	1.8938E-04	5.5264E-04	1.5299E-03

THE NUMBER OF NON-ZERO TERMS IN THE DENSEST COLUMN = 87

THE DENSITY OF THIS MATRIX IS 100.00 PERCENT.

*** MODULE NORM - DNAP 572 - MATRIX TOTMAN - COLS = 2, ROWS = 87, FORM = 2, TYPE = 1, NZMDS = 87, DEN = 1.0000, BLKS = 1 **

TABLE 7. DYNAMIC NASTRAN MODAL FREQUENCY RESPONSE ANALYSIS

AAH FREQUENCY RESPONSE / MODE CHECK
 RESTART FROM AD25 TAPE

MARCH 28, 1983

NASTRAN 12/14/81

MATRIX SUMA (GINO NAME 101) IS A COMPLEX 2 COLUMN X 1 ROW RECTANG MATRIX.

COLUMN 1 ROWS 1 THRU 1 -----

1) 9.6061E-02, 2.1326E-02

COLUMN 2 ROWS 1 THRU 1 -----

1) -8.5401E-02, 2.0536E-01

THE NUMBER OF NON-ZERO TERMS IN THE DENSEST COLUMN = 1

THE DENSITY OF THIS MATRIX IS 100.00 PERCENT.

TABLE 8. DYNAMIC NASTRAN MODAL FREQUENCY
RESPONSE ANALYSIS

RSS MAGNITUDE (Gs)

	Fz AT HUB	MODE #	FREQ Hz	Fz AT TAIL	MODE #	FREQ Hz
1	2.52 E-02	60	14.56	1.40 E-01	75	18.97
2	1.64 E-02	85	22.30	5.56 E-02	74	18.76
3	1.06 E-02	75	18.97	3.11 E-02	85	22.30
4	7.15 E-03	56	14.16	1.87 E-02	21	5.55
5	6.63 E-03	74	18.76	1.47 E-02	37	10.07
6	4.92 E-03	71	17.51	1.33 E-02	73	18.53

PILOT SEAT Z RESPONSE PER MODE
COMPARISON OF HUB VS. TAIL EXCITATION

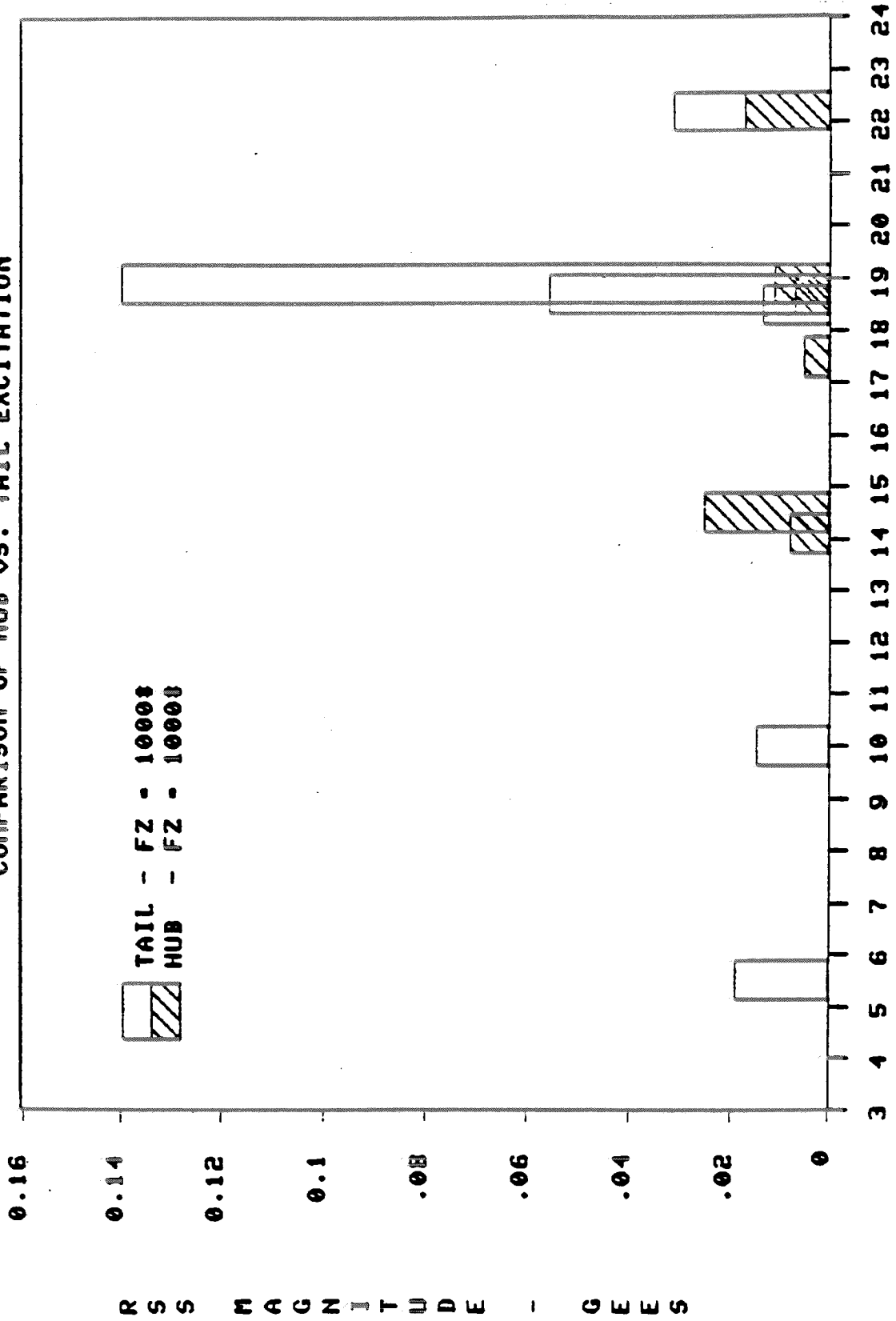


Figure 11. Dynamic NASTRAN Modal Frequency Response Analysis